

CS11313 - Spring 2022

Design & Analysis *of* Algorithms

Selection

Ibrahim Albluwi

Warmup Quiz

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Answer 4. Construct a heap and run m iterations of Heapsort. Take the last m elements in the array.

Running time: $\Theta(n)$ for heap construction + $O(m \log n)$ for the m iterations = $O(n + m \log n)$

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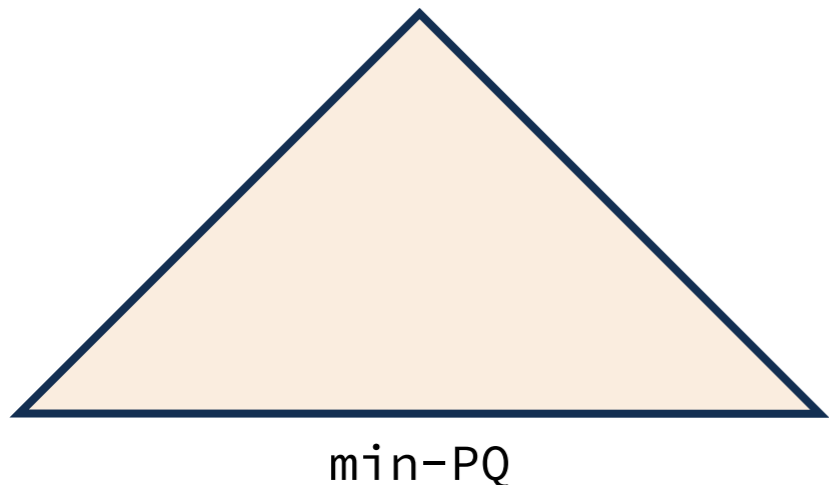
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Example. $m = 4$

`a[] = 1 5 9 8 4 11 3 0 7 8 6 10 2`



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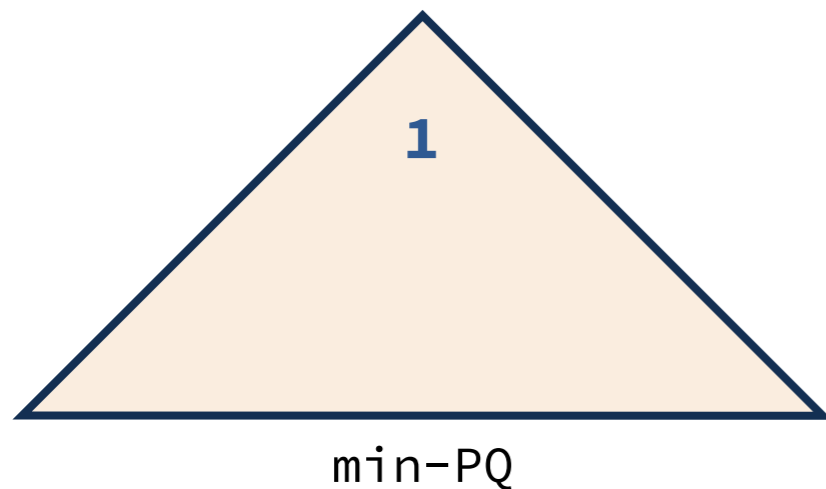
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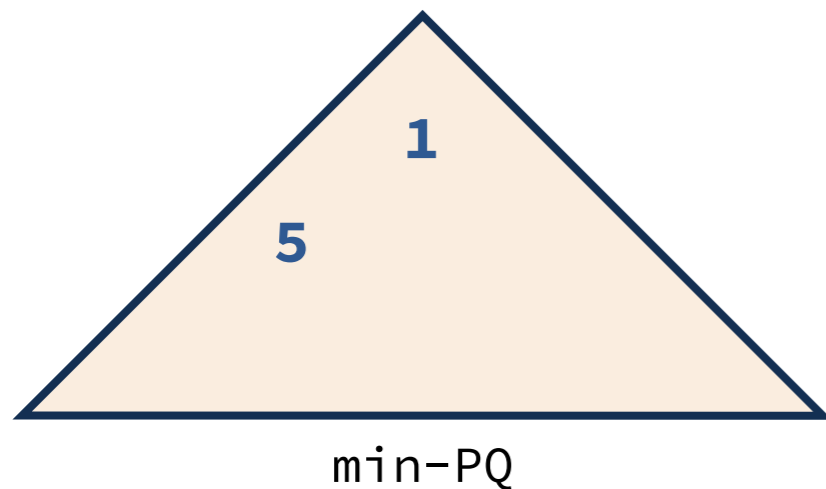
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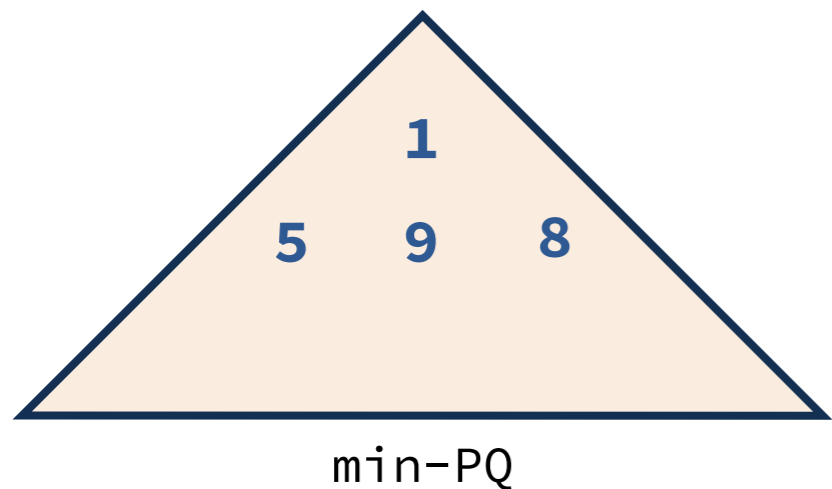
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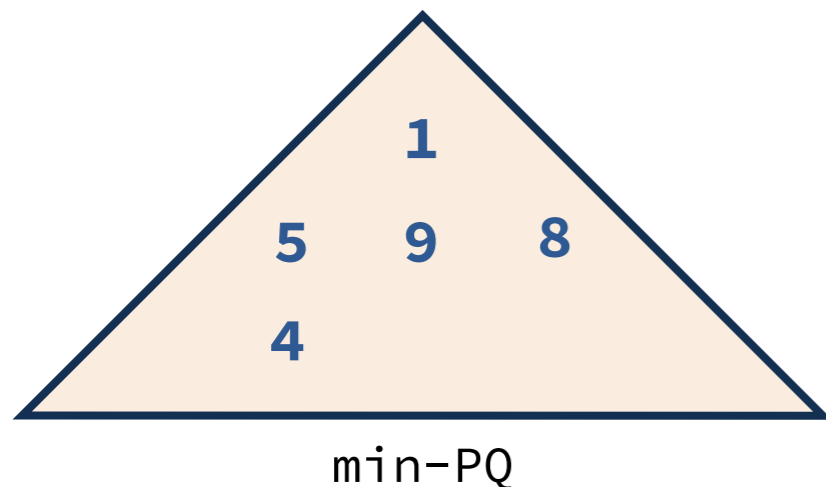
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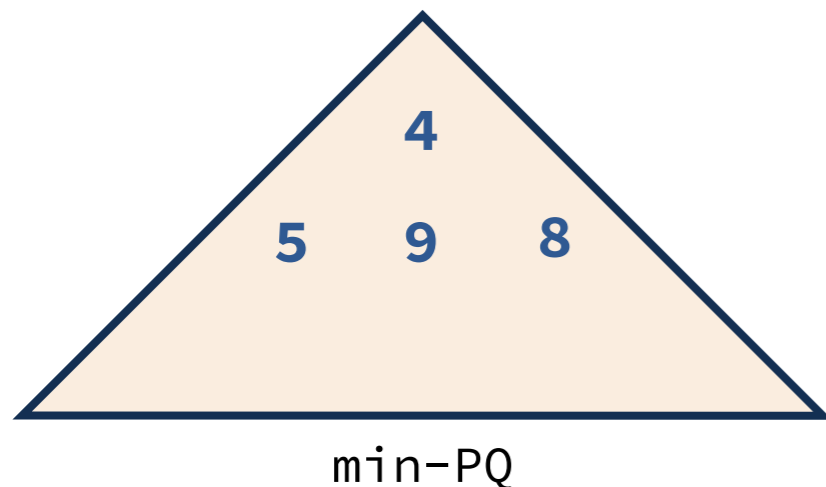
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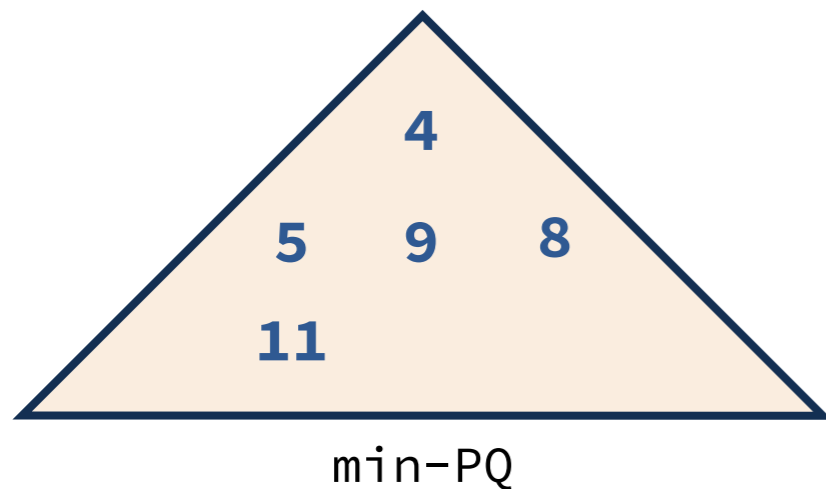
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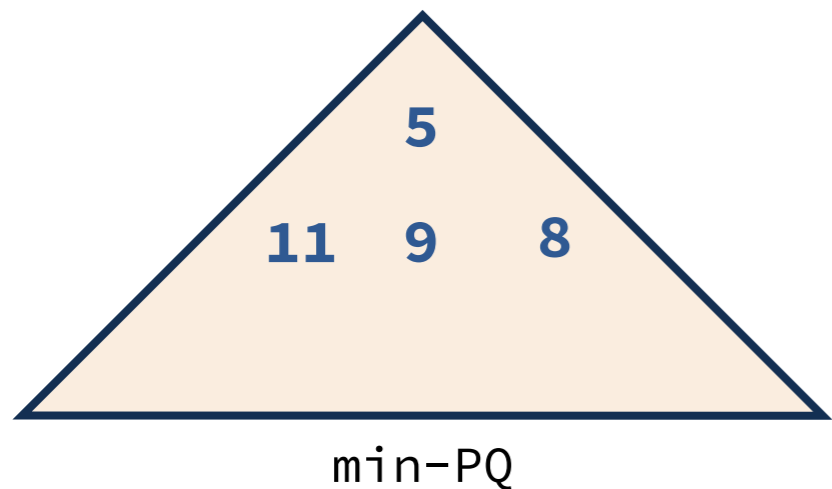
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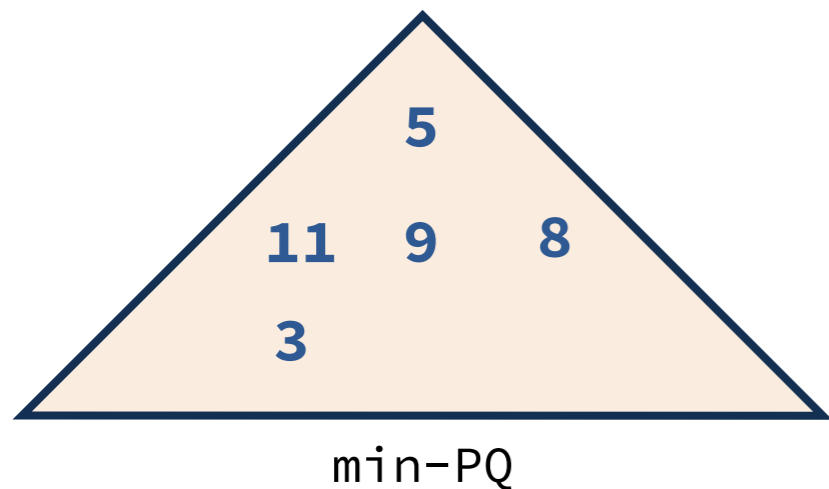
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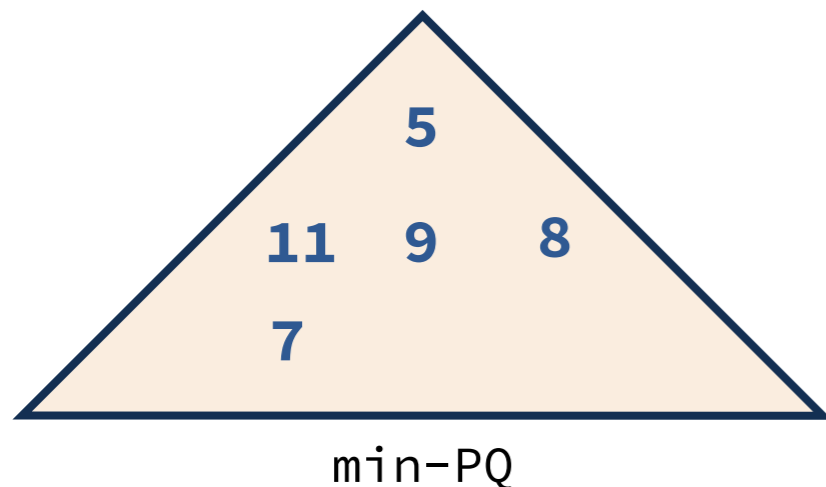
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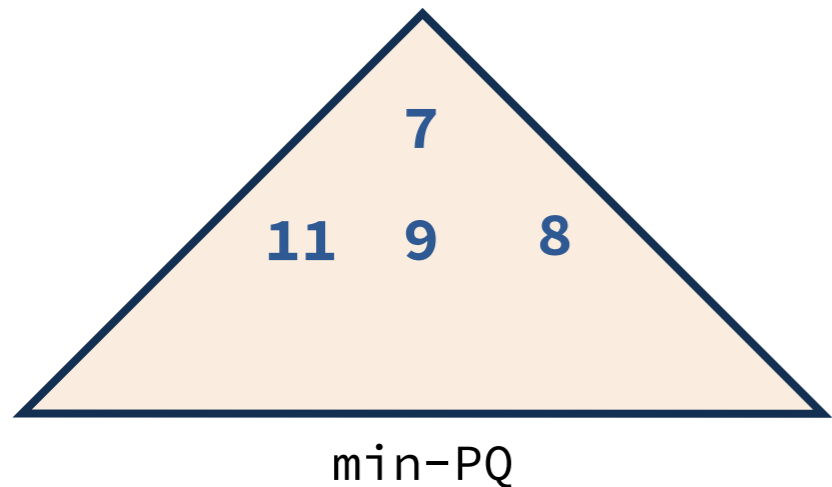
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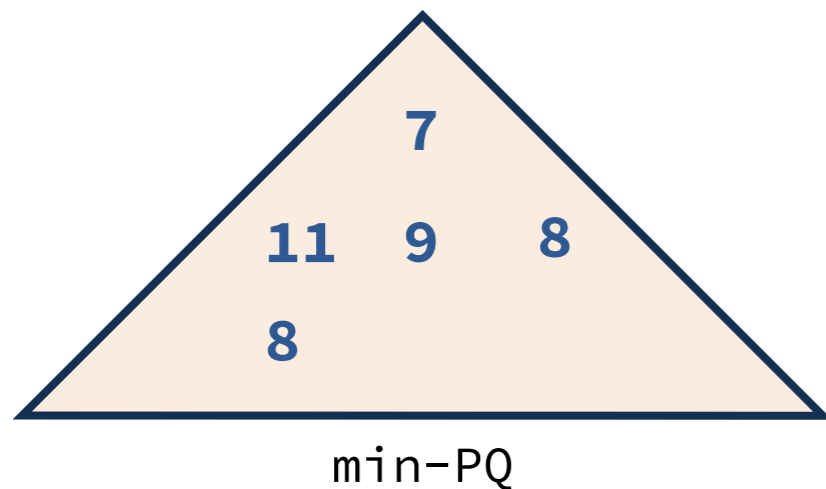
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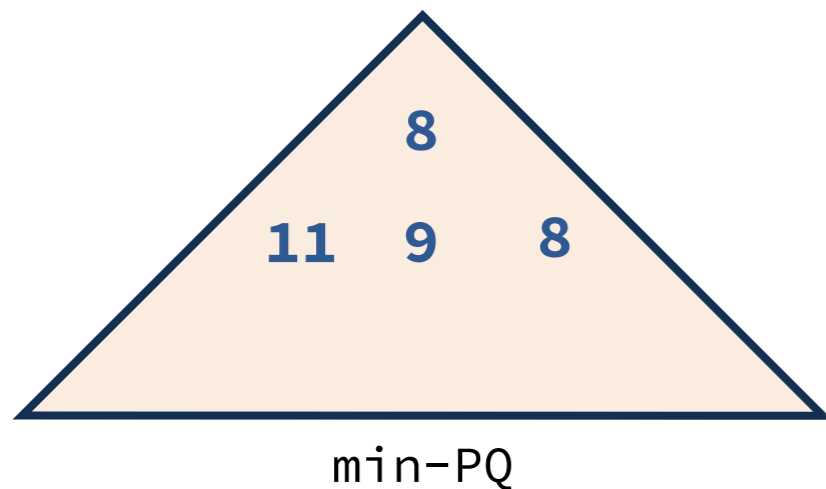
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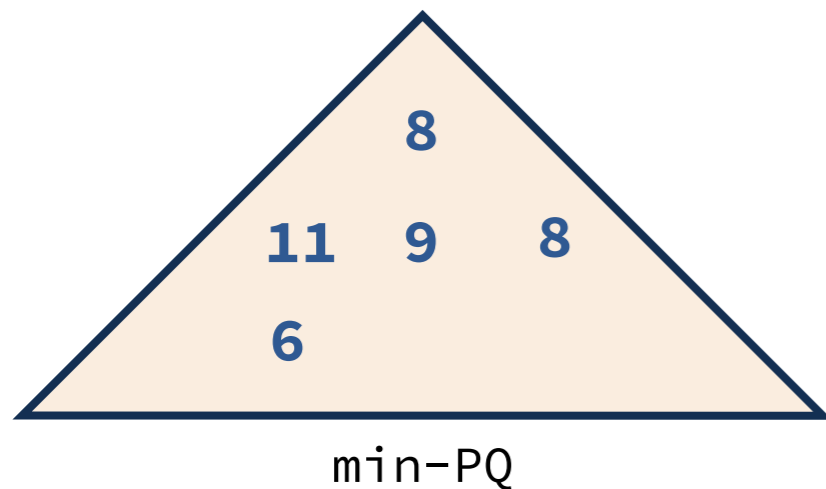
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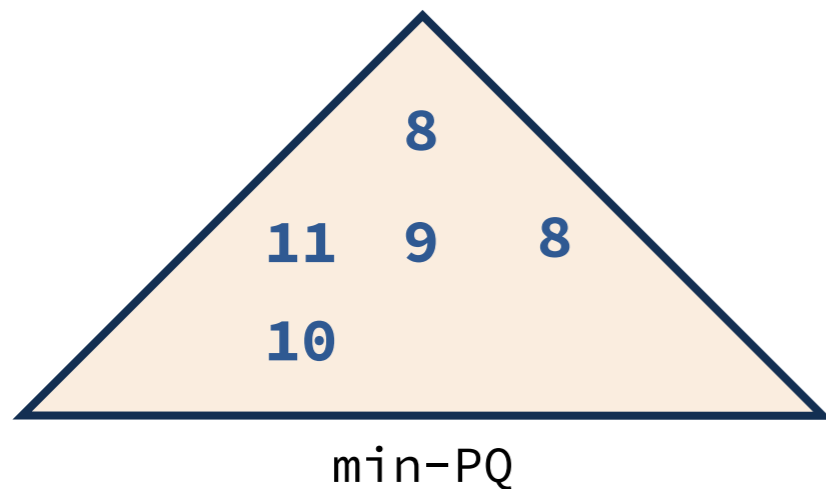
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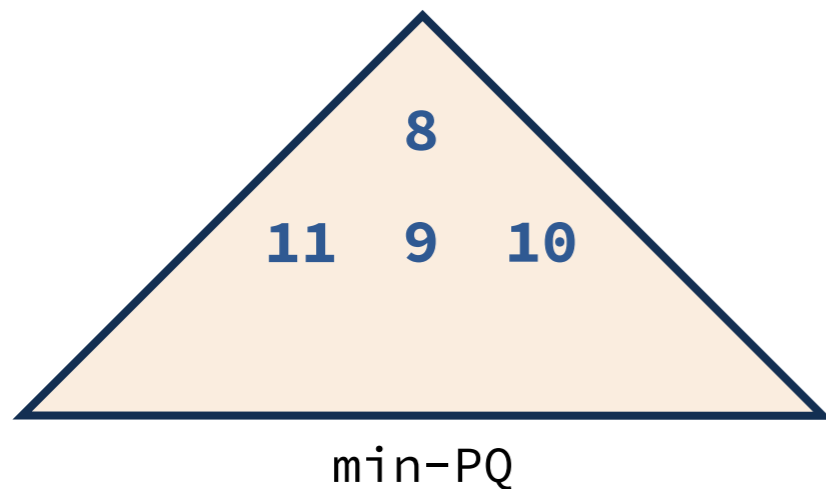
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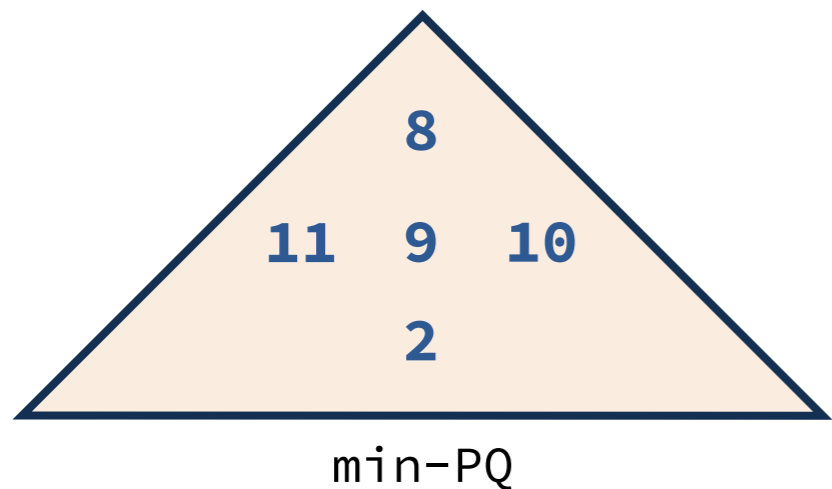
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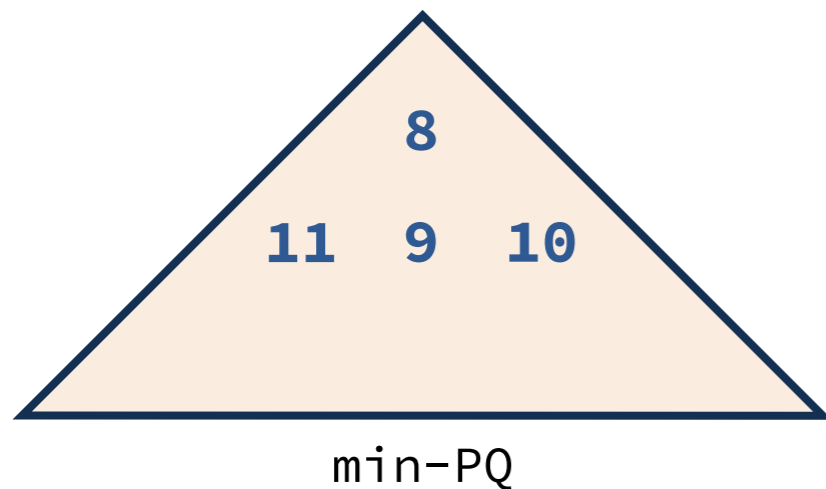
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- Insert the elements into a binary **heap** data structure. $\leftarrow O(n \log n)$
- **Sort** and then get the element at index k . $\leftarrow O(n \log n)$ if heapsort is used.
- Heapify and then remove k elements from the **heap**. $\leftarrow O(n + k \log n)$.

