

CS11212 - Spring 2022

Data Structures & Introduction to Algorithms

Data Structures

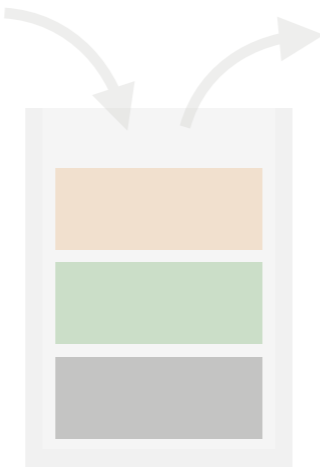
Priority Queues

Ibrahim Albluwi

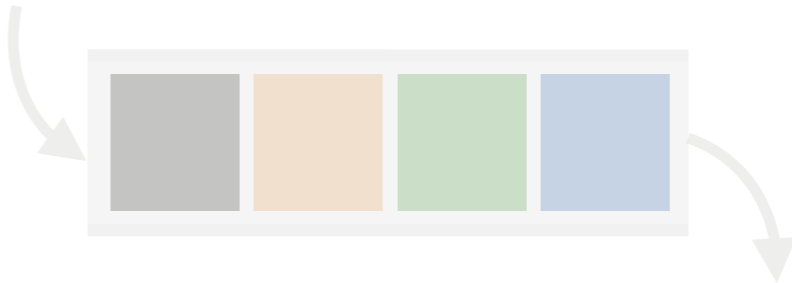
ADTs We Know So Far



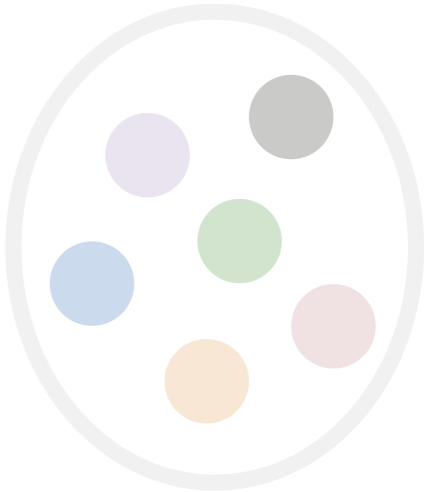
List



Stack



Queue



Set

operations

```
add_to_head(val)
add_to_tail(val)
remove_head()
remove_tail()
remove(val)
contains(val)
```

```
push(val)
pop()
top()
```

```
enqueue(val)
dequeue()
first()
last()
```

```
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remove(val)
contains(val)
```

Linked List
Array

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Linked List
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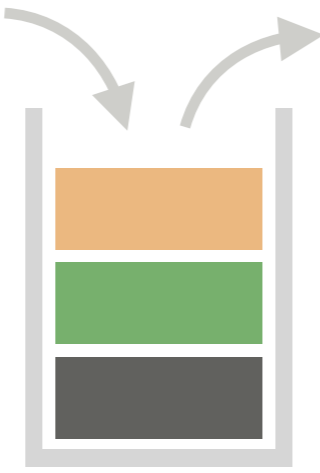
Linked List
Array
BST
Hash Table

common
data structures

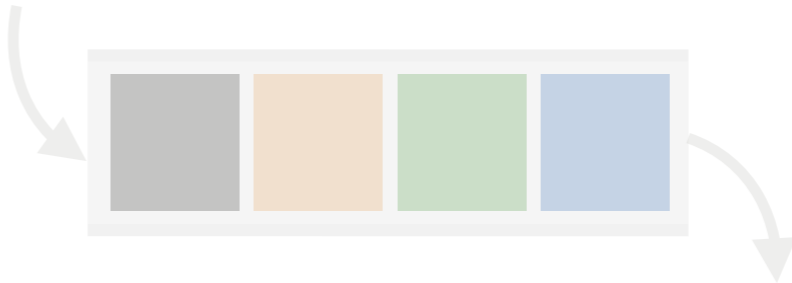
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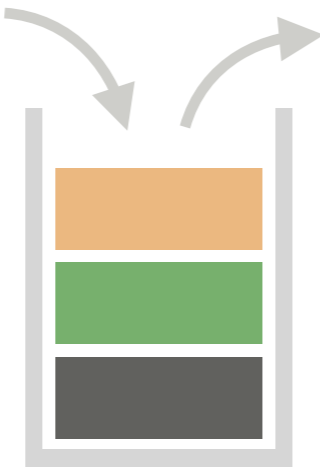
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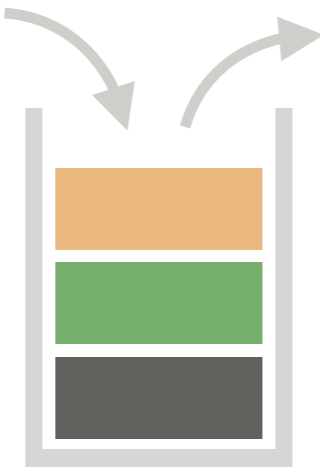
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Linked List
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**common
data structures**

Priority Queue (a new ADT)

Max-Priority Queue

```
T get_max() const  
T remove_max()  
void insert(const T& val)
```