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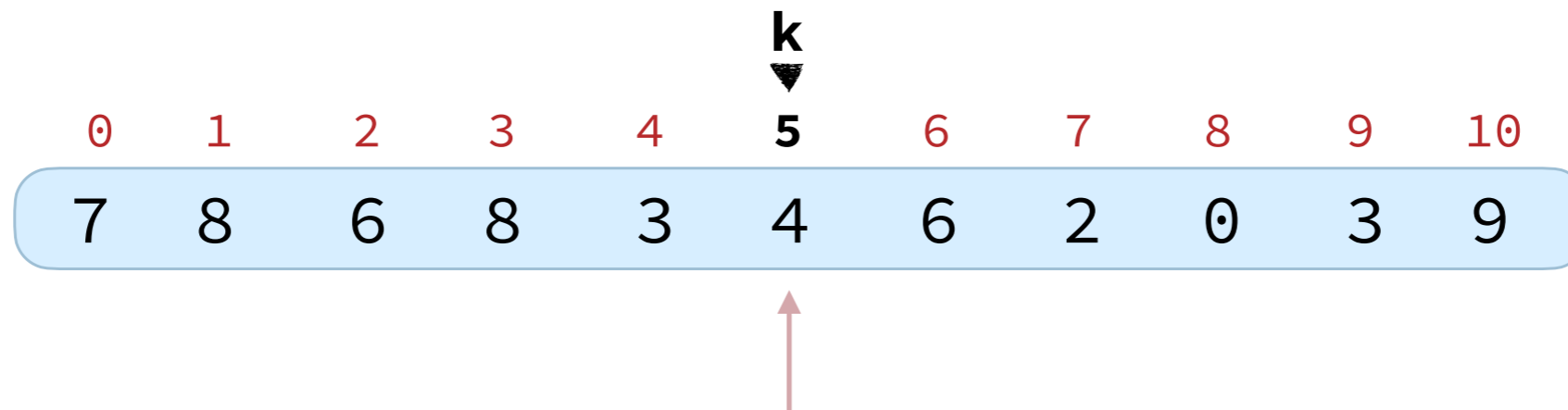
Can we do better?

Is selection as hard as sorting?

(requires $\sim n \log n$ compares
in the worst case if $k = \frac{n}{2}$)

Quickselect Demo

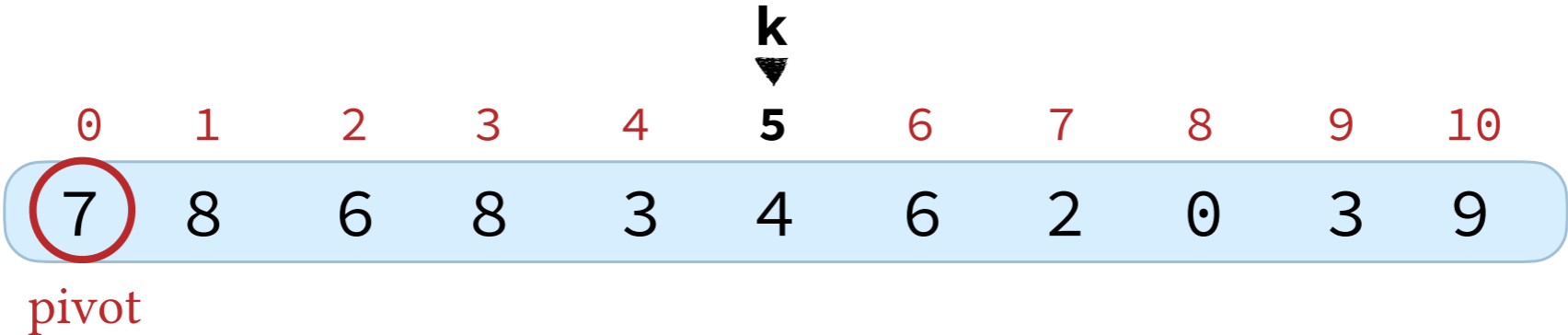
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which element should be at this index if the elements were sorted?

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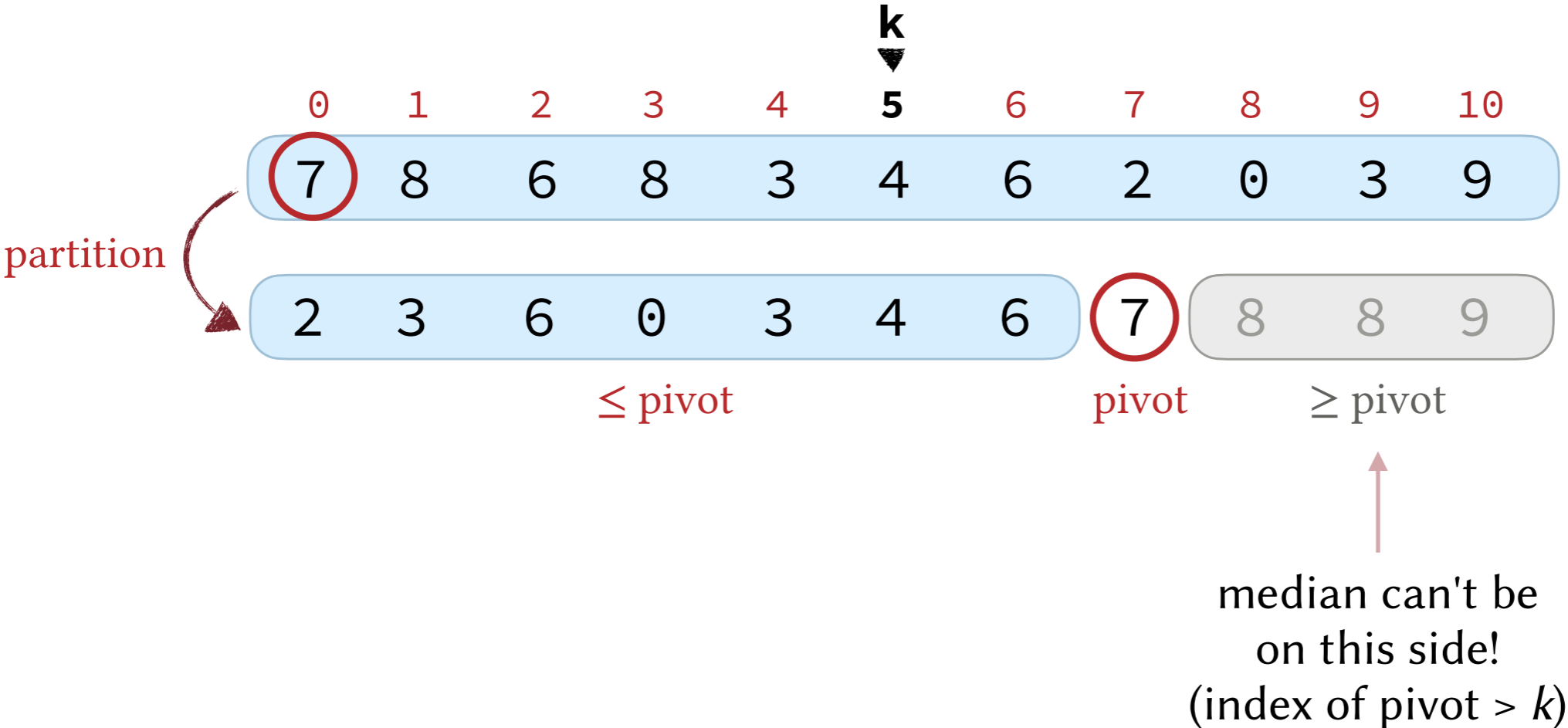
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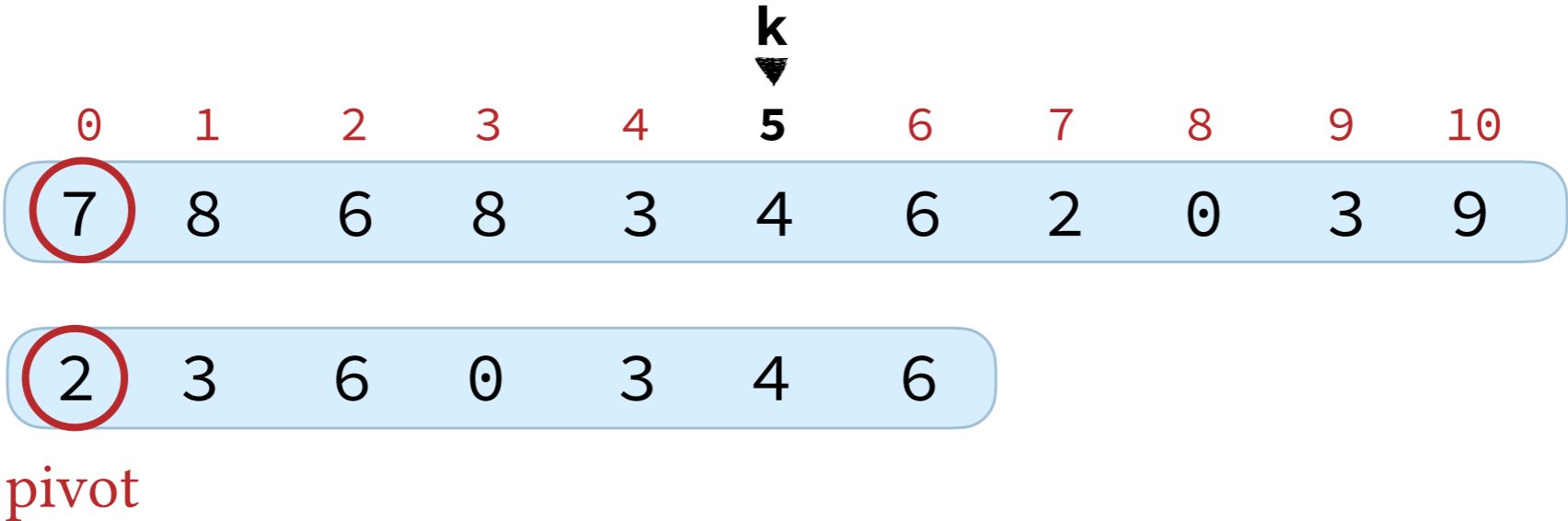
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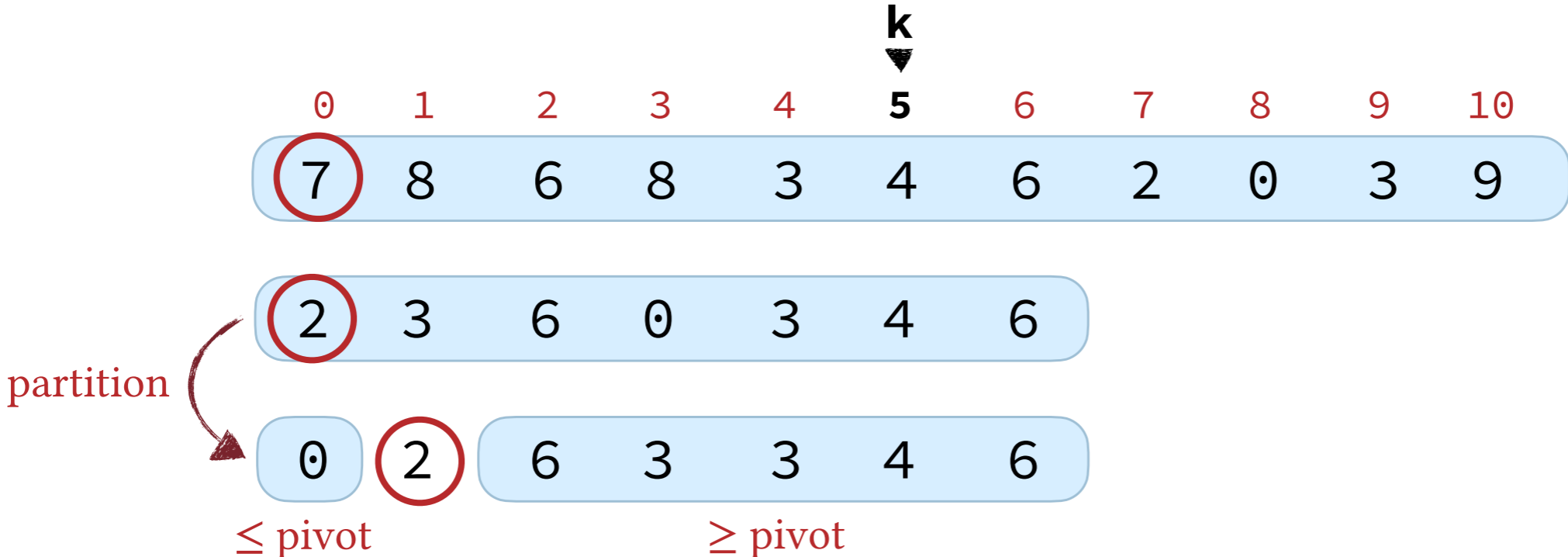
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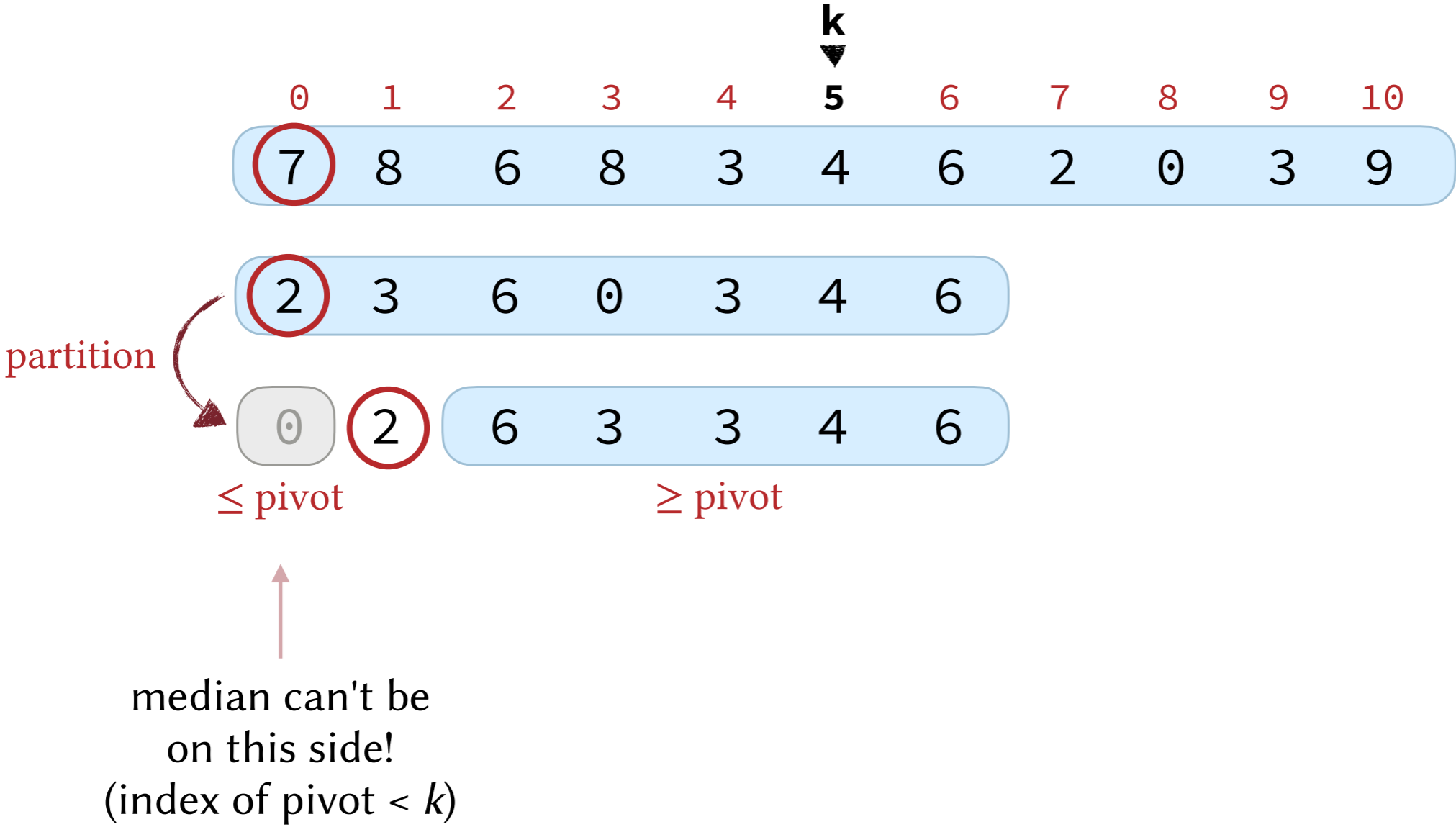
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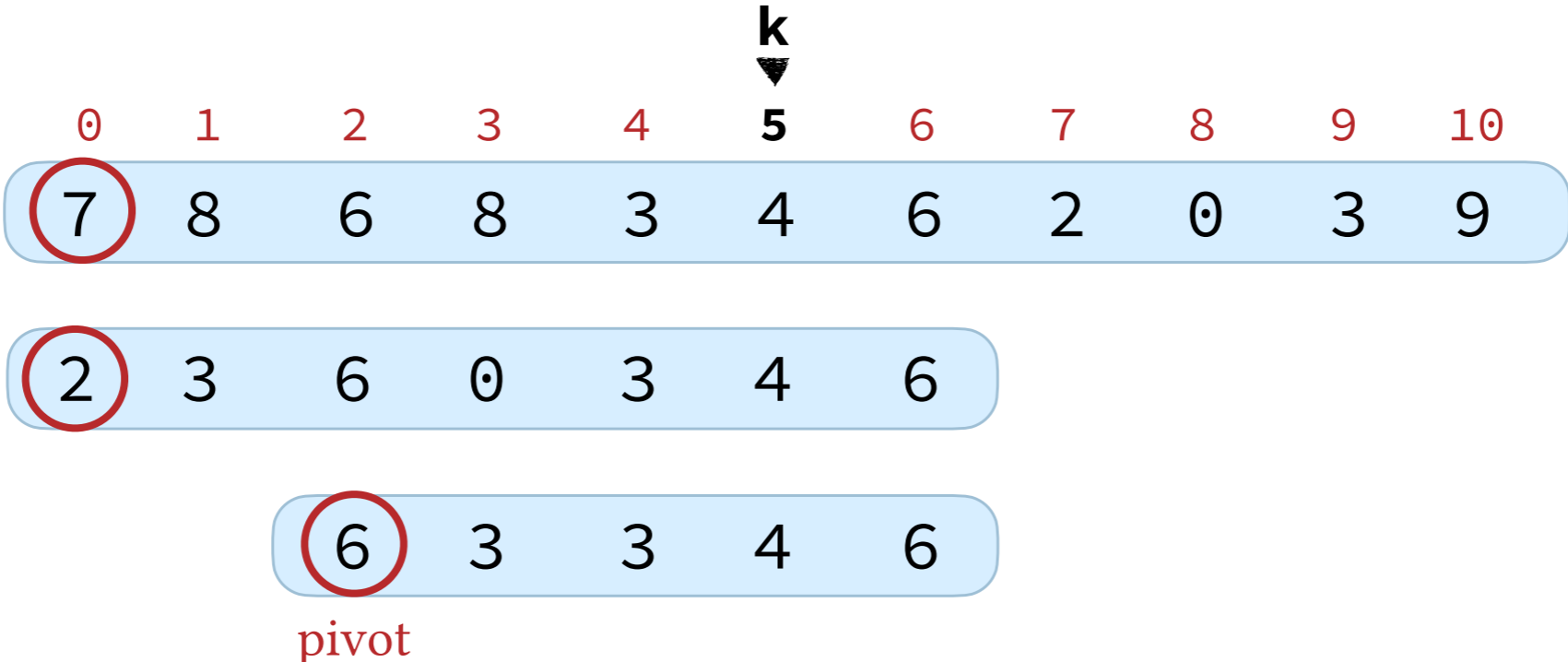
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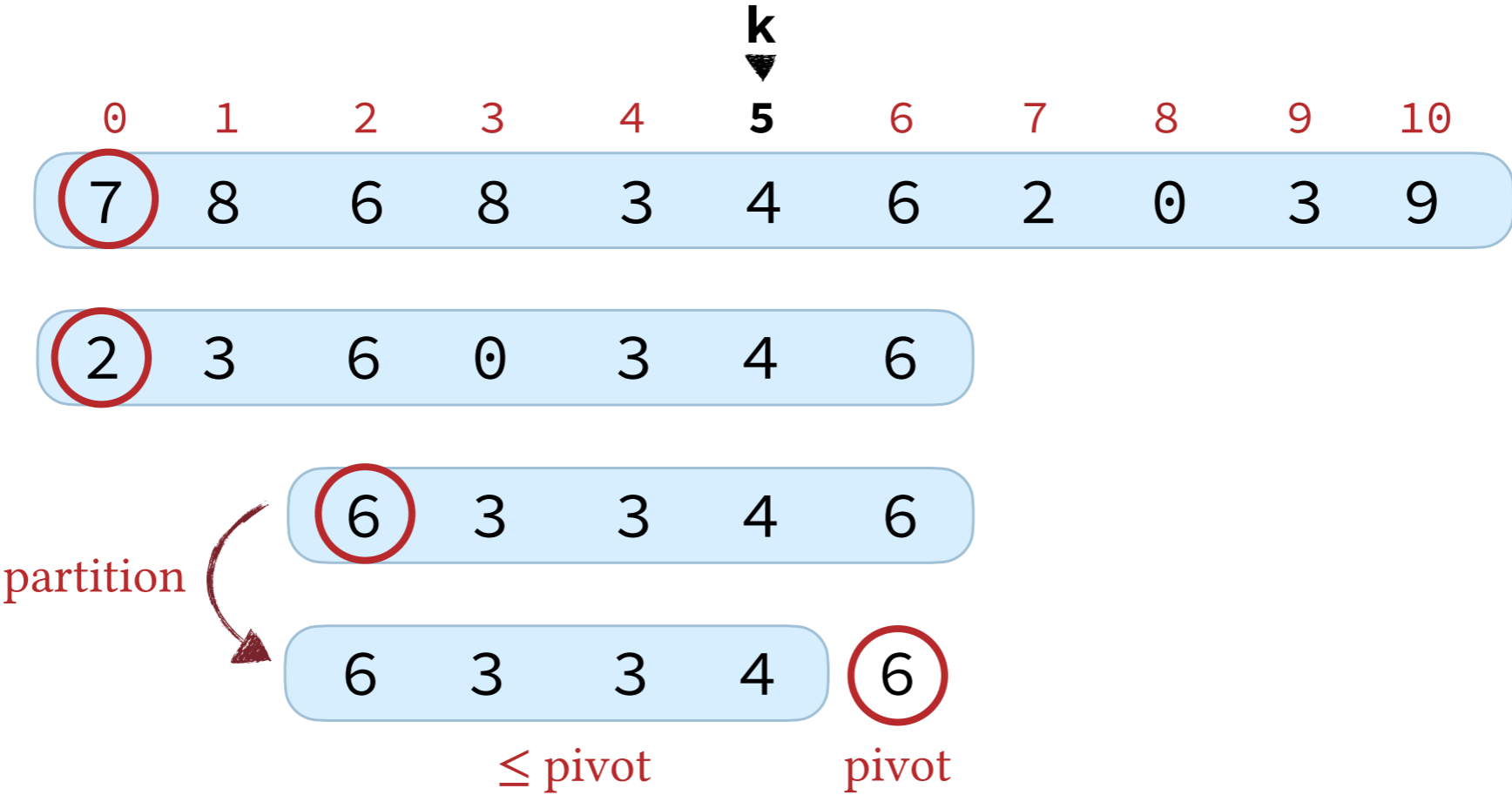
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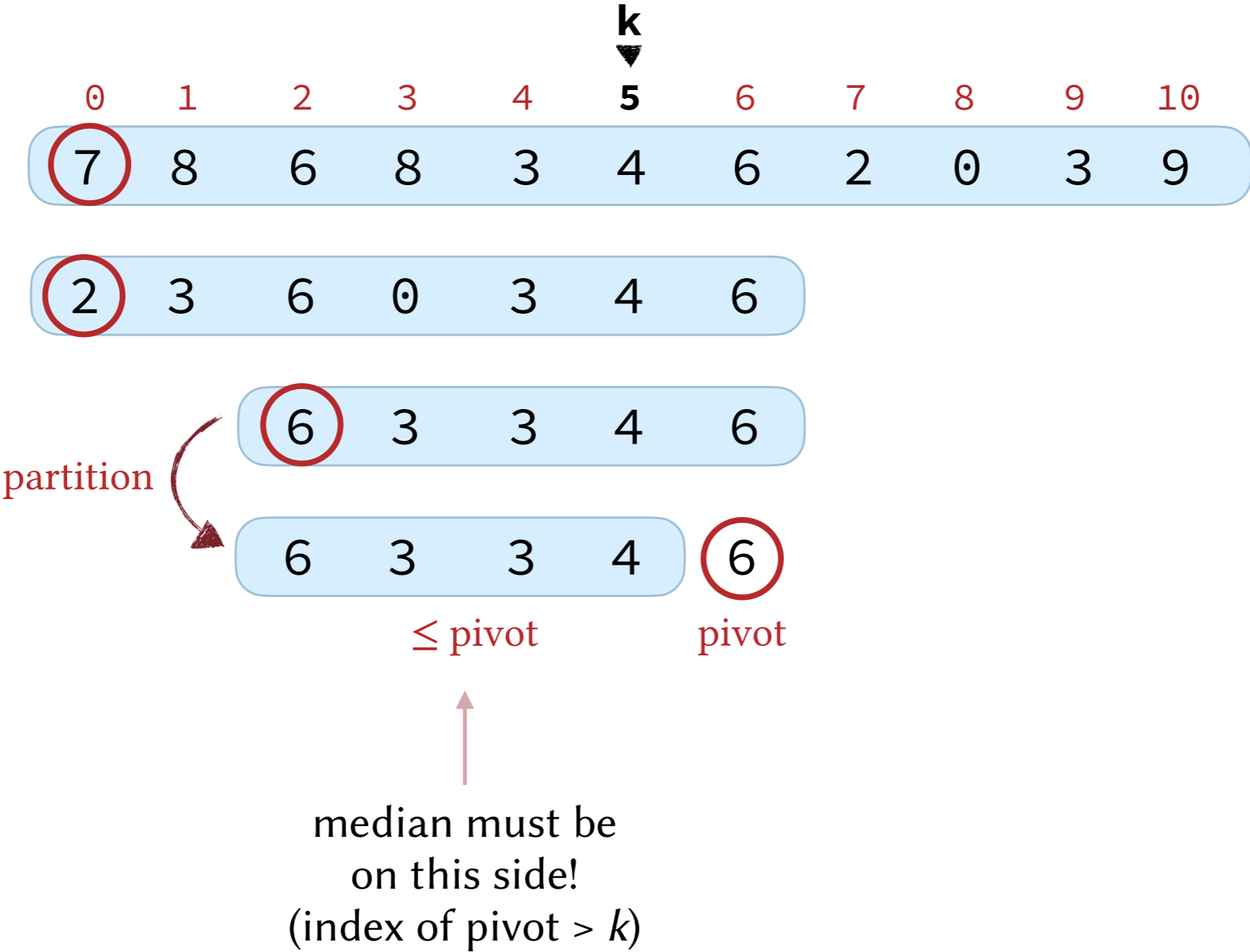
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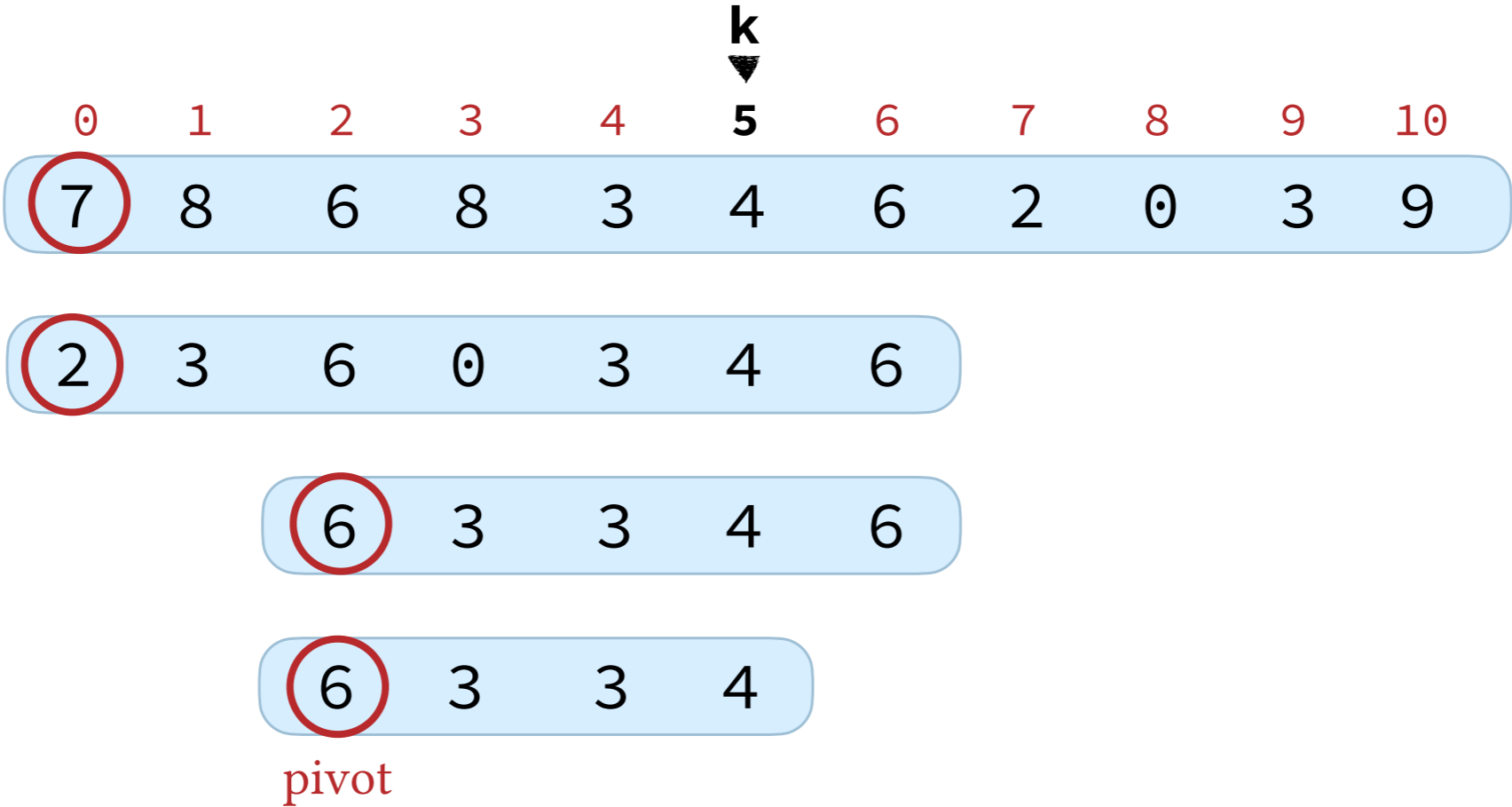
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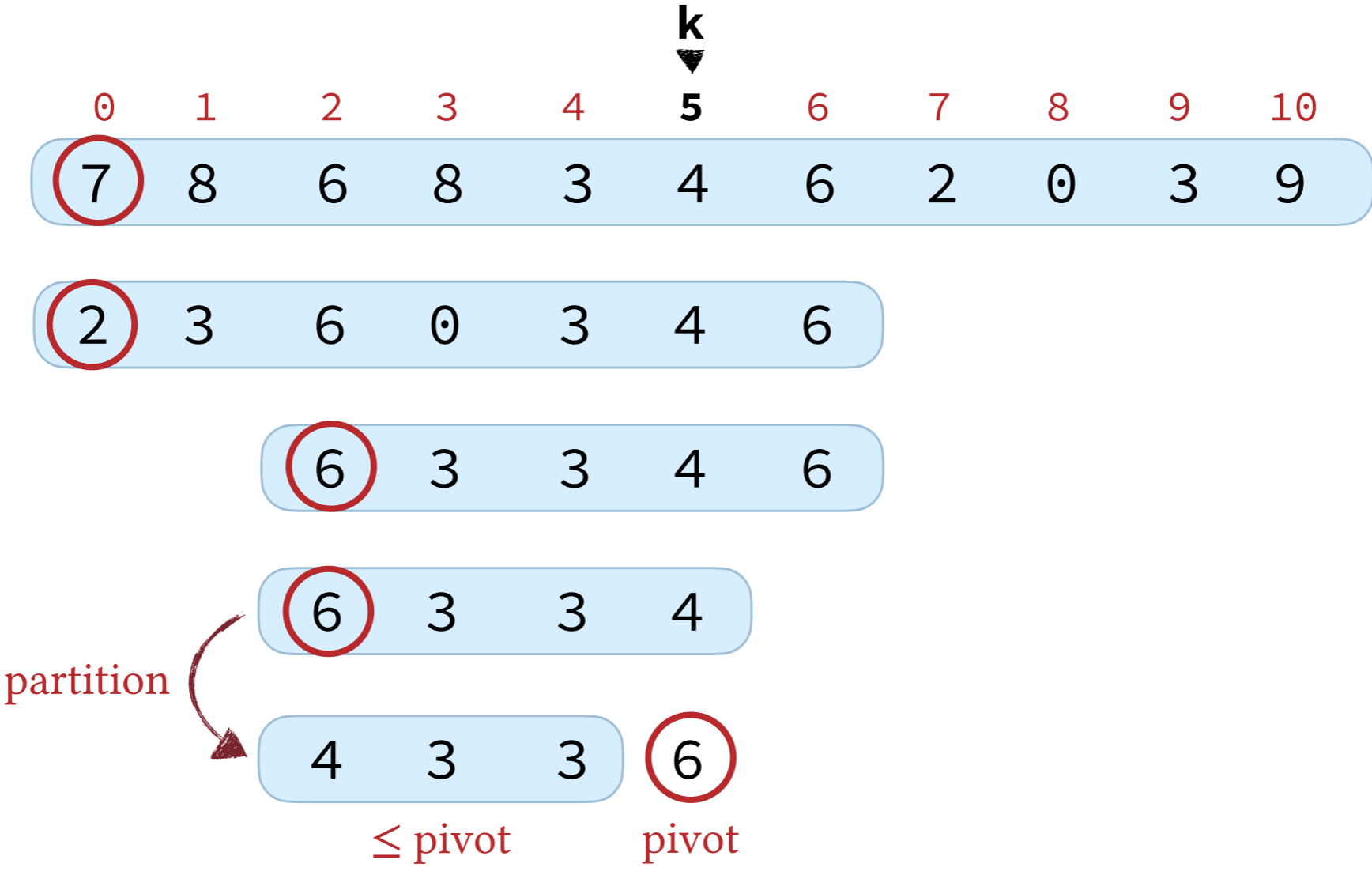
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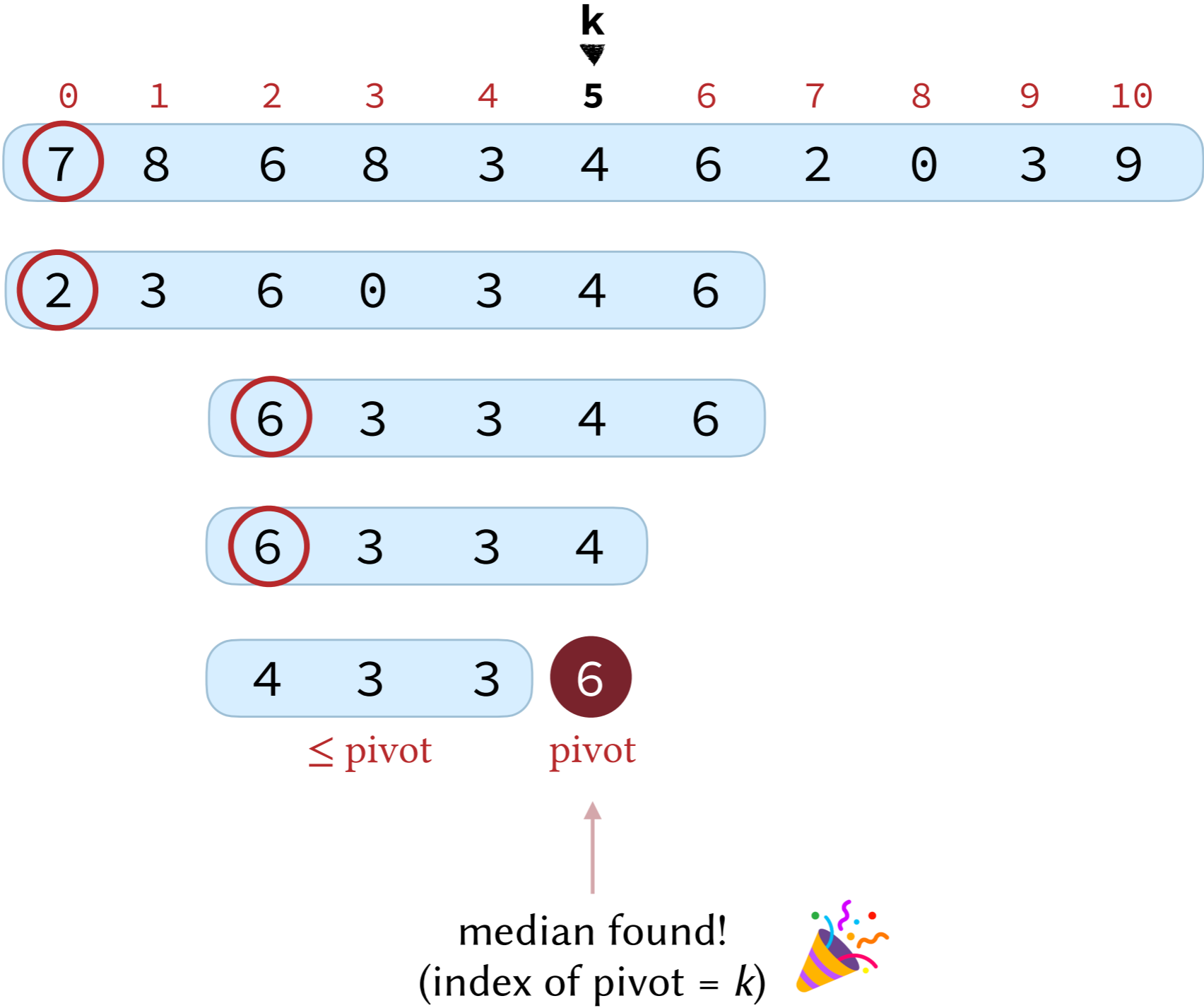
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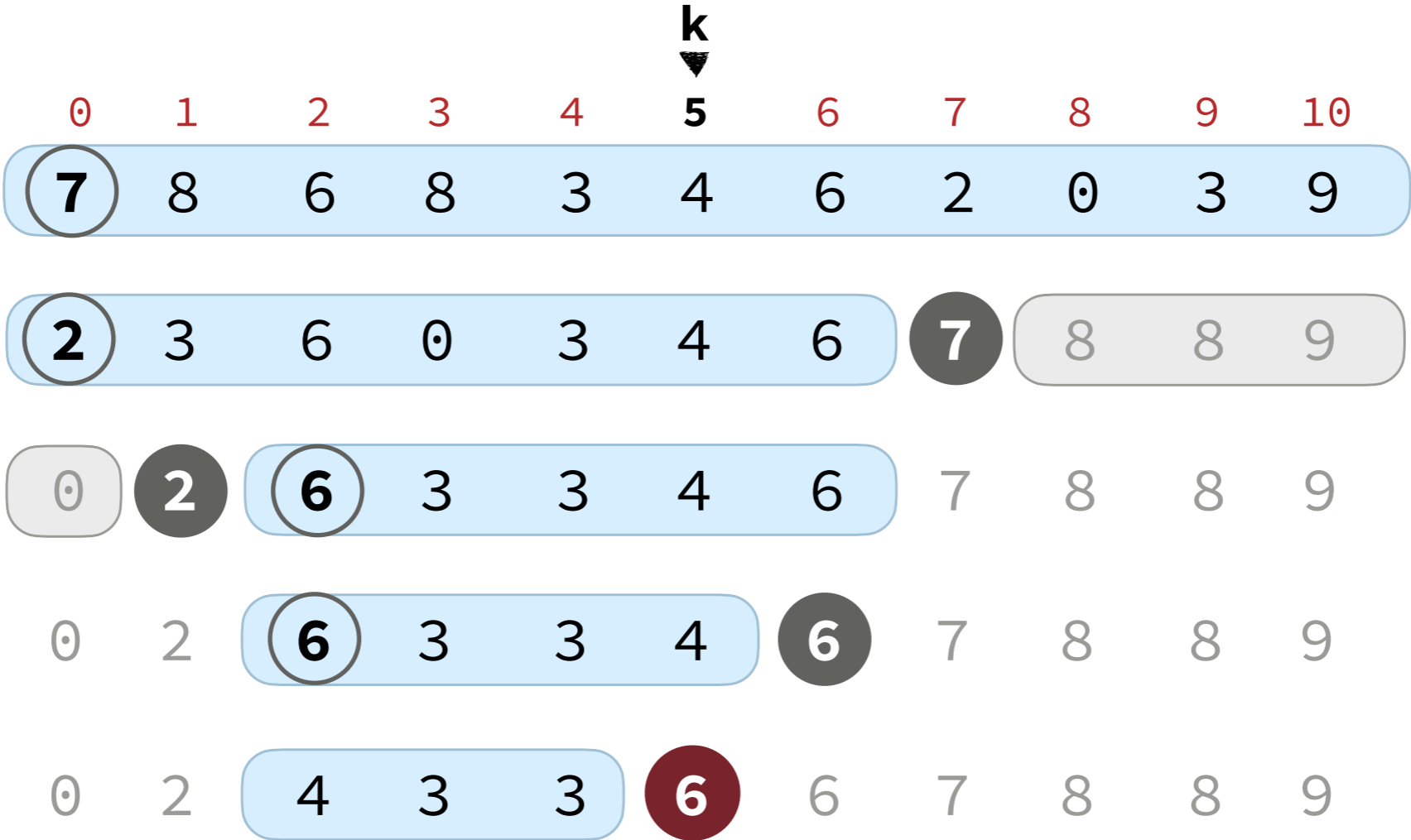
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median found!
(index of pivot = k)