Min-Priority Queue

```
T get_min() const  
T remove_min()  
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Priority Queue (a new ADT)

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```

Applications.

In an **emergency room**, patients are assigned priority based on their condition.



Priority Queue (a new ADT)

Max-Priority Queue

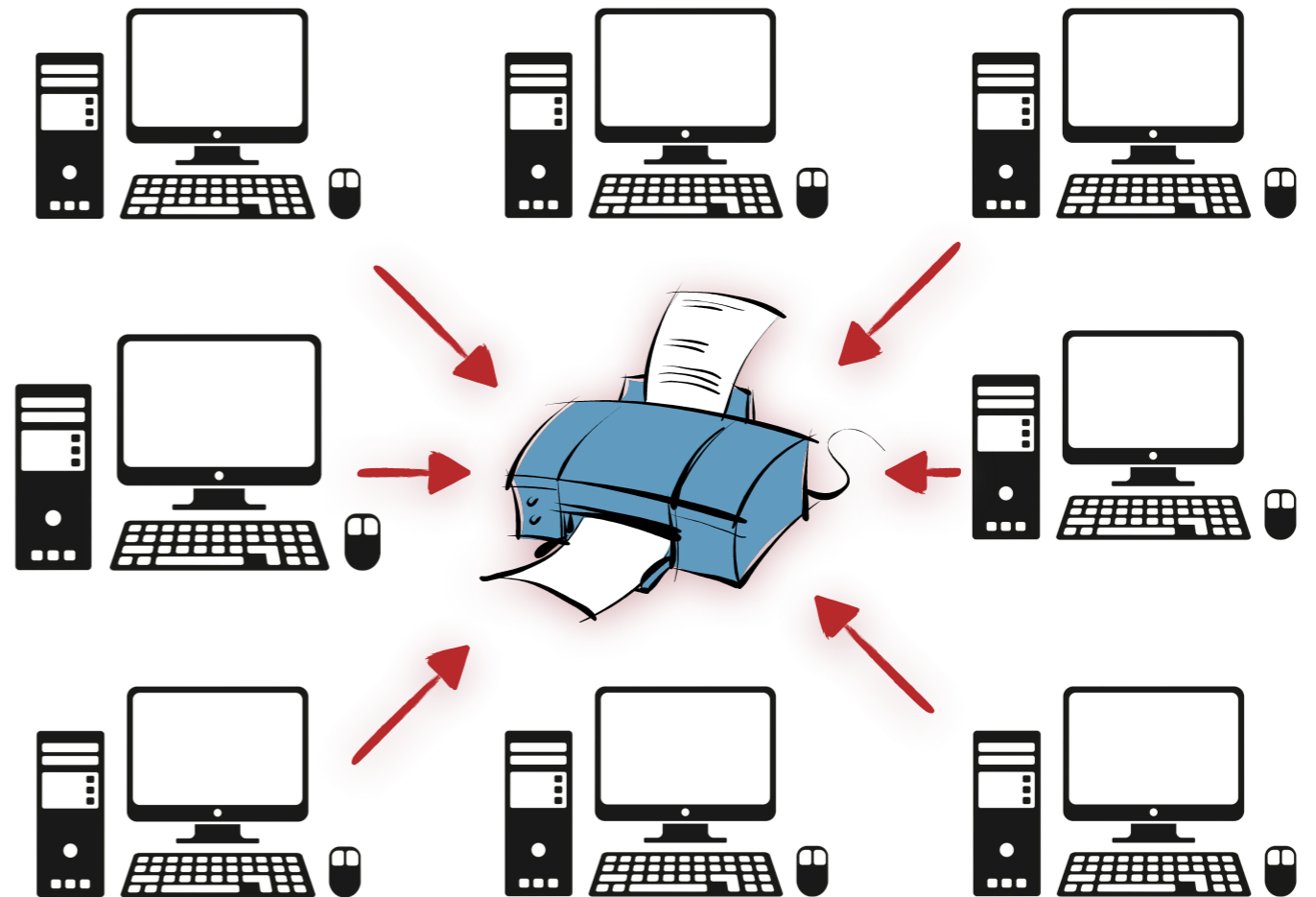
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```

Min-Priority Queue