Quickselect Algorithm

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SELECT(a[], first, last, k)
```

```
SHUFFLE(a, first, last) ←
```

```
QUICK-SELECT(a, first, last, k)
```

to guard against the worst case
(or pick pivot randomly)

assuming k is a valid index

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  p = PARTITION(a, first, last)
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  if p == k:  
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  if k > p:  
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  else:  
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    return QUICK-SELECT(a, first, p-1, k)
```


Quickselect Algorithm

```
SELECT(a[], first, last, k)
```

```
  SHUFFLE(a, first, last)
```

```
  QUICK-SELECT(a, first, last, k)
```

```
QUICK-SELECT(a[], first, last, k)
```

```
  if (first >= last):
```

```
    return a[k]
```

```
  p = PARTITION(a, first, last)
```

```
  if p == k:
```

```
    return a[k]
```

```
  if k > p:
```

```
    return QUICK-SELECT(a, p+1, last, k)
```

```
  else:
```

```
    return QUICK-SELECT(a, first, p-1, k)
```

Quickselect Algorithm

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SELECT(a[], first, last, k)
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  SHUFFLE(a, first, last)
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Quickselect Analysis

Best Case.

Quickselect Analysis

Best Case. Element at rank k found immediately after the first partitioning step: $\Theta(n)$.

Quickselect Analysis

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Worst Case.

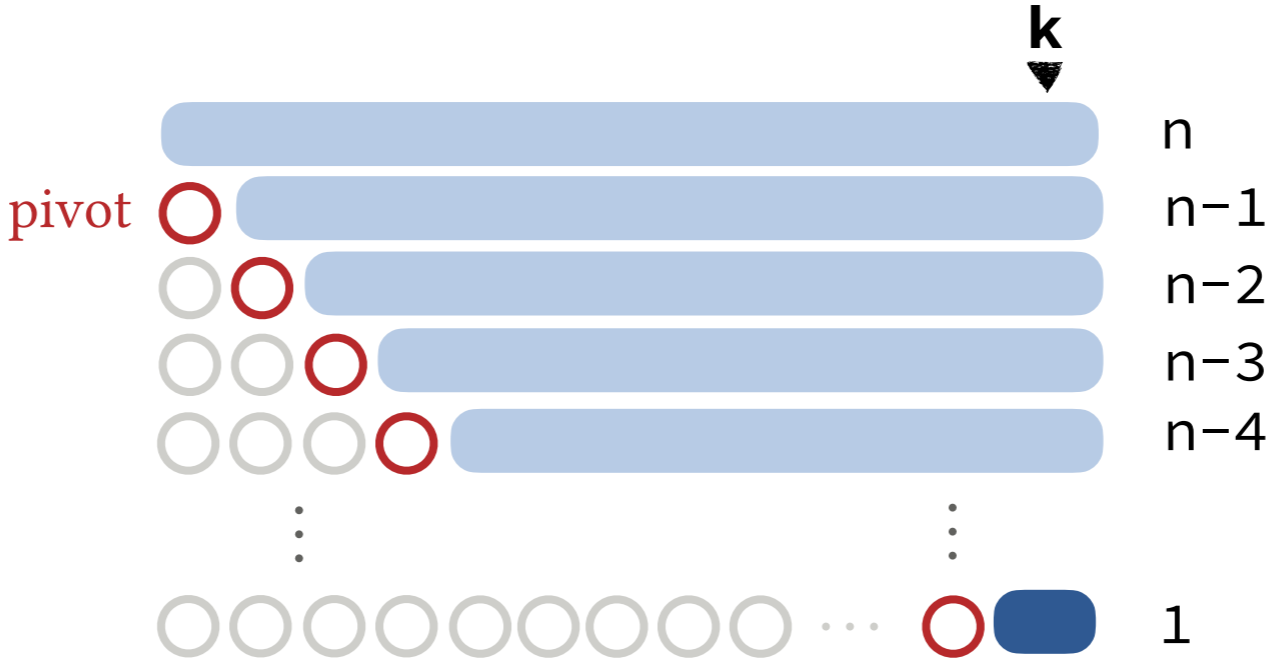
Quickselect Analysis

Best Case. Element at rank k found immediately after the first partitioning step: $\Theta(n)$.

Worst Case. Element at rank k found after $n - 1$ partitioning steps:

$$n + (n - 1) + (n - 2) + \dots + 1 = \Theta(n^2)$$

Example 1. $k = n - 1$



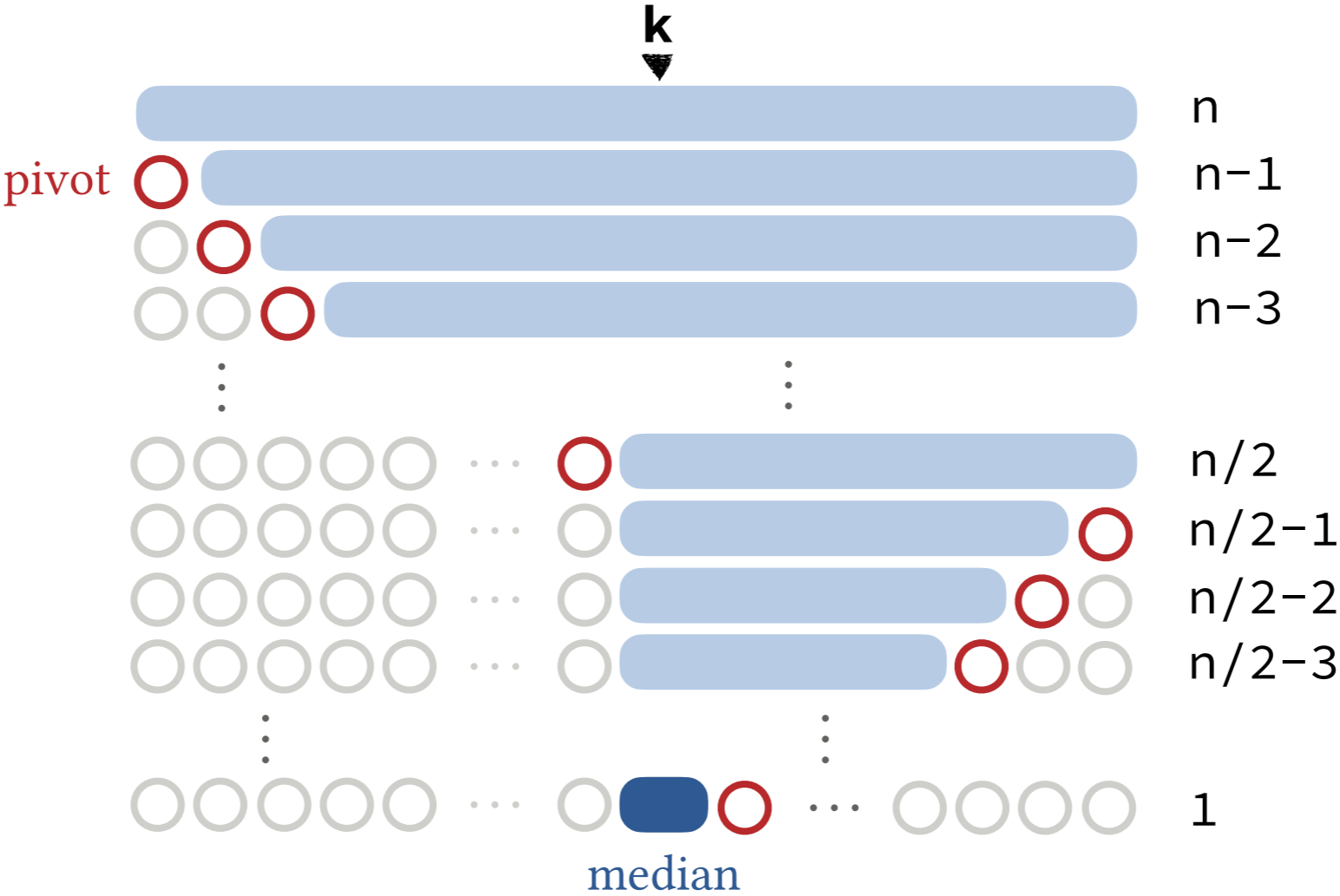
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Example 2. $k = \frac{n}{2}$



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probabilistically almost-
impossible if the array is
shuffled!

Quickselect Analysis

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$$n + (n - 1) + (n - 2) + \dots + 1 = \Theta(n^2)$$

Expected Case. $\Theta(n)$

Intuition. Partitioning always gets rid of around half of the remaining elements.

$$T(n) = T\left(\frac{n}{2}\right) + \sim n$$



time to **select** from
an array of size n

Quickselect Analysis

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time to **partition** an
array of size n

time to **select** from
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time to **partition** an array of size n

time to **select** from an array of size n

time to **select** from an array of size $n/2$

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Best Case. Element at rank k found immediately after the first partitioning step: $\Theta(n)$.

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n



time to partition
the whole array

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$$n + \frac{n}{2}$$



time to partition
half the array

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$$n + (n - 1) + (n - 2) + \dots + 1 = \Theta(n^2)$$

Expected Case. $\Theta(n)$

Intuition. Partitioning always gets rid of around half of the remaining elements.

$$T(n) = T\left(\frac{n}{2}\right) + \sim n$$

$$n + \frac{n}{2} + \frac{n}{4}$$



time to partition
a quarter of the array

Quickselect Analysis

Best Case. Element at rank k found immediately after the first partitioning step: $\Theta(n)$.

Worst Case. Element at rank k found after $n - 1$ partitioning steps:

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Expected Case. $\Theta(n)$

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$$n + \frac{n}{2} + \frac{n}{4} + \dots + 1$$

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Remember!

$$\sum_{i=0}^{\log_2 n} 2^i = 2^{\log_2 n + 1} - 1 = 2n - 1$$

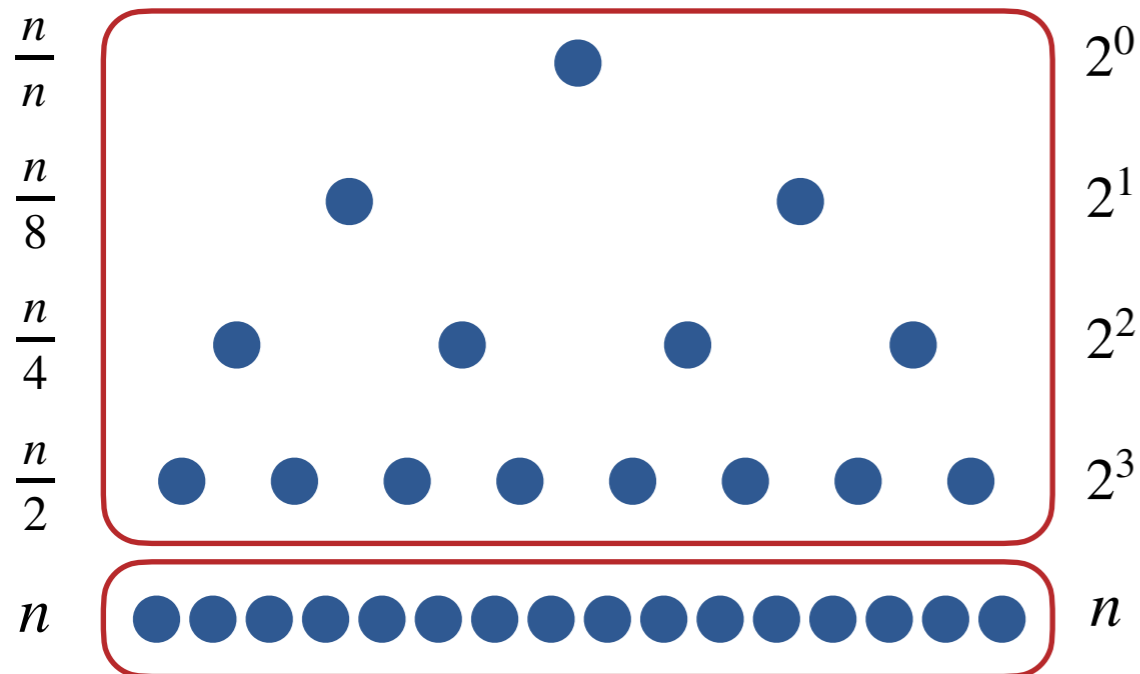
$$1 + 2 + 4 + 8 + \dots + n$$

$$= 2^0 + 2^1 + 2^2 + 2^3 + \dots + 2^{\log_2 n}$$

$$n + \frac{n}{2} + \frac{n}{4} + \dots + 4 + 2 + 1$$

$$n \times \left(1 + \frac{1}{2} + \frac{1}{4} + \dots + \frac{1}{n}\right)$$

$n - 1$ internal nodes in a complete tree of height $\log_2 n$



n leaves in a complete tree of height $\log_2 n$



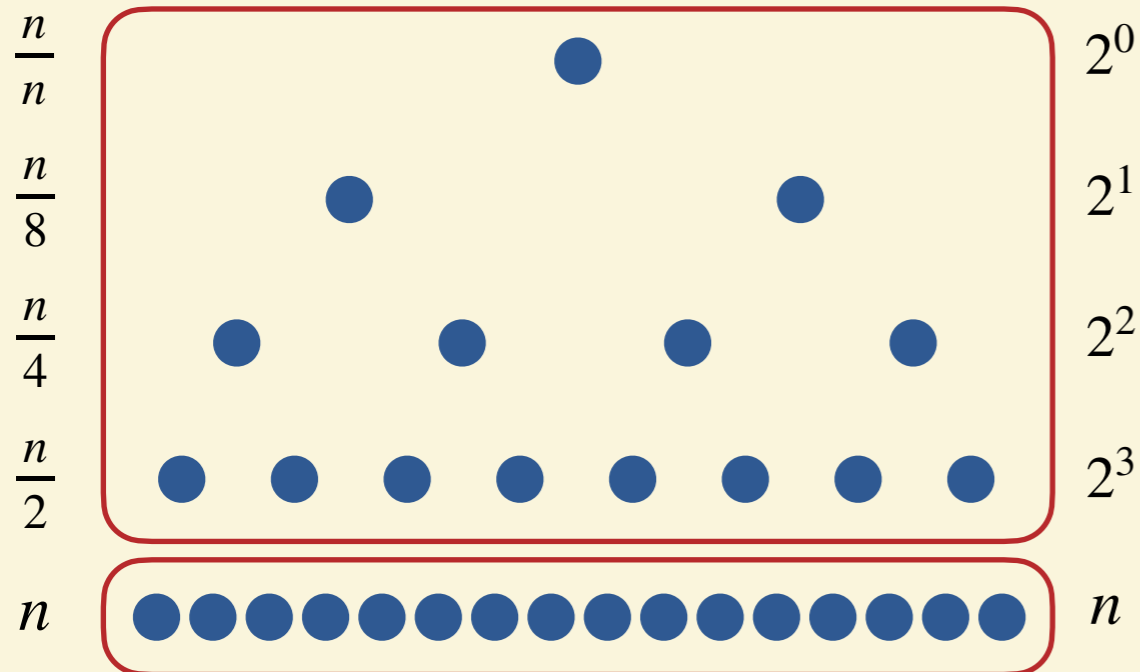
≤ 2

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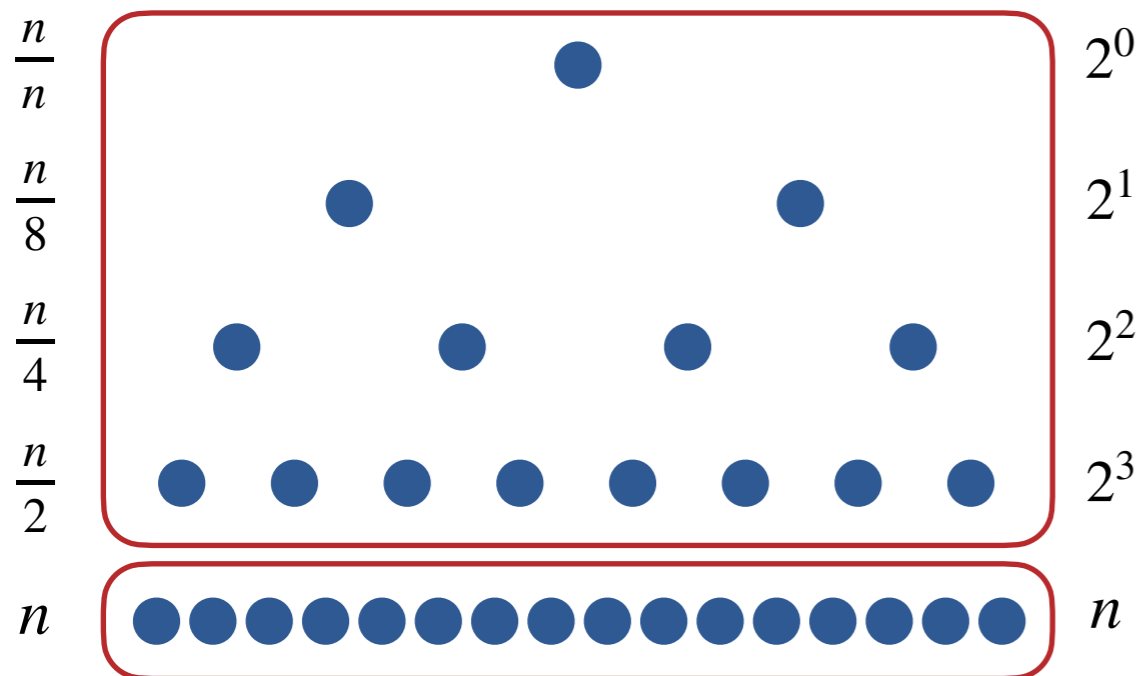
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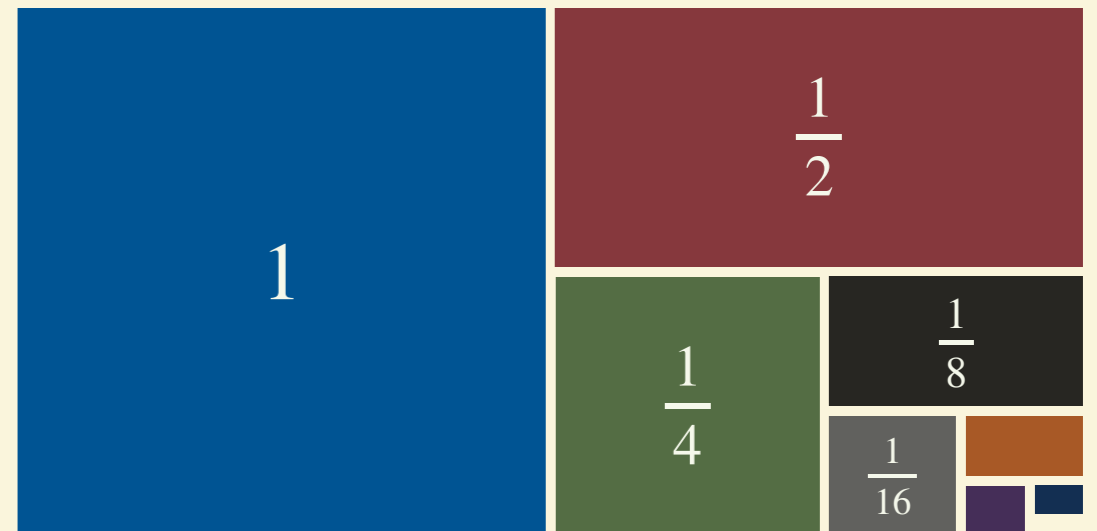
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≤ 2

Analysis Notes

Remember: Code that follows the pattern below has a running time of $\Theta(n \log n)$

foo(n)

```
if (n == 0): return
```

```
foo(n / 2)
```

```
foo(n / 2)
```

```
linear(n)
```

← solve *two* subproblems of half the size.

← do a *linear* amount of work.

Remember: Code that follows the pattern below has a running time of $\Theta(n)$

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```
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```
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```

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```

← solve *one* subproblems of half the size.

← do a *linear* amount of work.

Quickselect Analysis

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Expected Case. $\Theta(n)$

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Can we do better?

Is selection as hard as sorting?

(requires $\sim n \log n$ compares
in the worst case if $k = \frac{n}{2}$)

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Can we do better?

Theoretically. Selection can be done in linear time in the worst case using the **Median of Medians** algorithm. (Blum, Floyd, Pratt, Rivest, and Tarjan 1973).

Practically. Quickselect is faster in practice.

JOURNAL OF COMPUTER AND SYSTEM SCIENCES 7, 448–461 (1973)

Time Bounds for Selection*

MANUEL BLUM, ROBERT W. FLOYD, VAUGHAN PRATT,
RONALD L. RIVEST, AND ROBERT E. TARJAN

Department of Computer Science, Stanford University, Stanford, California 94305

Received November 14, 1972

The number of comparisons required to select the i -th smallest of n numbers is shown to be at most a linear function of n by analysis of a new selection algorithm—PICK. Specifically, no more than $5.4305n$ comparisons are ever required. This bound is improved for extreme values of i , and a new lower bound on the requisite number of comparisons is also proved.



Introselect

From Wikipedia, the free encyclopedia

In **computer science**, **introselect** (short for "introspective selection") is a **selection algorithm** that is a **hybrid** of **quickselect** and **median of medians** which has fast average performance and optimal worst-case performance. Introselect is related to the **introsort sorting algorithm**: these are analogous refinements of the basic quickselect and **quicksort** algorithms, in that they both start with the quick algorithm, which has good average performance and low overhead, but fall back to an optimal worst-case algorithm (with higher overhead) if the quick algorithm does not progress rapidly enough. Both algorithms were introduced by **David Musser** in (**Musser 1997**), with the purpose of providing **generic algorithms** for the **C++ Standard Library** that have both fast average performance and optimal worst-case performance, thus allowing the performance requirements to be tightened.^[1] However, in most C++ Standard Library implementations that use introselect, another "introselect" algorithm is used, which combines quickselect and heapselect, and has a worst-case running time of $O(n \log n)$ ^[2].

Introselect

Class	Selection algorithm
Data structure	Array
Worst-case performance	$O(n)$
Best-case performance	$O(n)$

Quicksort Improvement

What is the order of growth of the running time of **quicksort** is if a linear time median finding algorithm is used to pick the pivot?

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What is the order of growth of the running time of **quicksort** if a linear time median finding algorithm is used to pick the pivot?

Answer. If the pivot is always the median, the array is always split into almost equally-sized partitions. Therefore, the algorithm would run in $\Theta(n \log n)$.

Quicksort Improvement

What is the order of growth of the running time of **quicksort** if a linear time median finding algorithm is used to pick the pivot?

Answer. If the pivot is always the median, the array is always split into almost equally-sized partitions. Therefore, the algorithm would run in $\Theta(n \log n)$.

However: the overhead for finding the pivot would be high and the algorithm would be slower in practice compared to just picking the pivot randomly.

Selection (special cases)

- Finding the **largest** (or smallest) element: $n - 1$ compares.
Perform a linear scan in the array.

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 - **Can we do better?**
We can use some of the information gained while finding the maximum to find the minimum!

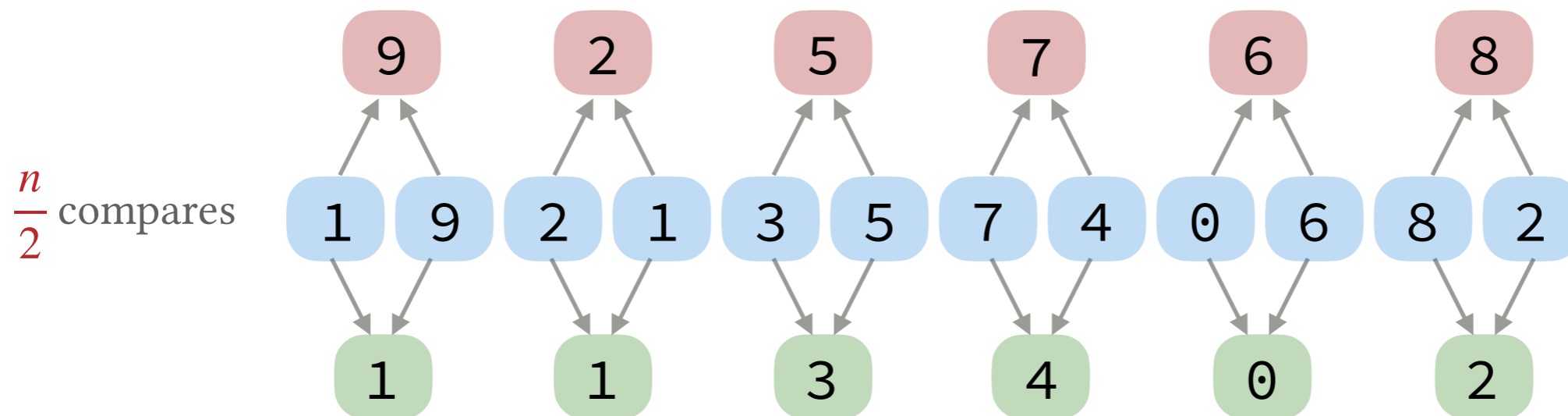
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1 9 2 1 3 5 7 4 0 6 8 2

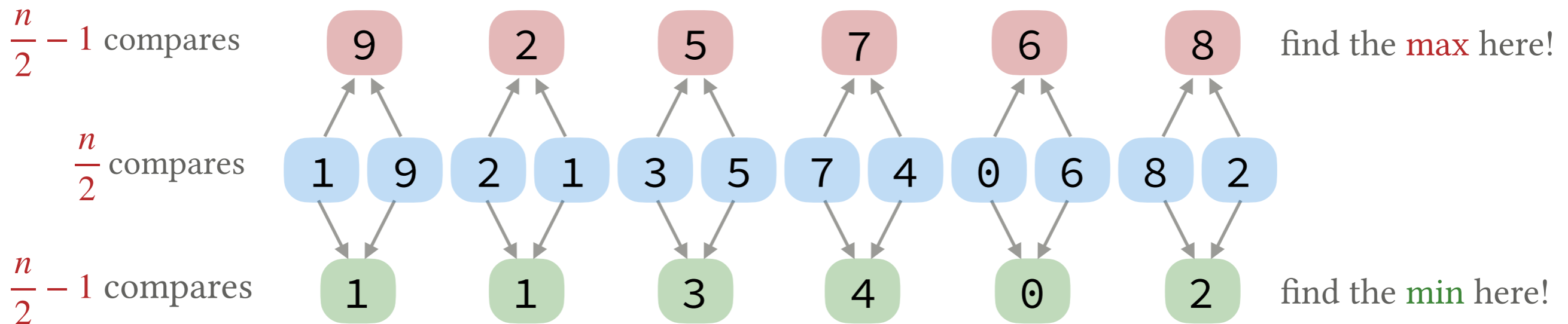
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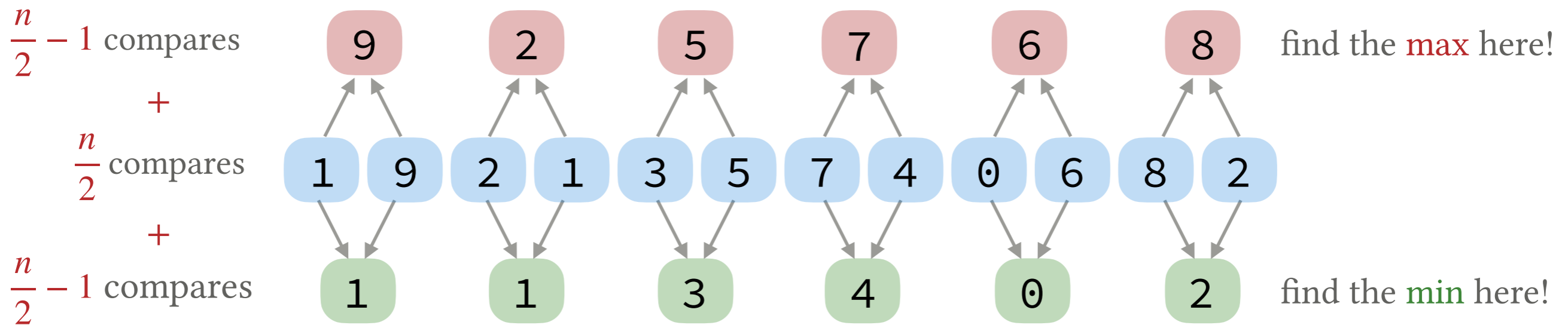
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$$\frac{3}{2}n - 2 \text{ compares}$$

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Theorem. Any comparison-based algorithm for finding both the minimum and maximum elements in an arbitrary array must perform at least $\frac{3}{2}n - 2$ compares in the worst case*.

* for the **proof**, see Computer Algorithms: Introduction to Design and Analysis for Sara Baase and Allen Van Gelder

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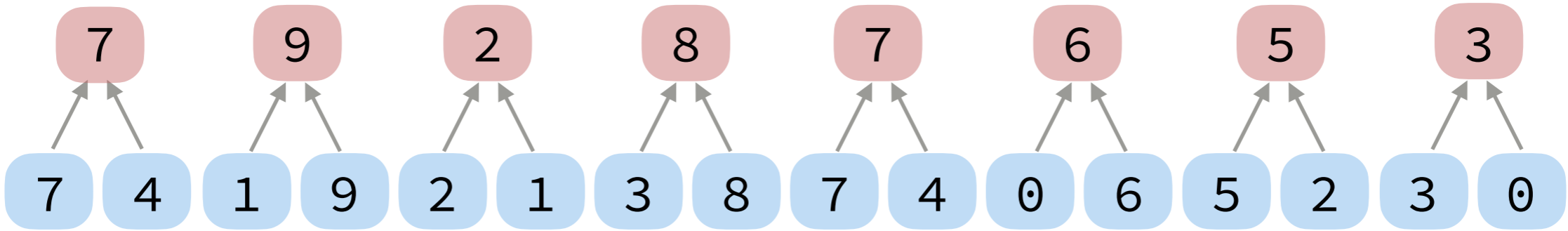
Selecting the 2nd Largest Element

A **Tournament**-based approach.

7 4 1 9 2 1 3 8 7 4 0 6 5 2 3 0

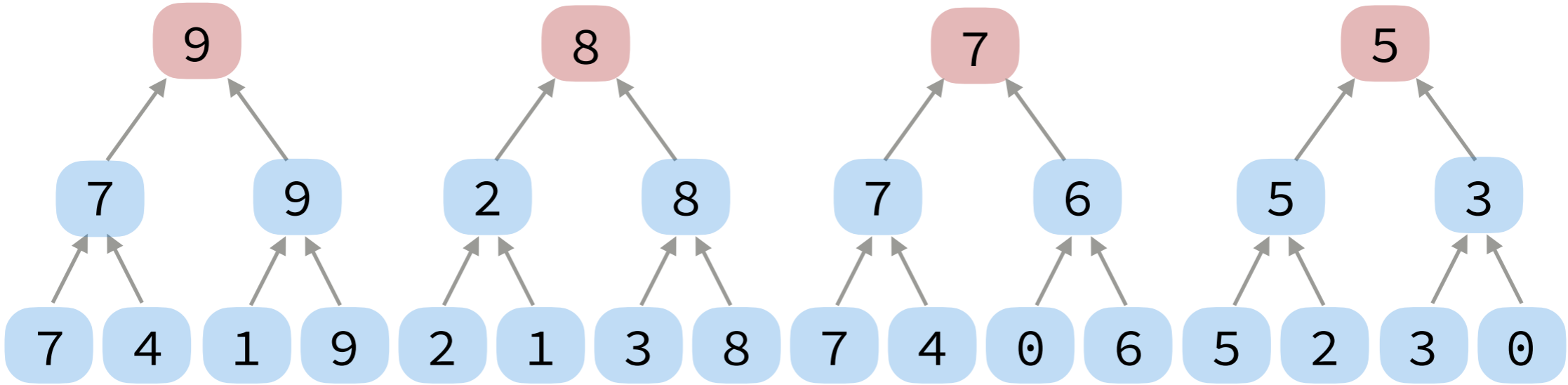
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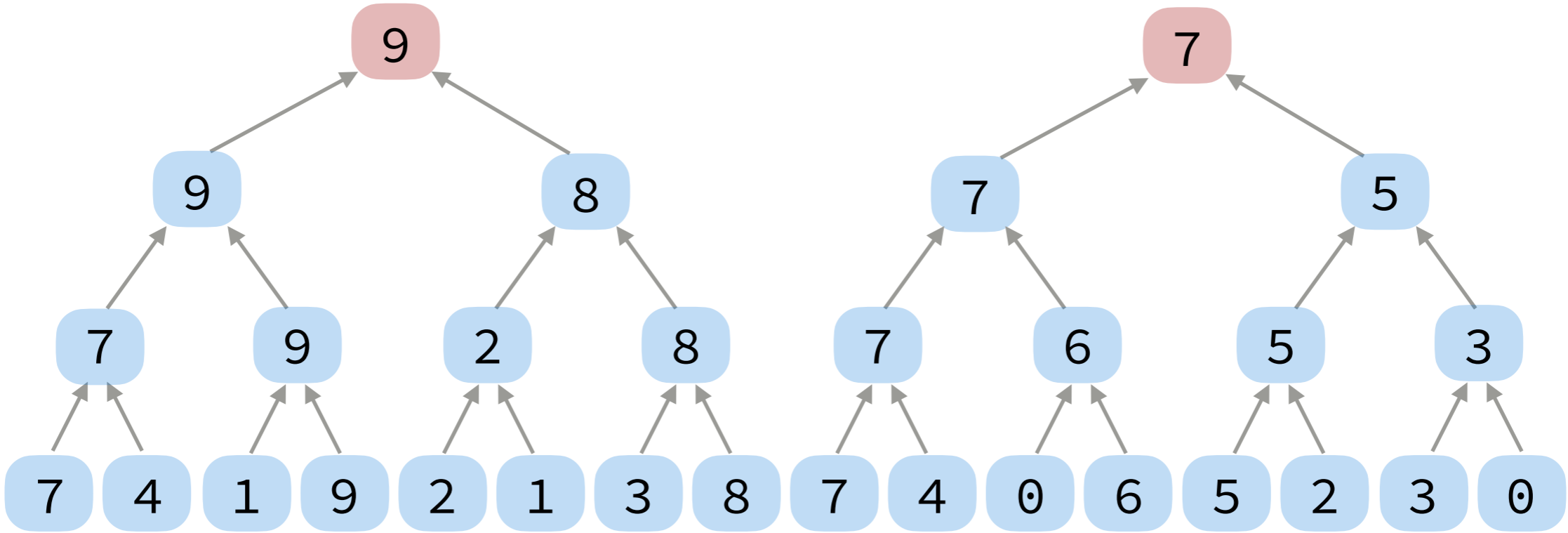
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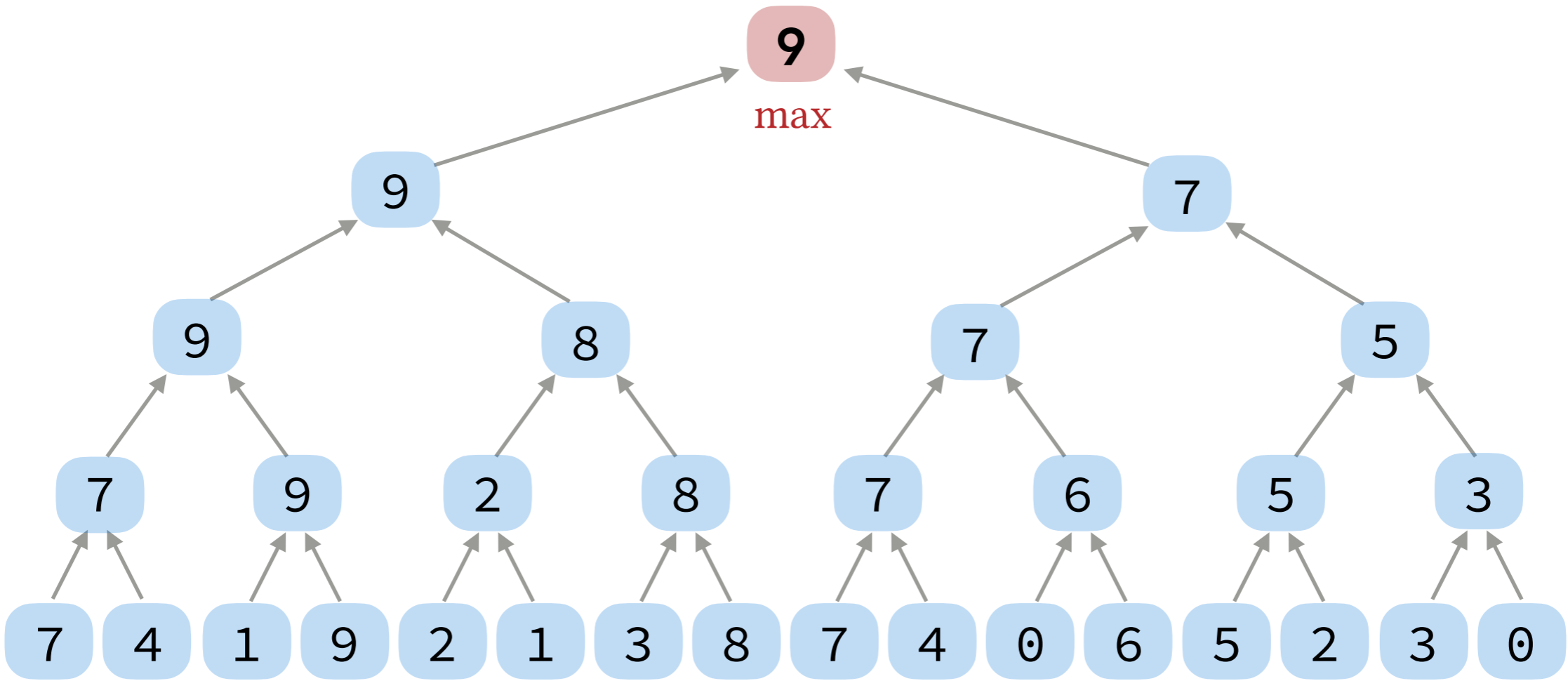
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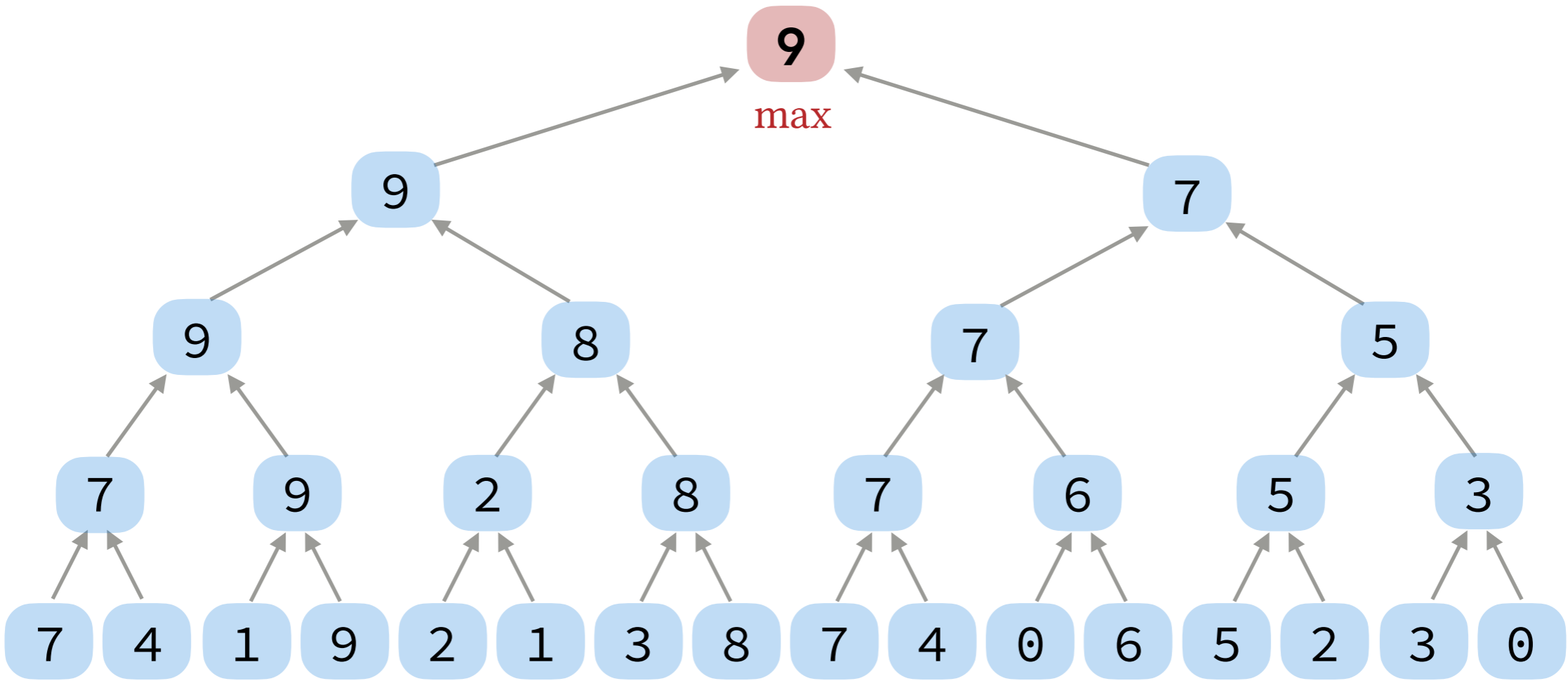
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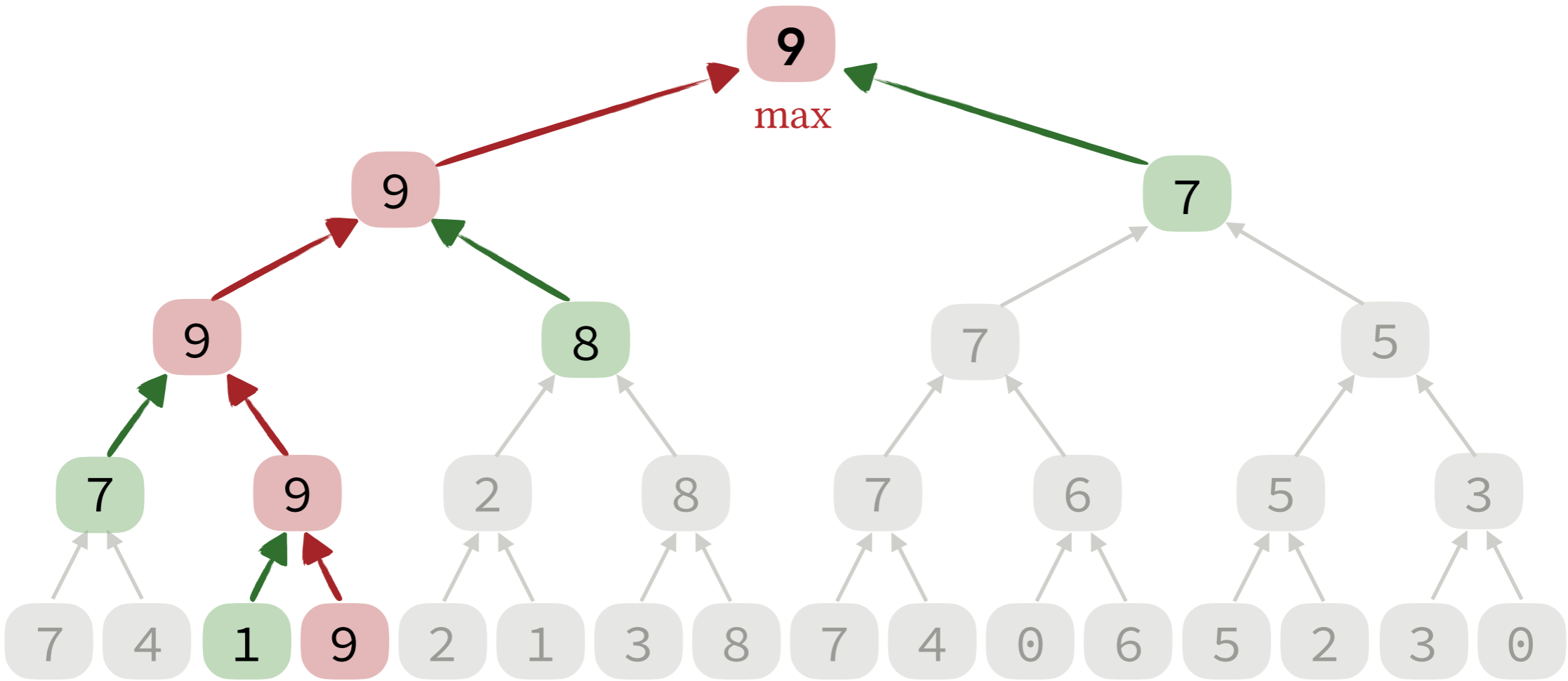
Observation. A key that loses to a key other than the max can't possibly be the second largest. There are at least two keys larger than that key: the max and the key it lost to!