```
T get_min() const  
T remove_min()  
void insert(const T& val)
```

Applications.

In an **printer queue**, can be configured to give higher priority to print jobs from certain people (e.g. based on role or department)



Priority Queue (a new ADT)

Max-Priority Queue

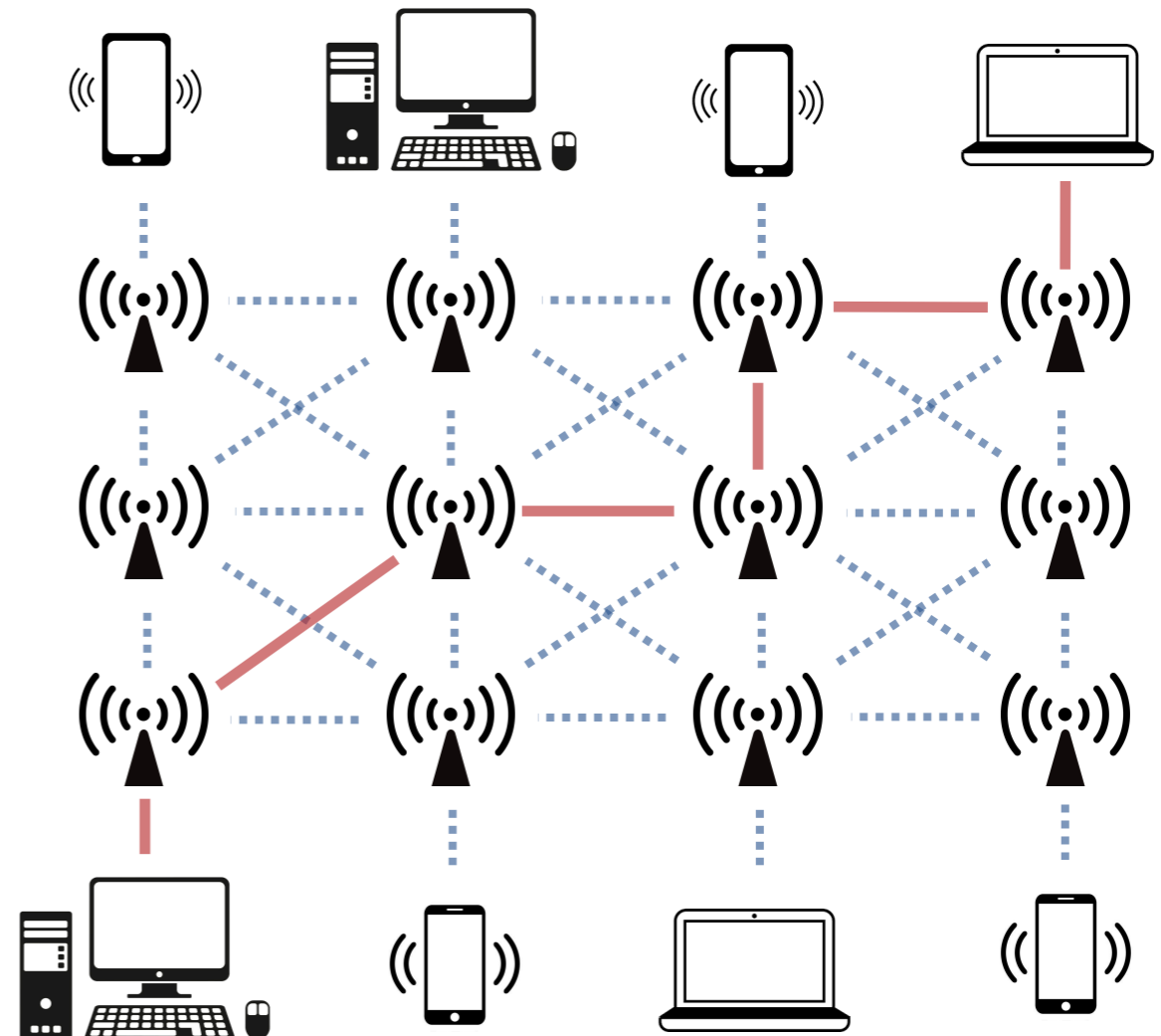
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Min-Priority Queue

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T get_min() const  
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void insert(const T& val)
```

Applications.

A **network router**, can give higher priority to packets based on their type or sender (e.g. live streaming data is very important to be routed quickly)



Priority Queue (a new ADT)

Max-Priority Queue

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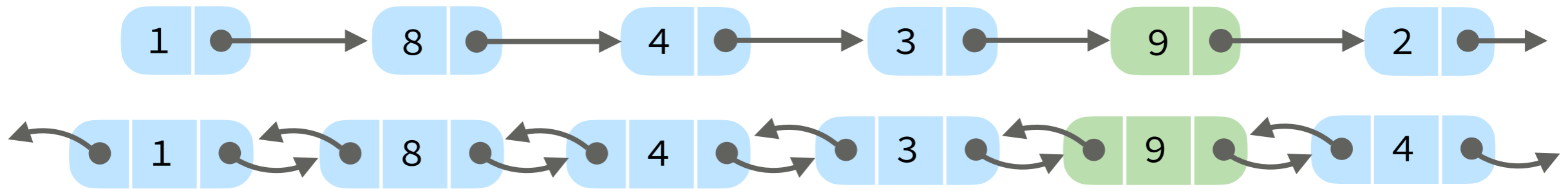
Applications.

Used in many algorithms to process data elements in ascending or descending order or to keep track of the largest (or smallest) k elements seen so far.

- A*
- Dijkstra's Shortest Paths Algorithm
- Prim's Minimum Spanning Trees Algorithm
- Huffman Coding
- Streaming Median
- Interrupt Handling
- etc.

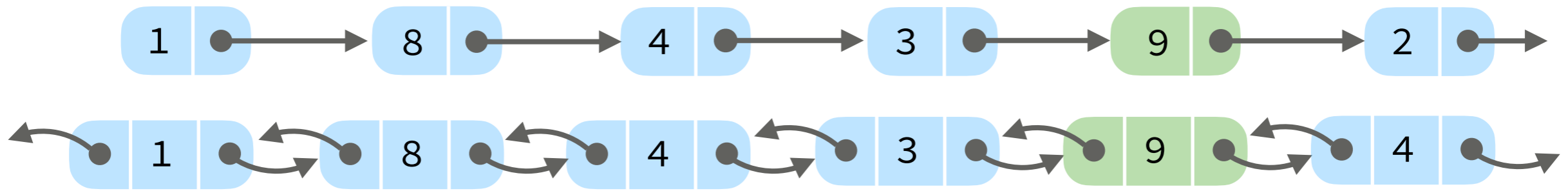
Max-Priority Queue: Possible Implementations

	<code>insert(val)</code>	<code>remove_max()</code>	<code>get_max()</code>
Unordered DLL			
Unordered SLL			