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The second largest must be on this path!
(must have lost to the max)

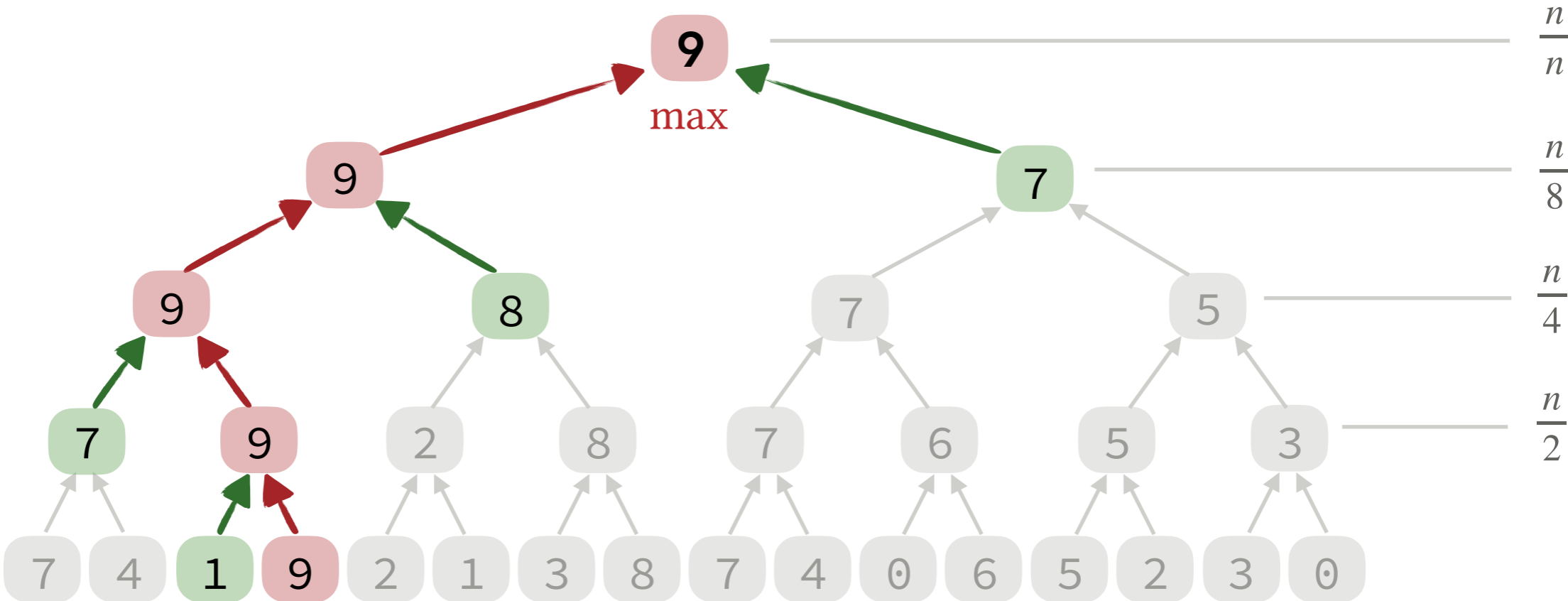
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 Proof by contradiction.

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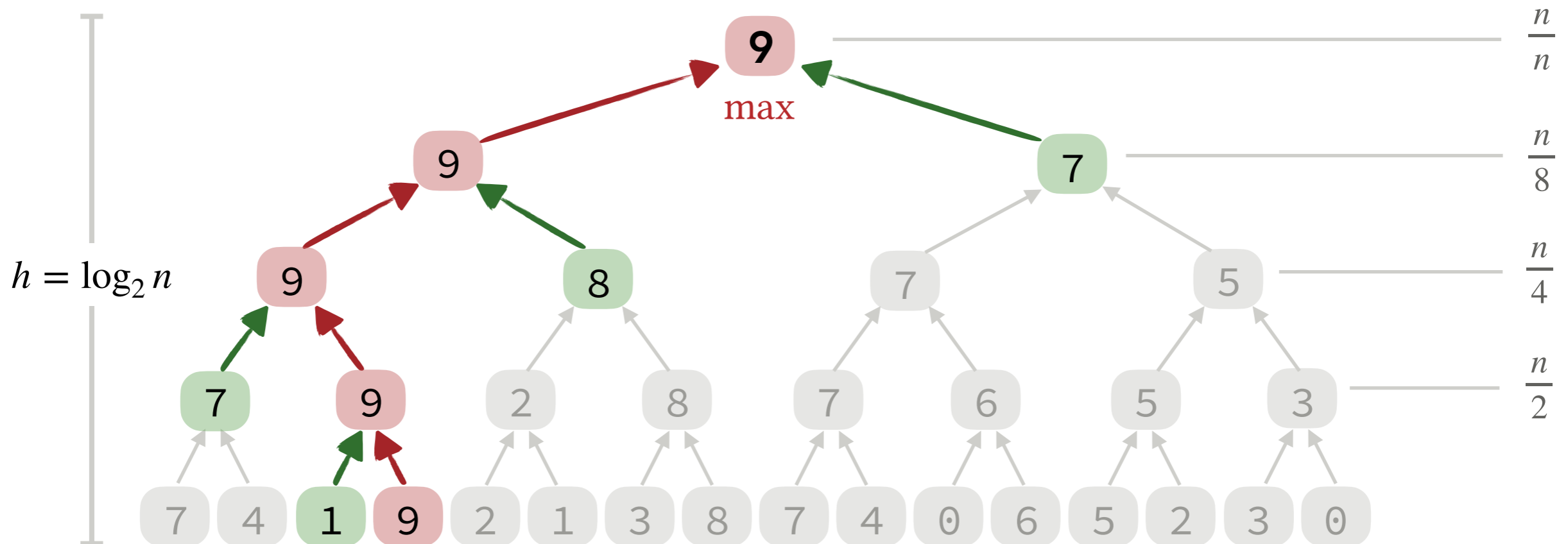
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- The algorithm needs an additional $\log_2 n - 1$ compares to find the second largest among the nodes on the path representing comparisons with the max.



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Theorem. Any comparison-based algorithm for finding the second largest element in an arbitrary array must make at least $n + \lceil \log_2 n \rceil - 2$ compares in the worst case*.

* for the **proof**, see Computer Algorithms: Introduction to Design and Analysis for Sara Baase and Allen Van Gelder

Selecting the 2nd Largest Element

A **Tournament**-based approach.

Observation. Keys that lose to keys other than the max can't possibly be the second largest.
Proof by contradiction.

Analysis. (assuming n is a power of 2)

- The algorithm performs $\frac{n}{2} + \frac{n}{4} + \frac{n}{8} + \dots + 1 = n - 1$ compares to find the max.
- The algorithm needs an additional $\log_2 n - 1$ compares to find the second largest among the nodes on the path representing comparisons with the max.

Theorem. Any comparison-based algorithm for finding the second largest element in an arbitrary array must make at least $n + \lceil \log_2 n \rceil - 2$ compares in the worst case*.

Implementation. How can we keep track of which elements lost to the max?

* for the **proof**, see Computer Algorithms: Introduction to Design and Analysis for Sara Baase and Allen Van Gelder

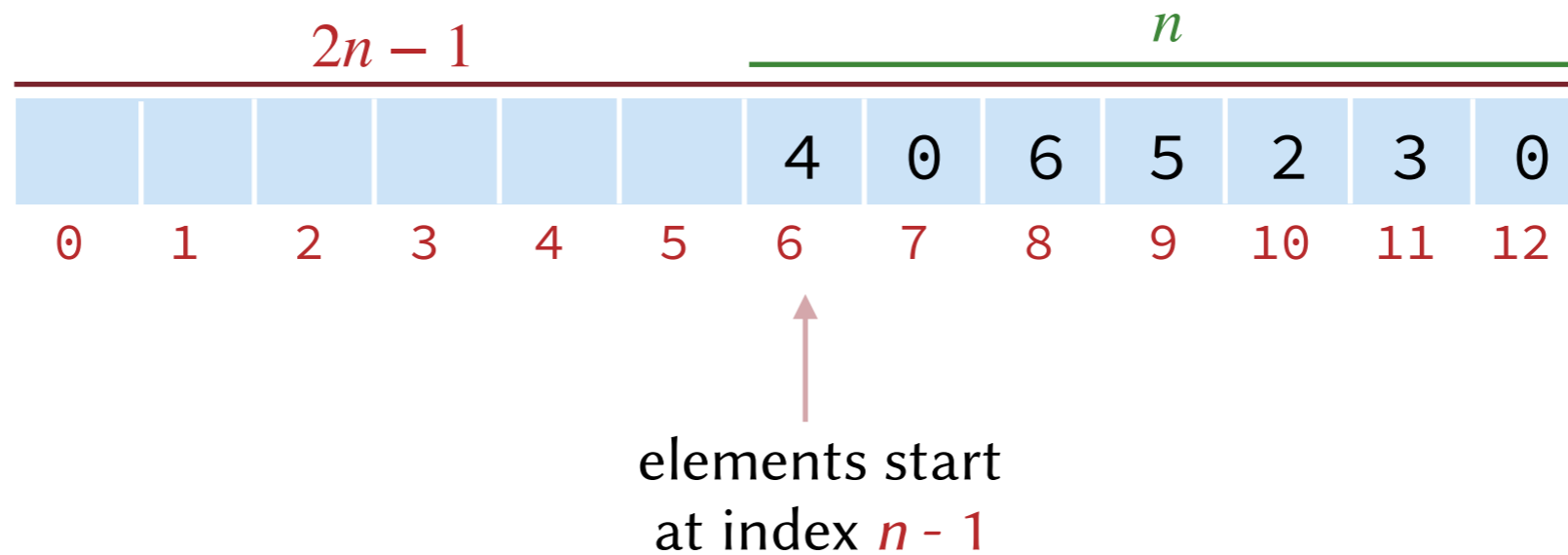
Implementation

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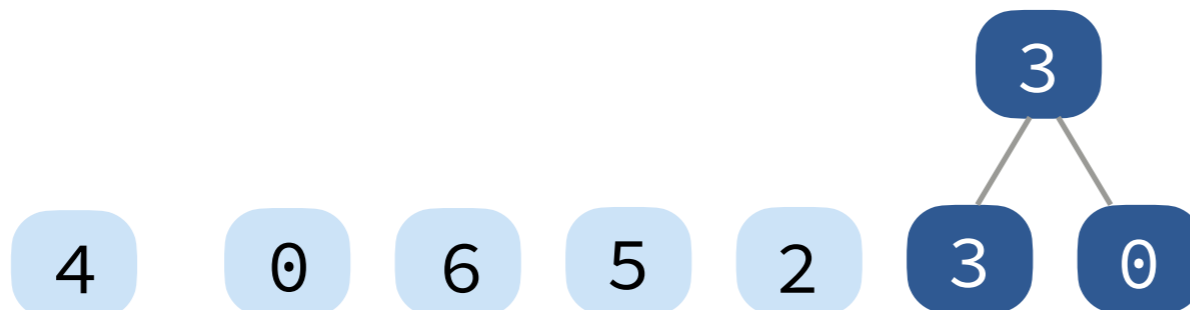
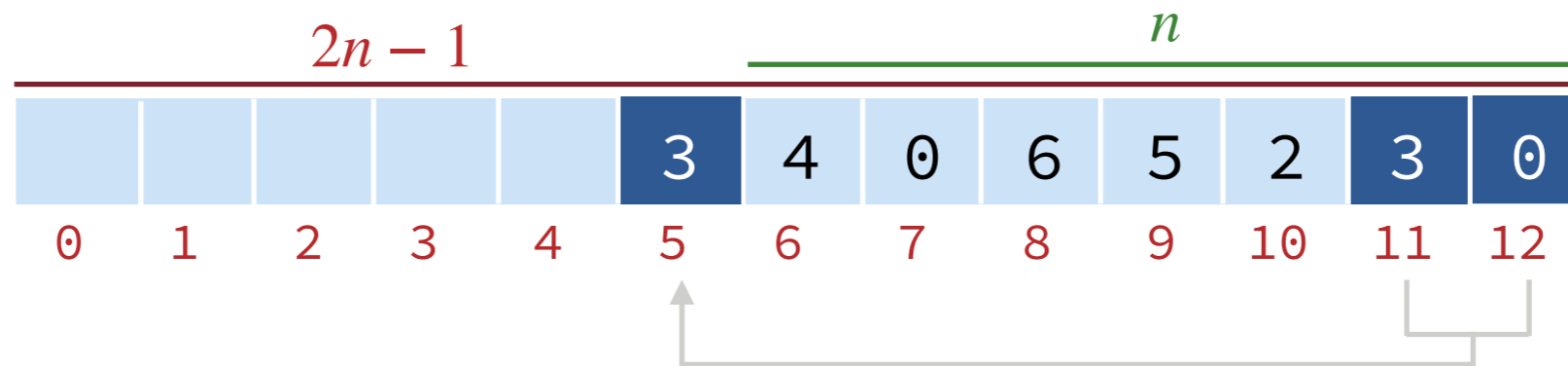
1. Load the n elements into the **right half** of an array of size $2n - 1$.



Implementation

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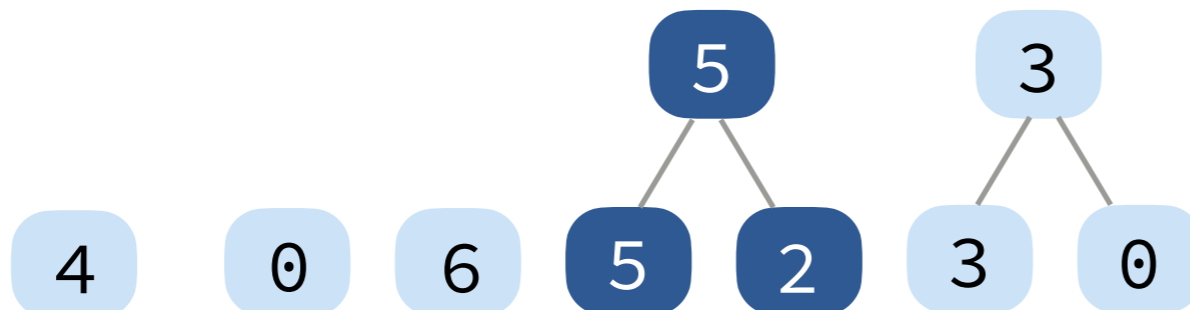
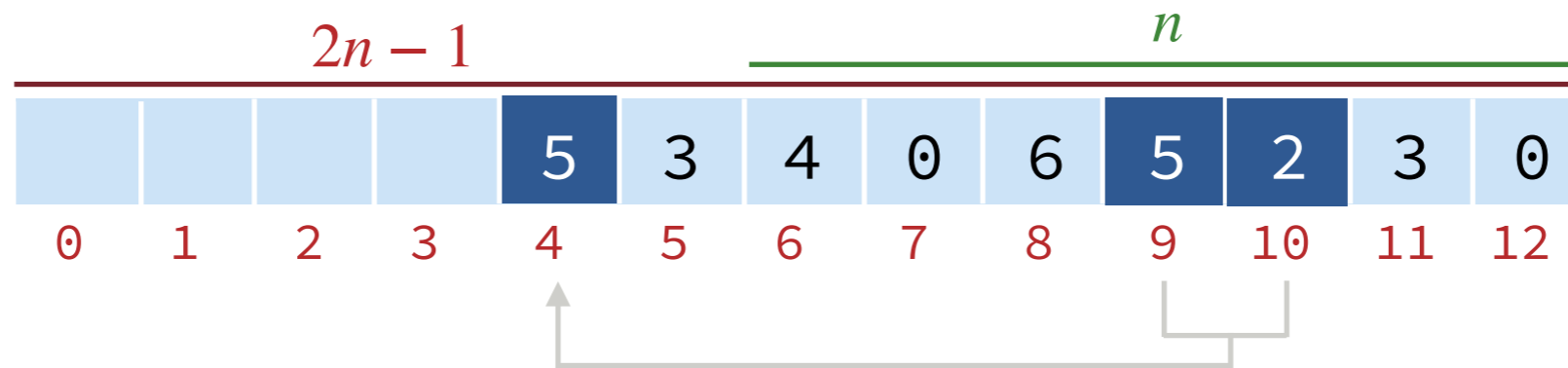
1. Load the n elements into the **right half** of an array of size $2n$.
2. Compute the **max** of each pair and store it at the location of the **parent**.