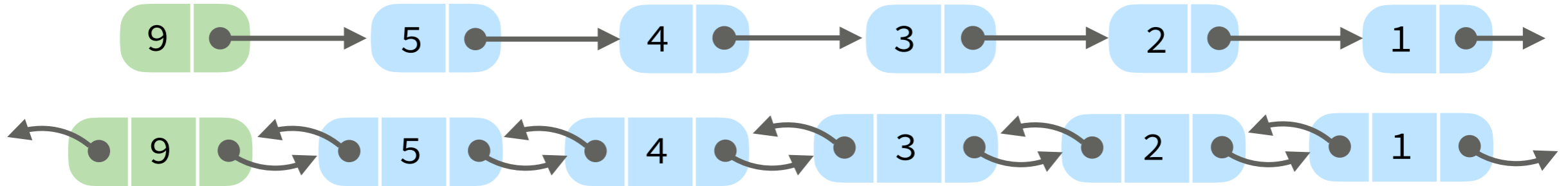
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	<code>insert(val)</code>	<code>remove_max()</code>	<code>get_max()</code>
Unordered DLL	$O(1)$	$O(n)$	$O(n)$
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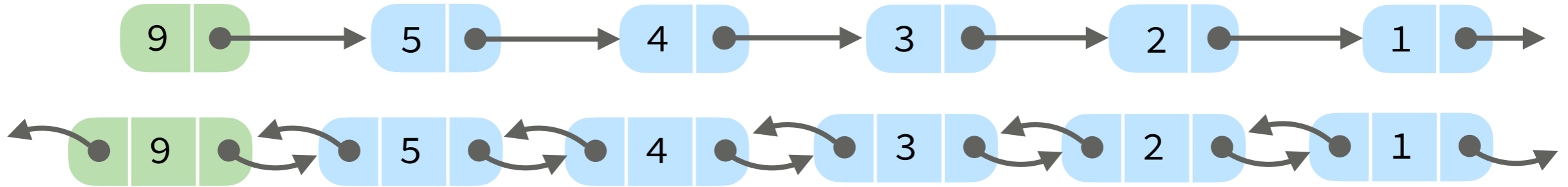
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Ordered DLL Ordered SLL			



Max-Priority Queue: Possible Implementations

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Unordered Array			



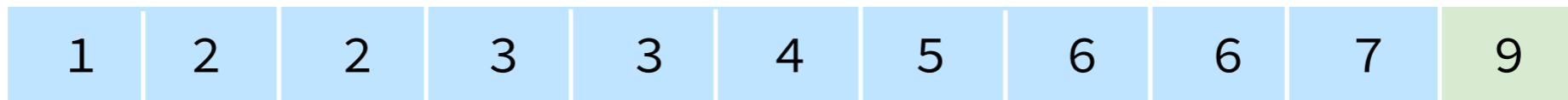
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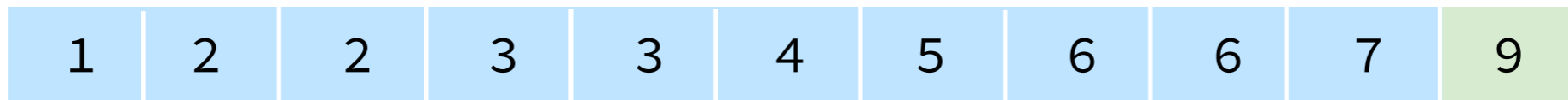
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Ordered Array			



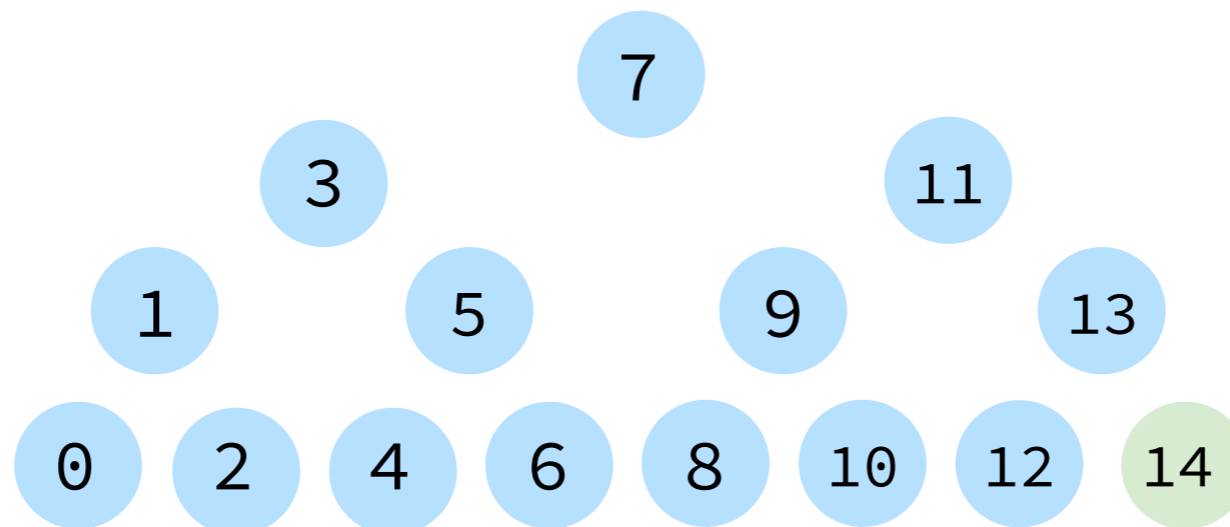
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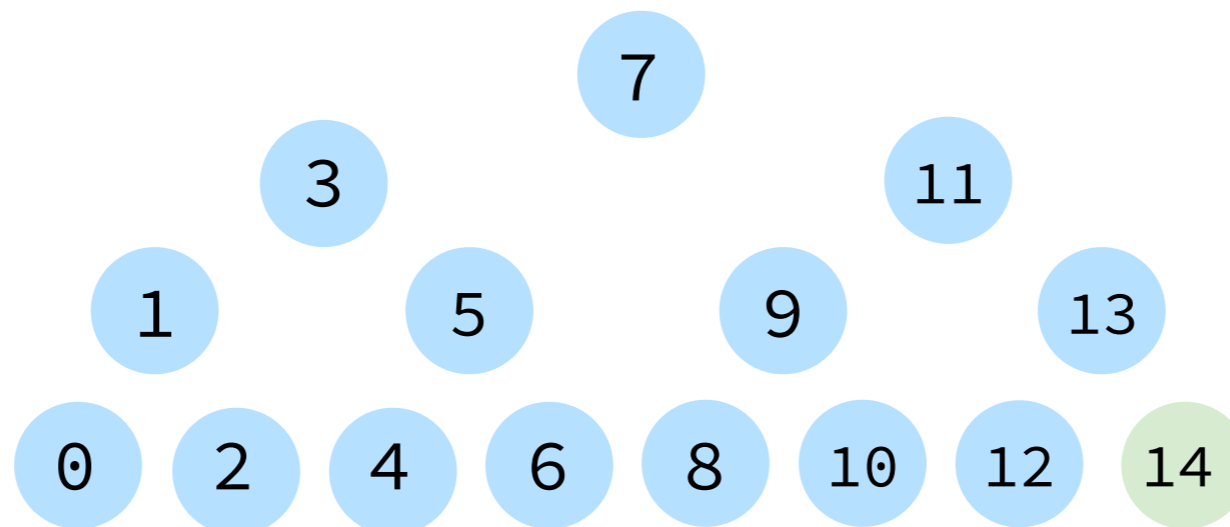
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Balanced BST			



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Can we do better?

Max-Priority Queue: Possible Implementations

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Binary Heap	$O(\log n)$	$O(\log n)$	$O(1)$



Can we do better?

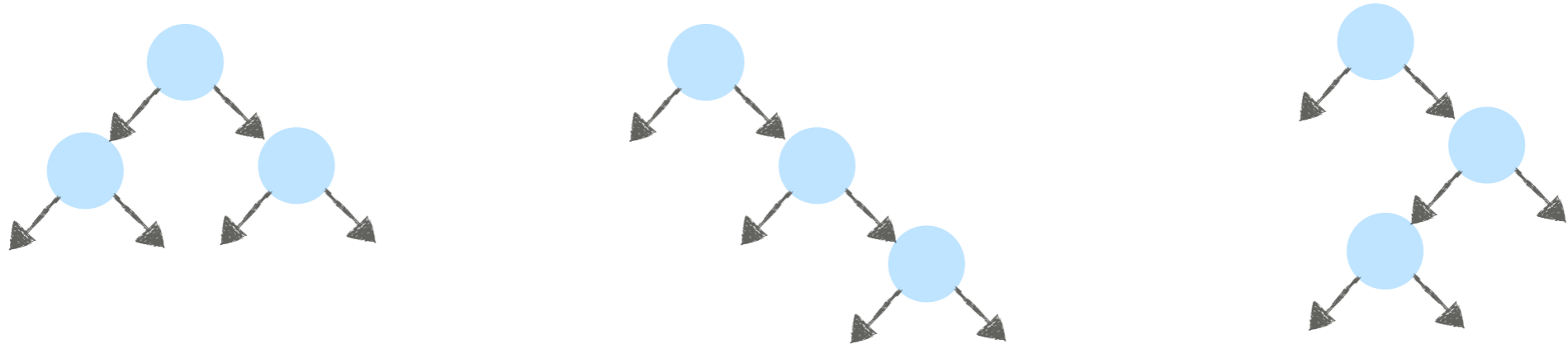


Yes! ... *slightly better*

Using a very simple data structure!

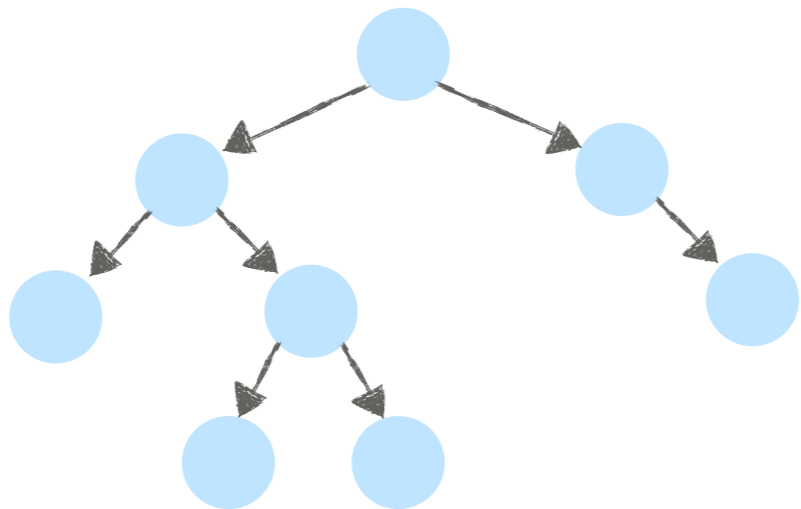
Binary Heaps are Complete Binary Trees

Binary Tree: Every node has *at most* two children.