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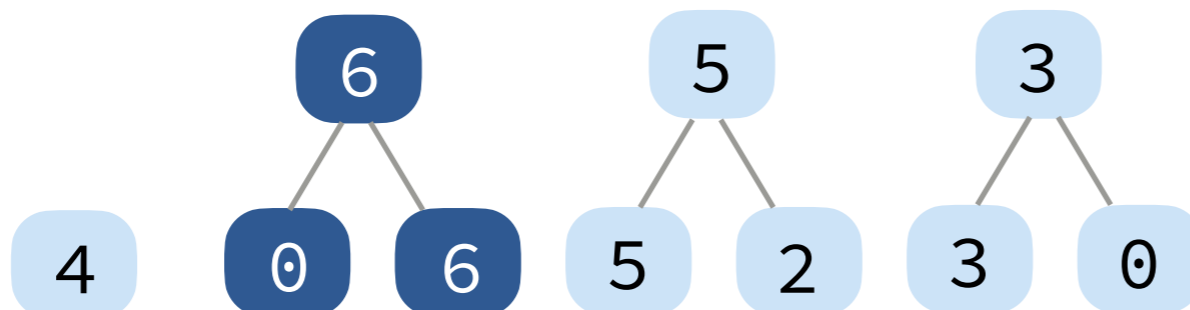
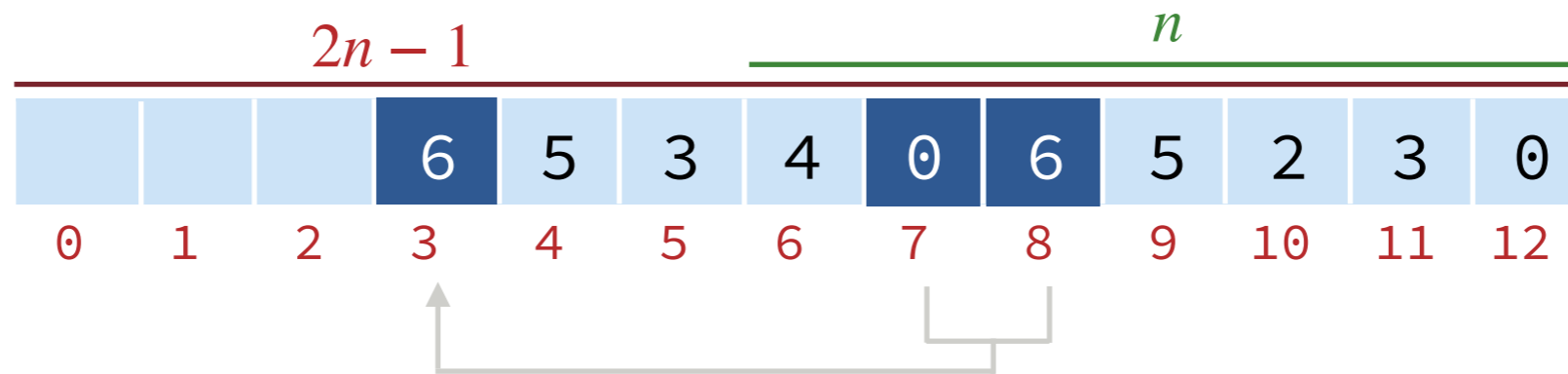
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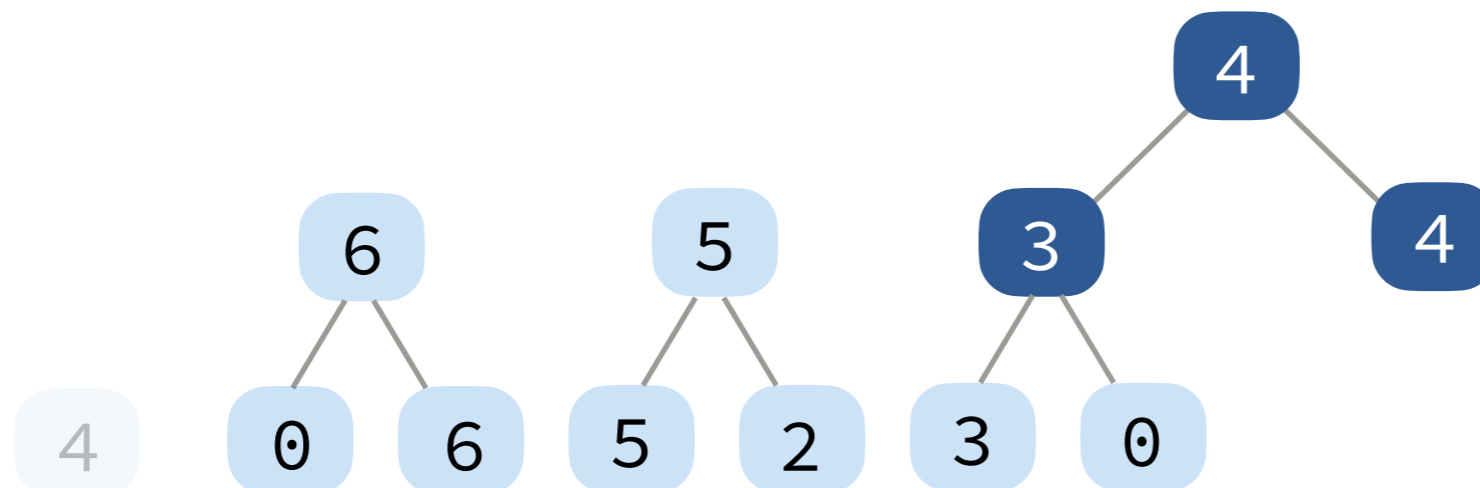
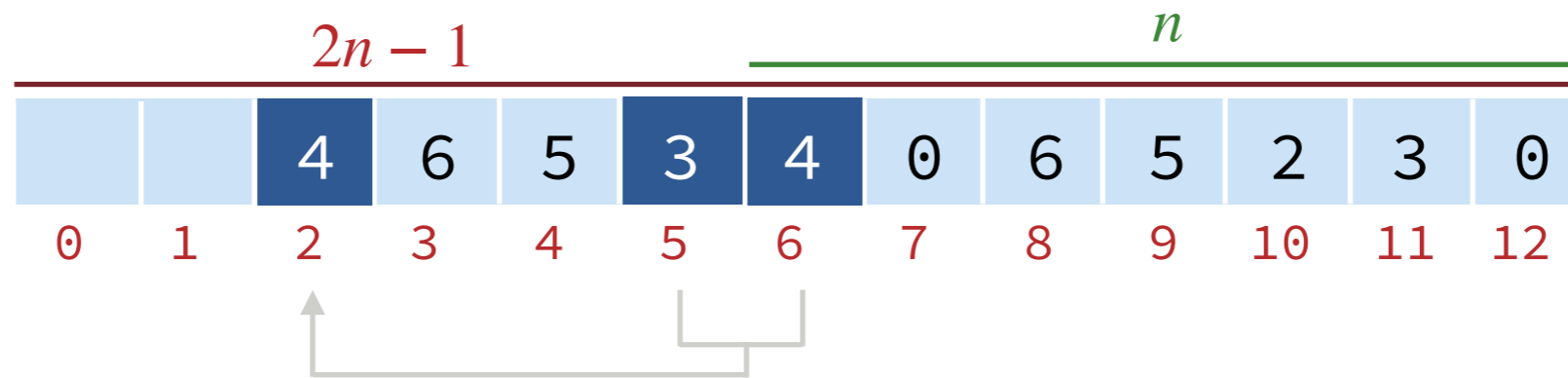
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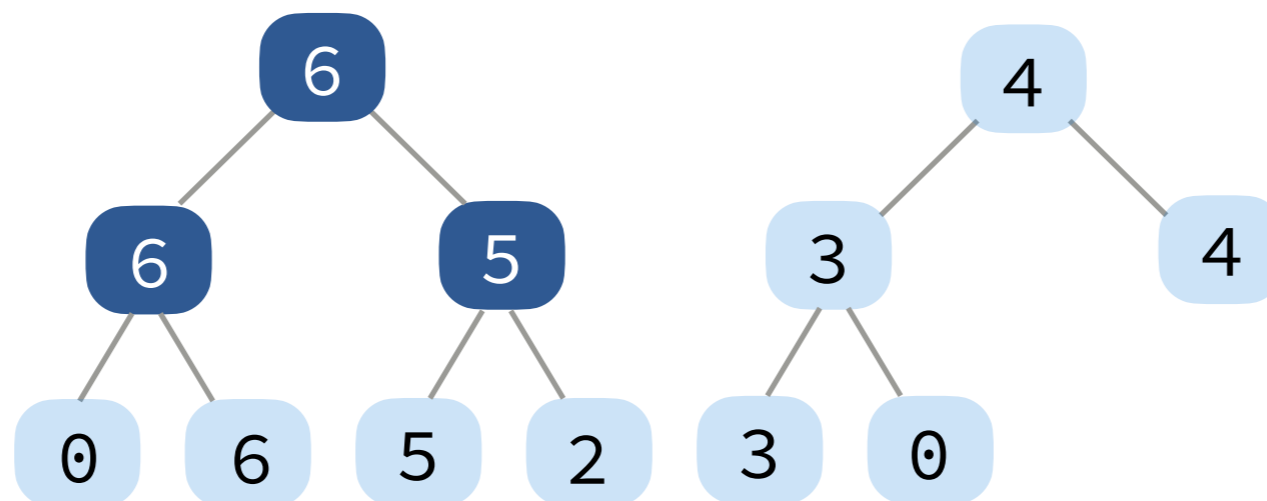
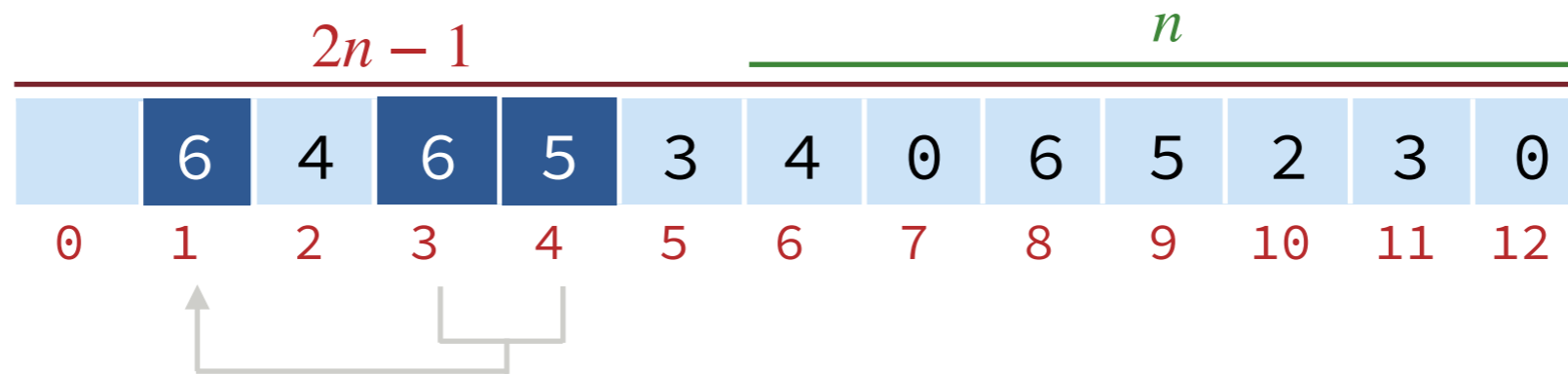
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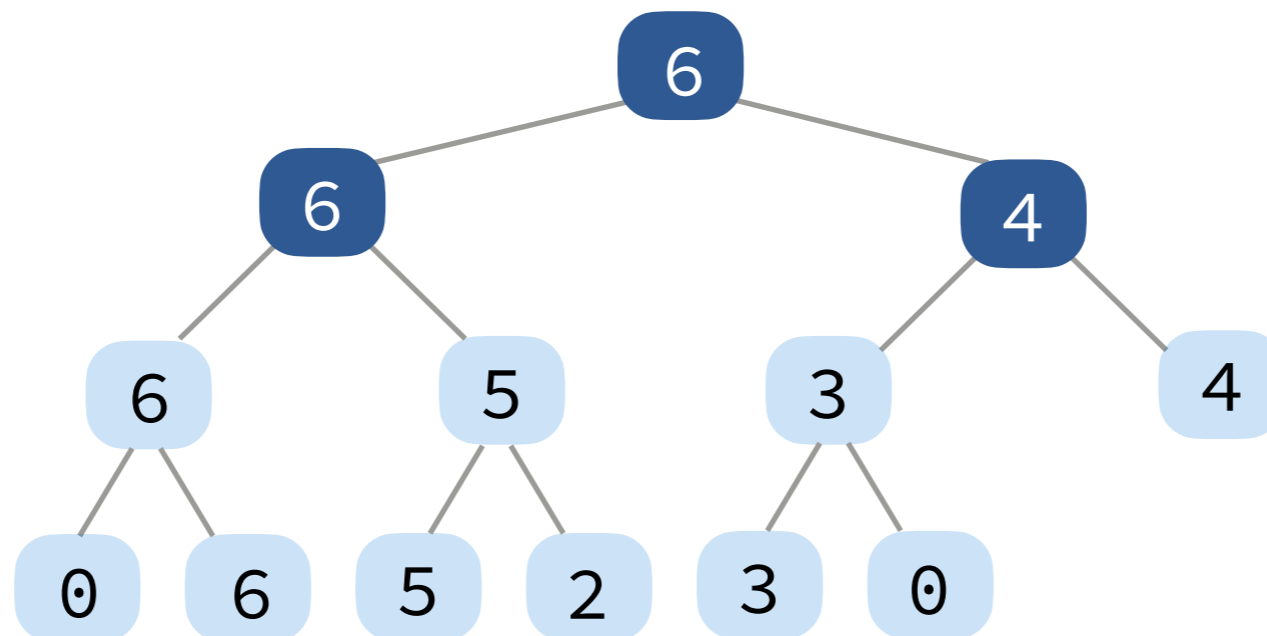
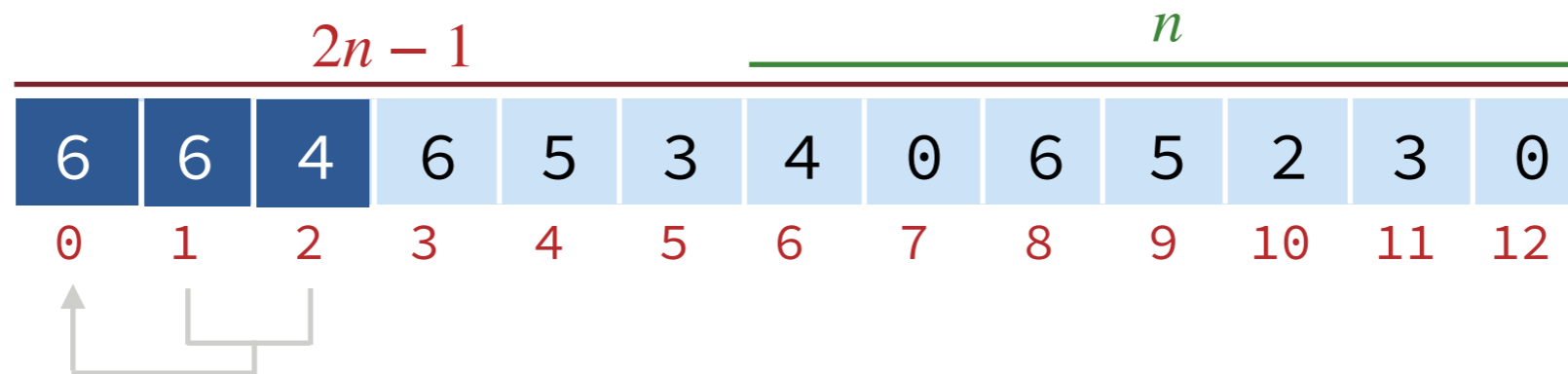
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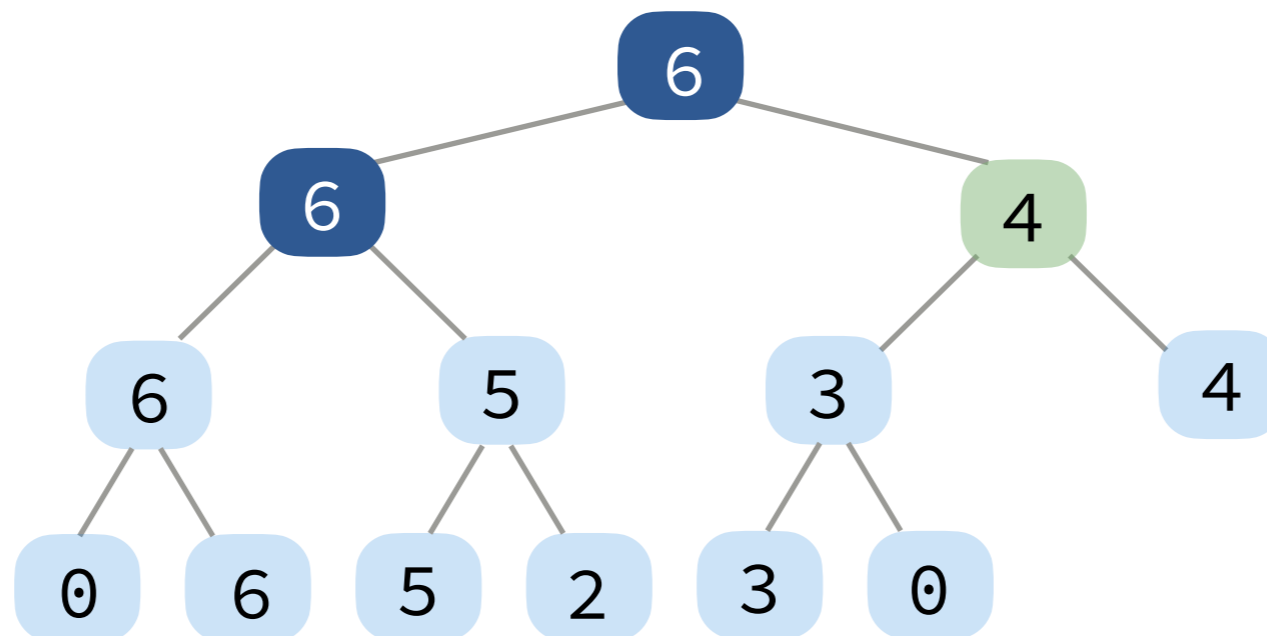
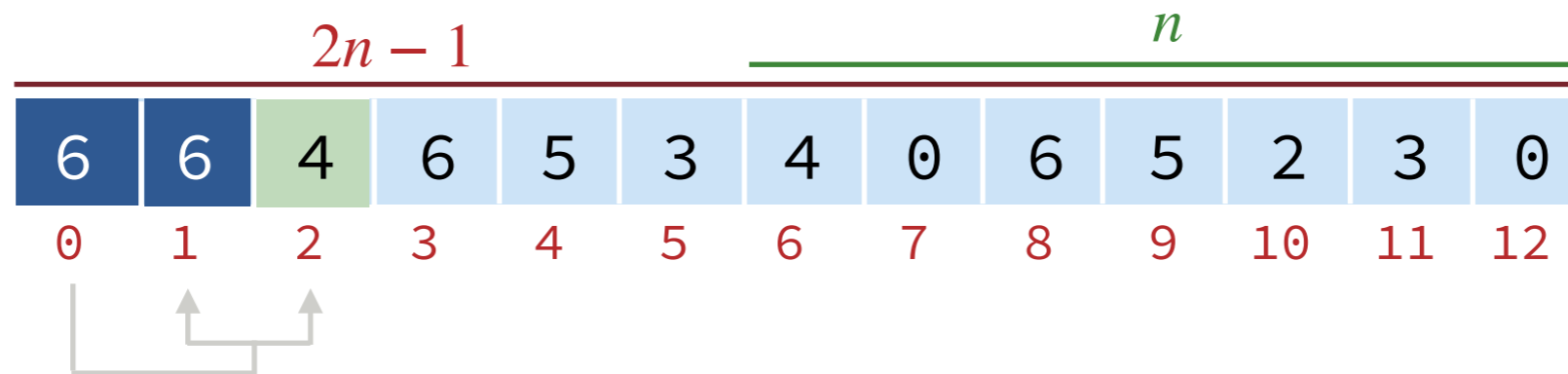
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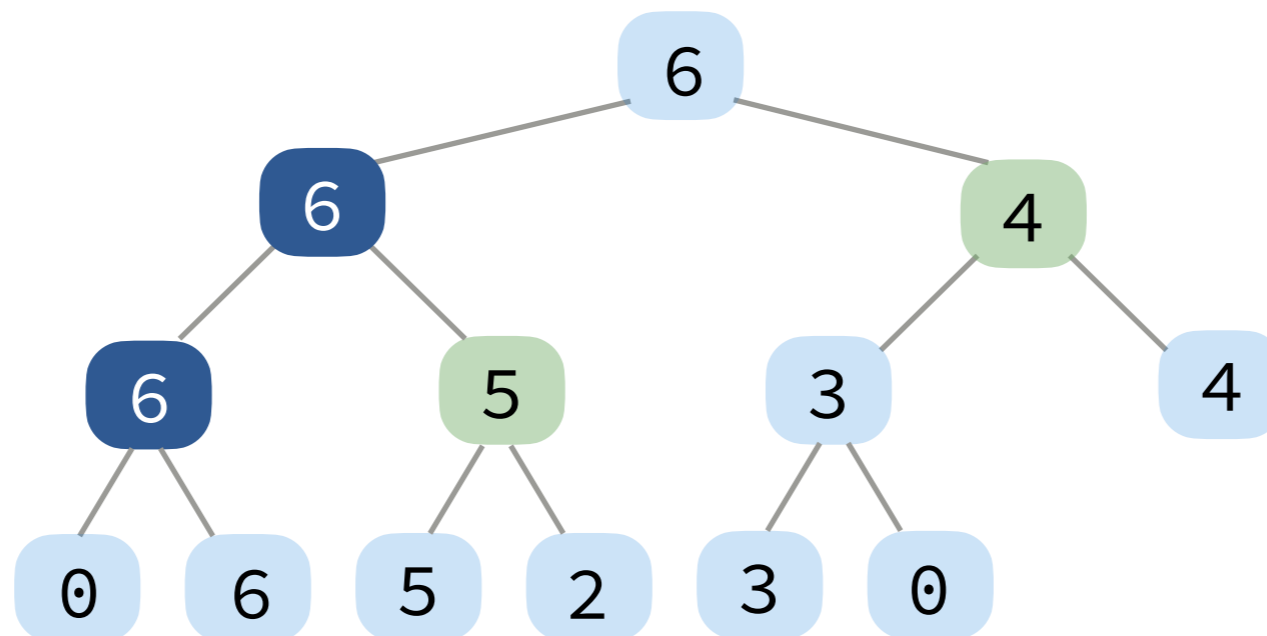
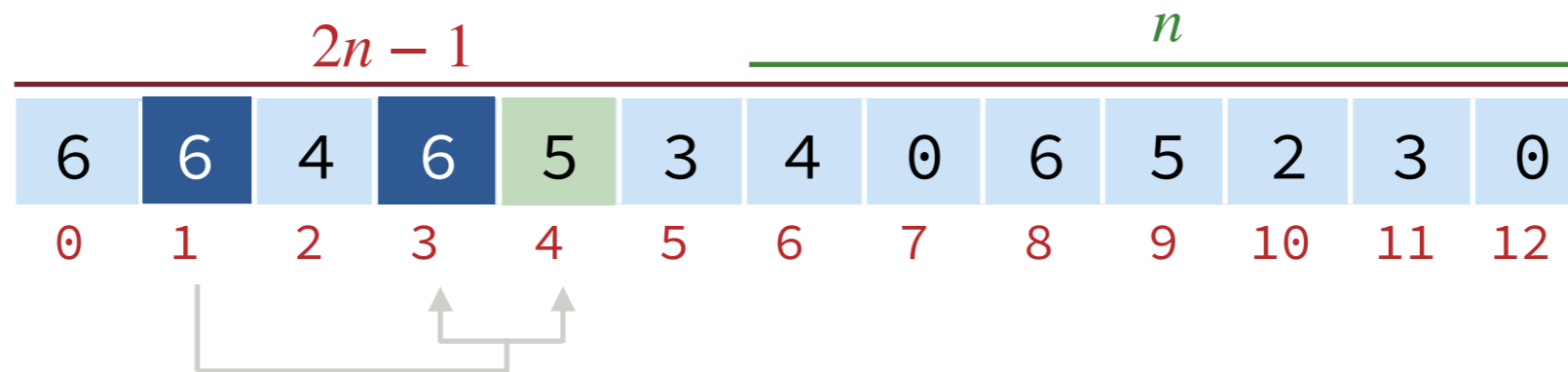
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3. **Trace back** from the root and compare to elements that lost to the max.