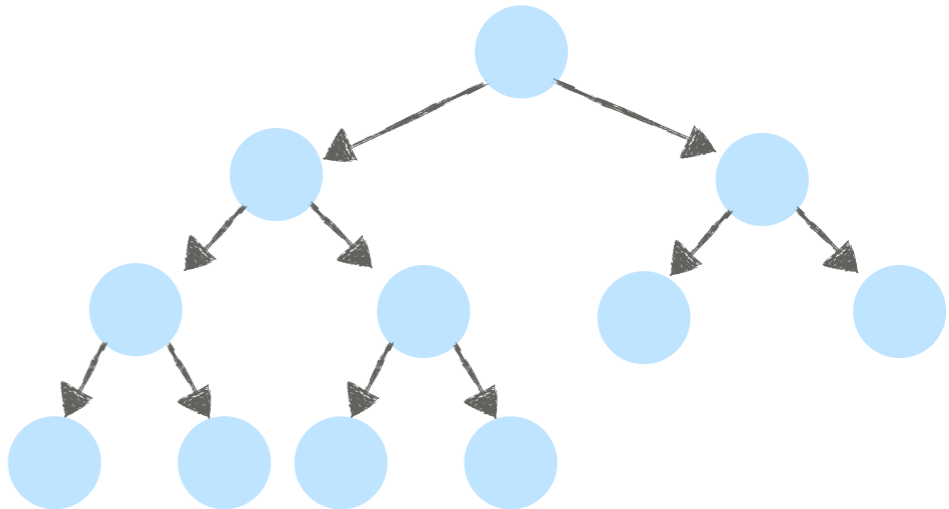


Complete Binary Tree:

- All levels are full (except possibly the last level).
- Last level is filled left-to-right.



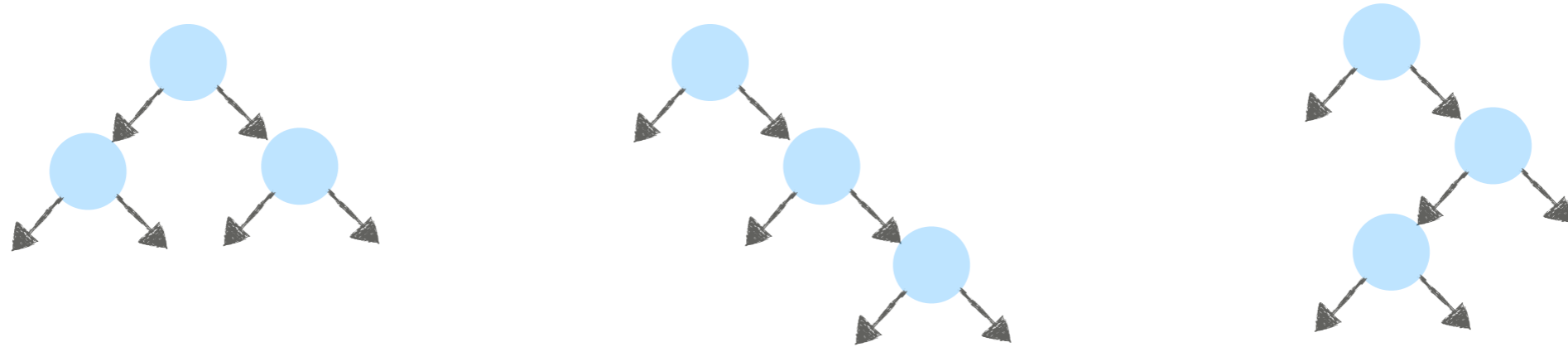
not complete



complete

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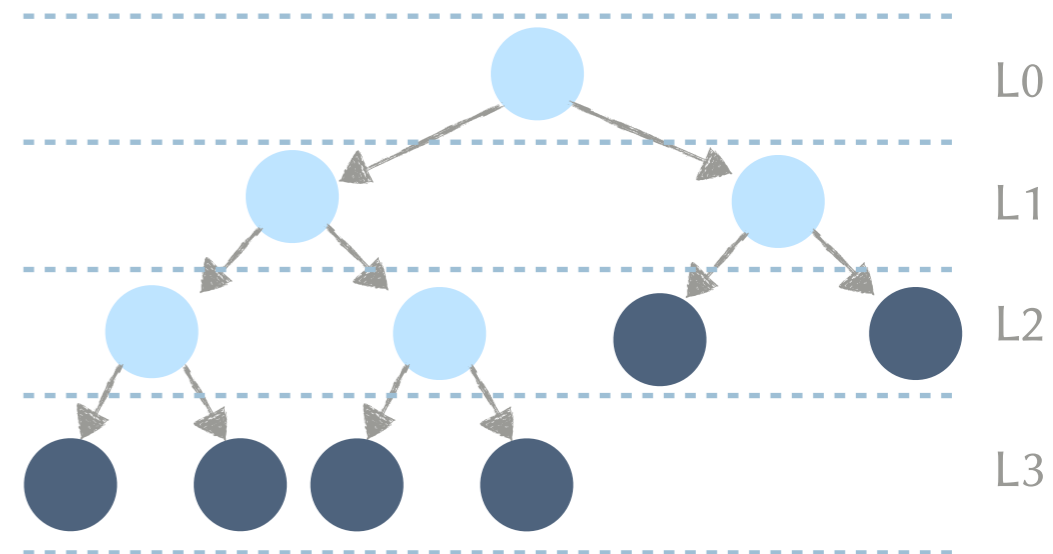