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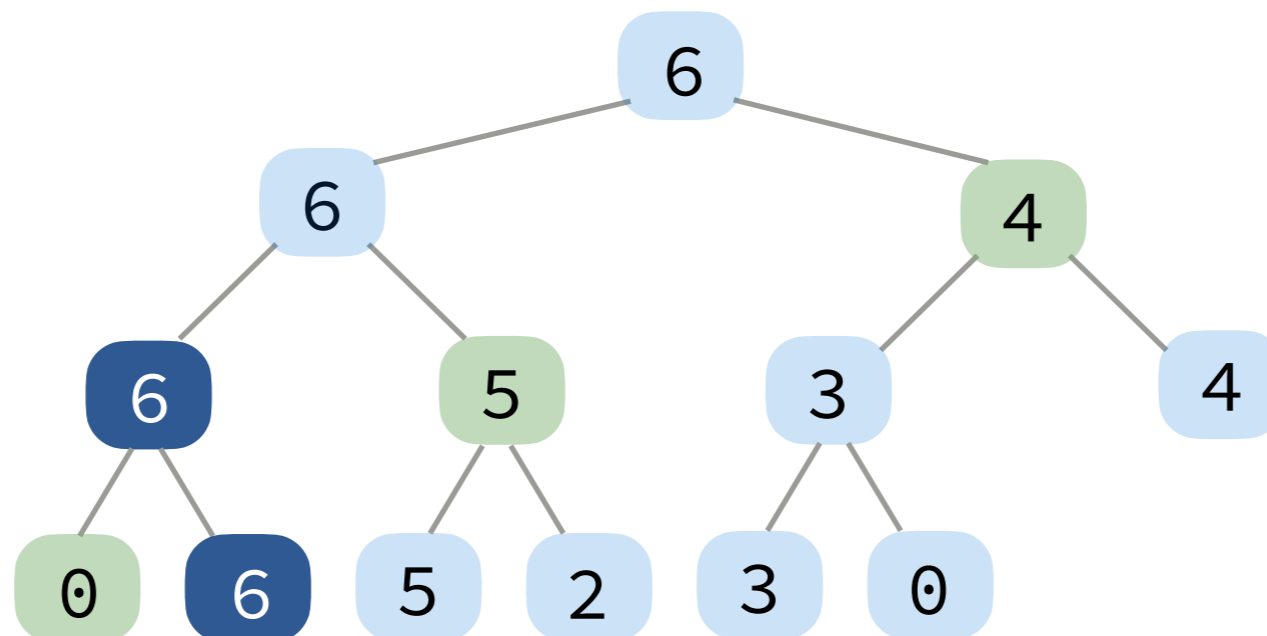
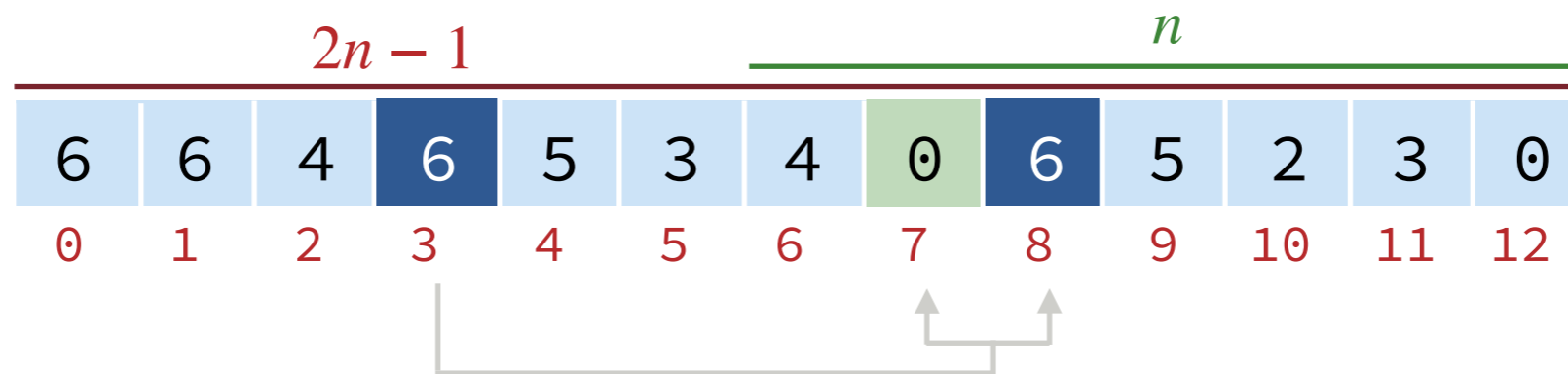
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Implementation

BUILD-HEAP($a[]$, n)

Create an array named $h[]$ of size $2n-1$

Copy $a[0 \rightarrow n-1]$ to $h[n-1 \rightarrow 2n-2]$

Implementation

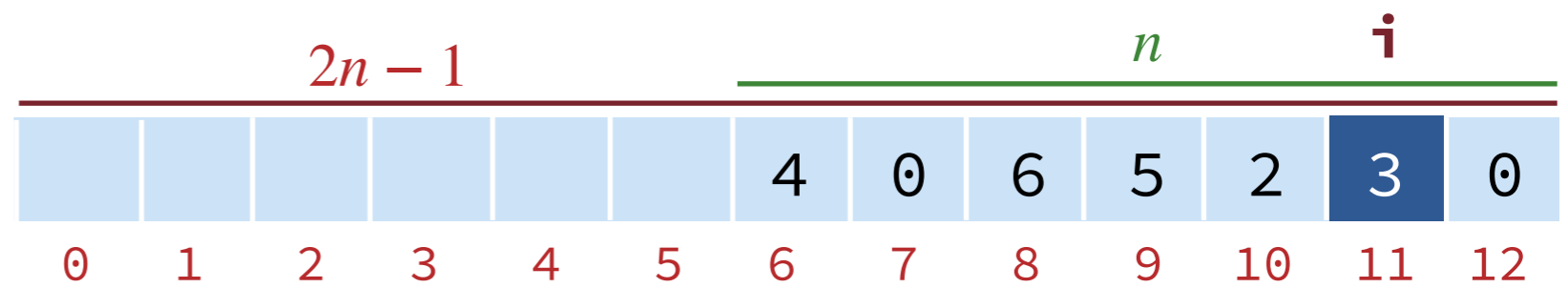
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$i = 2n-3$

↑
start at the 2nd to last
element in the array



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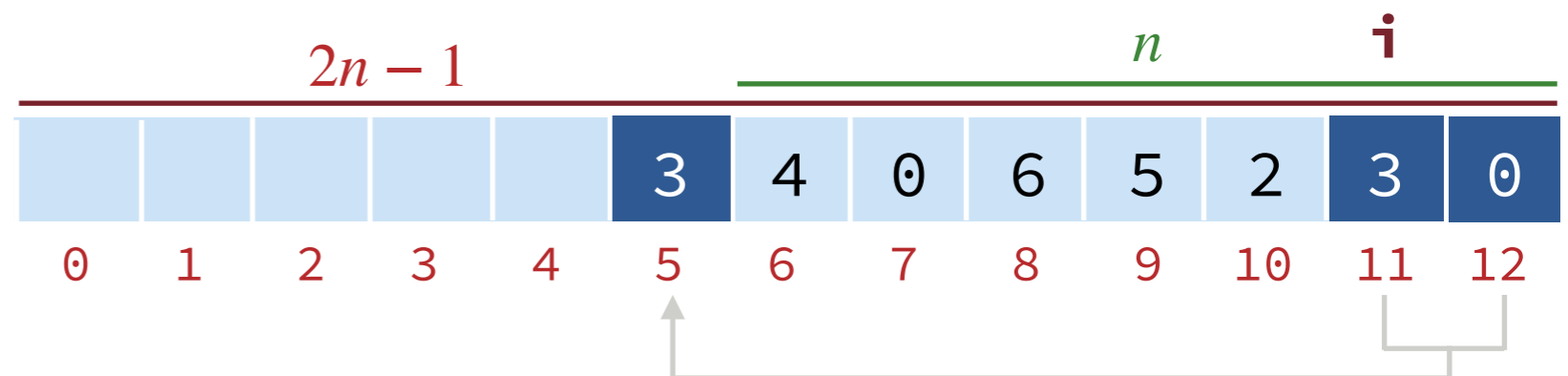
$i = 2n-3$

while ($i > 0$):

$h[\text{PARENT}(i)] = \max(h[i], h[i+1])$

store the max at
the index of the
parent node
 $(i-1)/2$

compare every
pair of nodes



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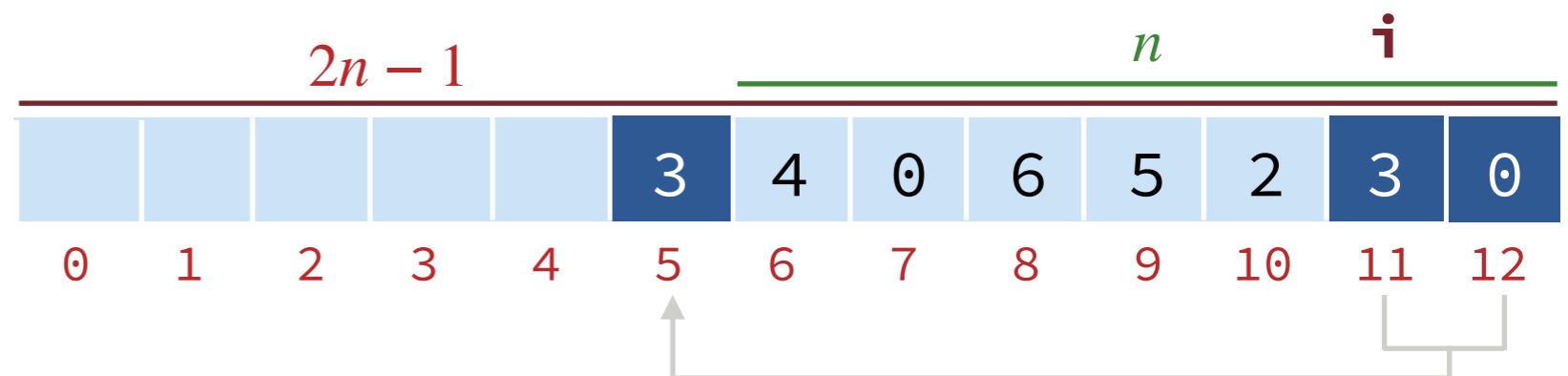
$i = 2n-3$

while ($i > 0$):

$h[\text{PARENT}(i)] = \max(h[i], h[i+1])$

$i = i-2$

↑
move to the
next pair



Implementation

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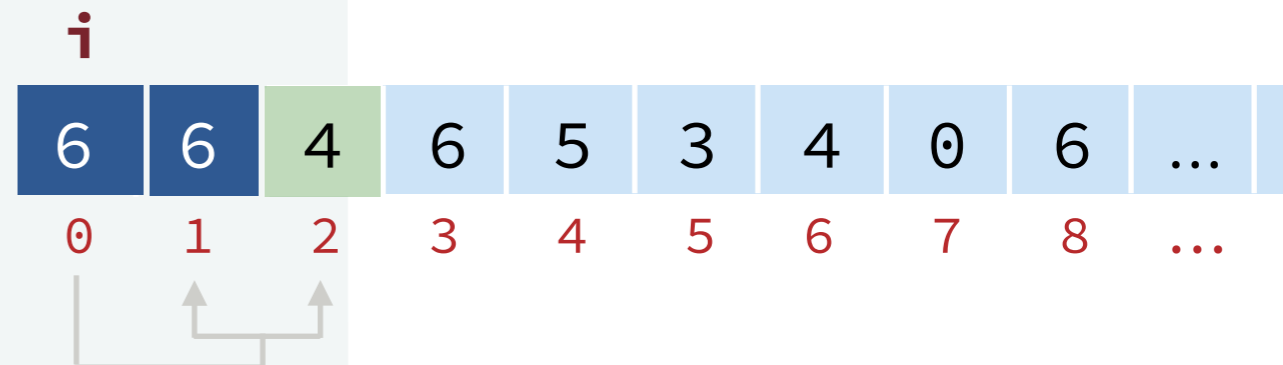
$i = i-2$

HEAP-FIND-MAX($h[]$, n)

$\text{max2} =$ a very small number, $i=0$

while $i < n - 1$:

elements after this
are leaves



Implementation

BUILD-HEAP($a[]$, n)

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Copy $a[0 \rightarrow n-1]$ to $h[n-1 \rightarrow 2n-2]$

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while ($i > 0$):

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while $i < n - 1$:

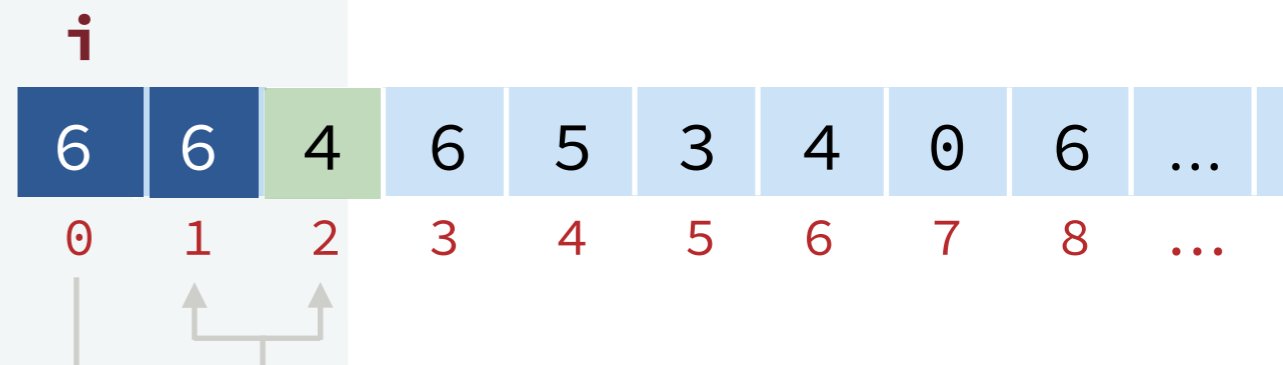
```
if ( $h[i] == h[\text{LEFT}(i)]$ ):  
     $\text{max2} = \text{MAX}(\text{max2}, h[\text{RIGHT}(i)])$   
     $i = \text{LEFT}(i)$ 
```

Remember:

$\text{LEFT}(i): 2*i + 1$

$\text{RIGHT}(i): 2*i + 2$

if the max is in the left child,
compare the current 2nd largest to the
right child and then move to the left child



Implementation

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Create an array named $h[]$ of size $2n-1$

Copy $a[0 \rightarrow n-1]$ to $h[n-1 \rightarrow 2n-2]$

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$i = i-2$

HEAP-FIND-MAX($h[]$, n)

$\text{max2} =$ a very small number, $i=0$

while $i < n - 1$:

if ($h[i] == h[\text{LEFT}(i)]$):

$\text{max2} = \text{MAX}(\text{max2}, h[\text{RIGHT}(i)])$

$i = \text{LEFT}(i)$

else:

$\text{max2} = \text{MAX}(\text{max2}, h[\text{LEFT}(i)])$

$i = \text{RIGHT}(i)$

← otherwise, compare the current 2nd largest to the left child and then move to the right child

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while ($i > 0$):

$h[\text{PARENT}(i)] = \max(h[i], h[i+1])$

$i = i-2$

HEAP-FIND-MAX($h[]$, n)

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if ($h[i] == h[\text{LEFT}(i)]$):

$\text{max2} = \text{MAX}(\text{max2}, h[\text{RIGHT}(i)])$

$i = \text{LEFT}(i)$

else:

$\text{max2} = \text{MAX}(\text{max2}, h[\text{LEFT}(i)])$

$i = \text{RIGHT}(i)$

return max2

optional

Streaming Median

Assume that you receive an arbitrary **stream of numbers**. How can we efficiently report the **median** at any point in time?

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Solution 1. Maintain a **max-heap**:

insert(): $O(\log n)$

median(): $O(n \log n)$

Remove from the heap the first $\frac{n}{2}$ elements to reach the median and then insert them back.

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Solution 2. Maintain an **unordered array**:

insert(): $\Theta(1)$

Add to the end of the list. Note that the array might resize, so the running time is amortized.

median(): $\Theta(n)$

Use `Quickselect` to find the median. Note that this is the expected case if the array is shuffled.

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median(): $\Theta(n)$

Use Quickselect to find the median. Note that this is the expected case if the array is shuffled.

Solution 3. Maintain a **sorted array**:

insert(): $O(n)$

Search for the right position and then shift any elements that come after.

median(): $\Theta(1)$

The median is always at index $\frac{n}{2}$.

Streaming Median

Solution 4. Use a **max-heap** to store the **lower** half of the elements (\leq median) and a **min-heap** to store the **upper** half of the elements ($>$ median).

Assume that the max-heap is named **left** and the min-heap is named **right**. Ensure that:

- Any element in **left** is smaller than or equal to all the elements in **right**.

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- **left.size() - right.size()** is 0 (equal) or 1 (**left** is larger by 1).

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Therefore, **left** always has $\lceil \frac{n}{2} \rceil$ elements and the **median** is always the **maximum** element in **left**.

Example:

	left		right	
	[1	2	3	• 4 5 6]
			↑	
			median	

Example:

	left		right		
	[1	2	3	4	• 5 6 7]
				↑	
				median	

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Example: [1 2 **3** • 4 5 6]

Example: [1 2 3 **4** • 5 6 7]

General Idea:

- **Insert** the new element into the left heap if it is less than or equal to the current median and to the right if it is greater than the current median.
- **Rebalance** the heaps by moving an element from the larger heap to the smaller heap if the size invariant is violated.

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Example: [1 2 **3** • 4 5 6]

Example: [1 2 3 **4** • 5 6 7]

insert(k):

If $k \leq \mathbf{left.max()}: \mathbf{left.insert(k)}$

Else: $\mathbf{right.insert(k)}$

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If $k \leq$ **left.max()**: **left.insert(k)**

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↑
median

← insert k in **left** if $k \leq$ median

← insert k in **right** if $k >$ median

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insert(k):

If $k \leq \mathbf{left.max()}: \mathbf{left.insert(k)}$

Else: $\mathbf{right.insert(k)}$

If $\mathbf{left.size() > right.size()+1}: \mathbf{right.insert(left.delMax())}$.


more than $\lceil \frac{n}{2} \rceil$ elements are in **left**

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remove the max from left
and insert it into right



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If $\mathbf{right.size()} > \mathbf{left.size()}: \mathbf{left.insert(right.delMin())}$.

If **right** is larger than **left**

remove the min from **right** and insert it into **left**.

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Example: [1 2 **3** • 4 5 6]

Example: [1 2 3 **4** • 5 6 7]

insert(k):

**insert into
the correct heap**

If $k \leq \mathbf{left.max()}: \mathbf{left.insert(k)}$

Else: $\mathbf{right.insert(k)}$

**rebalance the
heaps if necessary**

If $\mathbf{left.size()} > \mathbf{right.size()+1}: \mathbf{right.insert(left.delMax())}$.

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$O(\log n)$

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$O(\log n)$

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Running Time:

insert(): $O(\log n)$

Inserting into the left or the right heaps is $O(\log n)$ and rebalancing is $O(\log n)$.

median(): $\Theta(1)$

The median is always `left.max()`.