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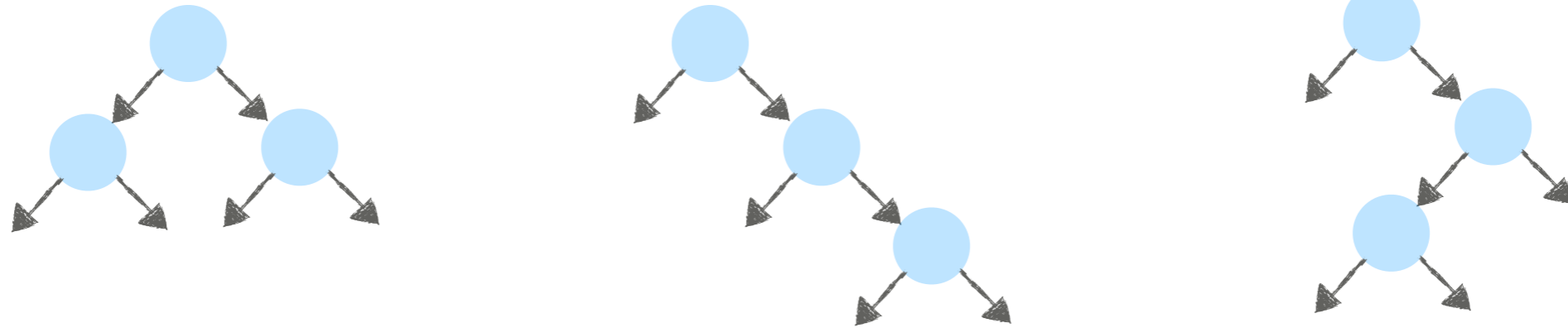
Properties:

- All leaves are at level h or $h - 1$.
(h = tree height)



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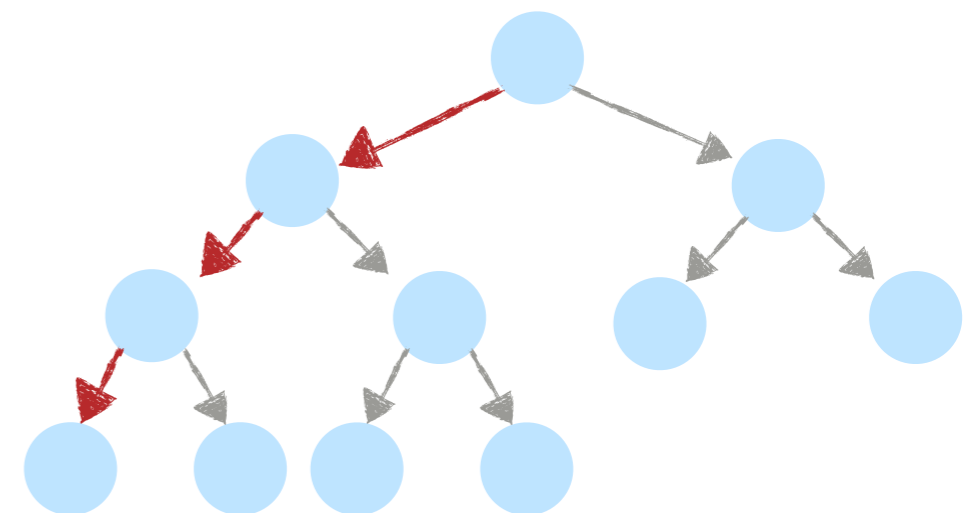


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Properties:

- All leaves are at level h or $h - 1$.
- **Height** if there are n nodes: $h = \lfloor \log_2 n \rfloor$



$$h = \lfloor \log_2 11 \rfloor = \lfloor 3.459 \rfloor = 3$$

Binary Heaps (Tree Representation)

Binary Heap: (max-ordered)

- **Structure:** Must be a complete binary tree.
- **Order:** Every node is not less than its children.

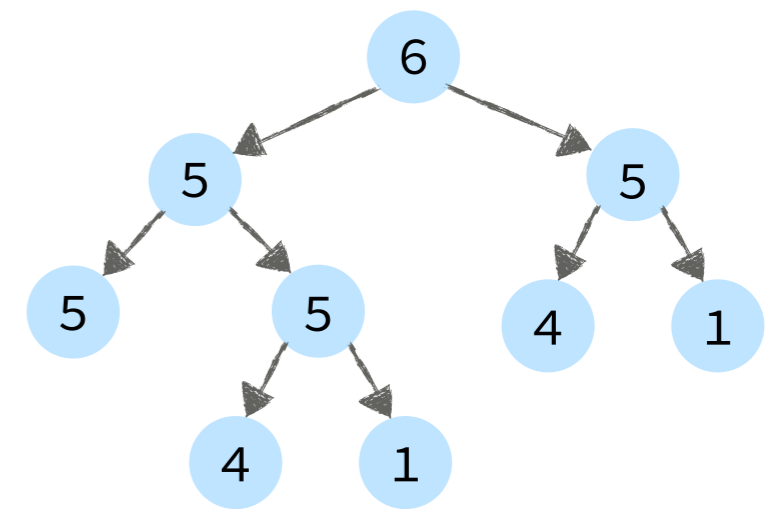
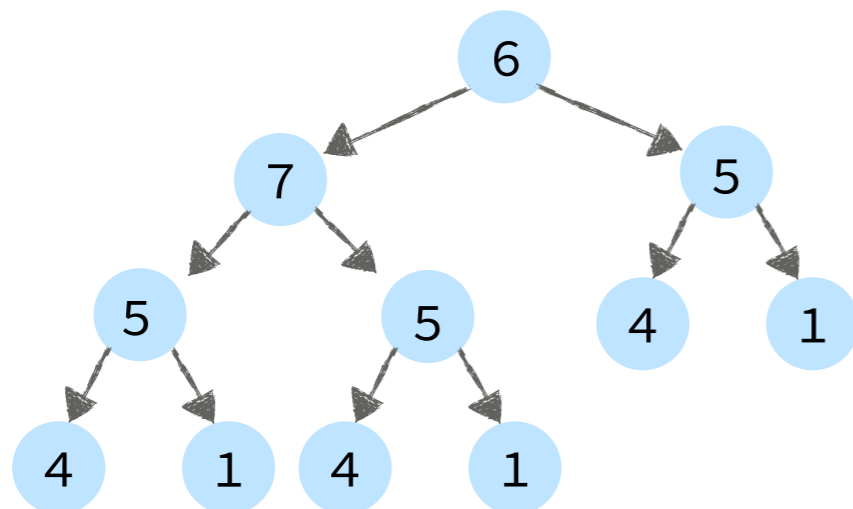
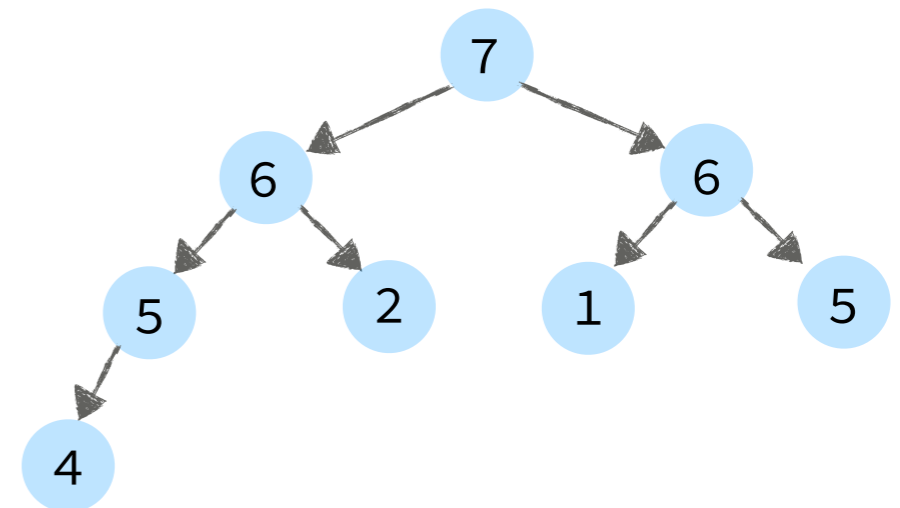
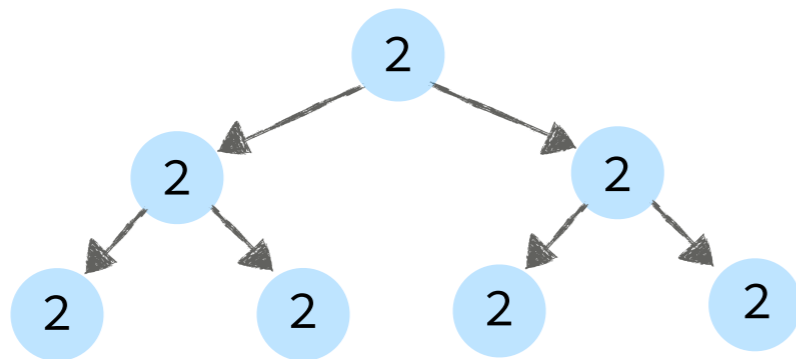
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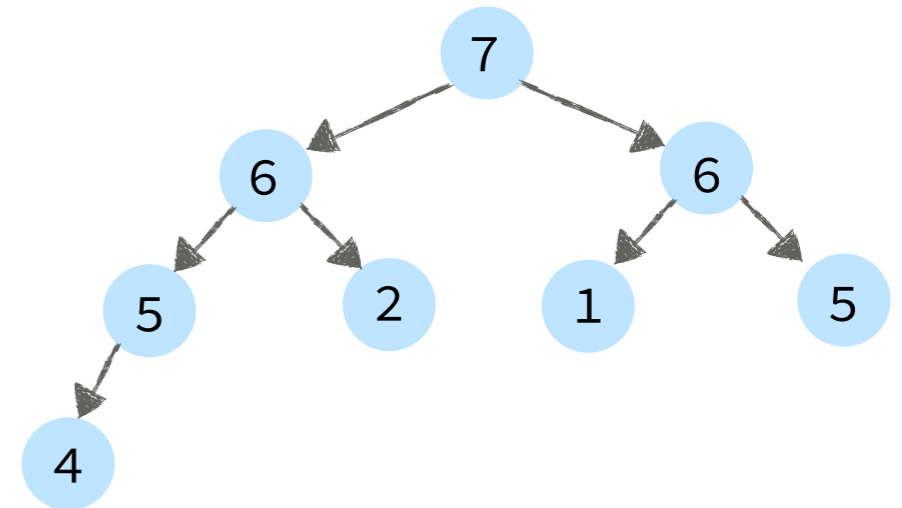
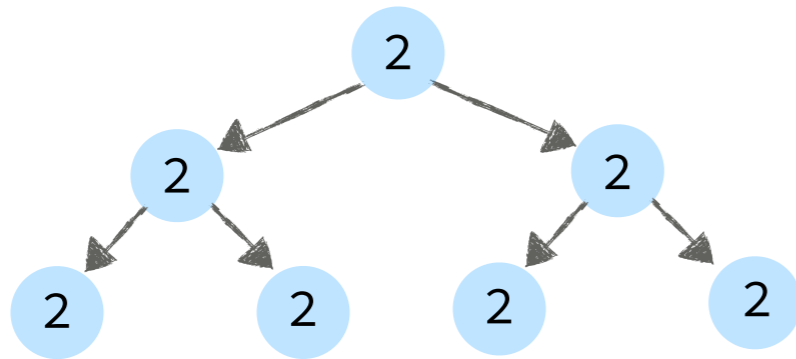
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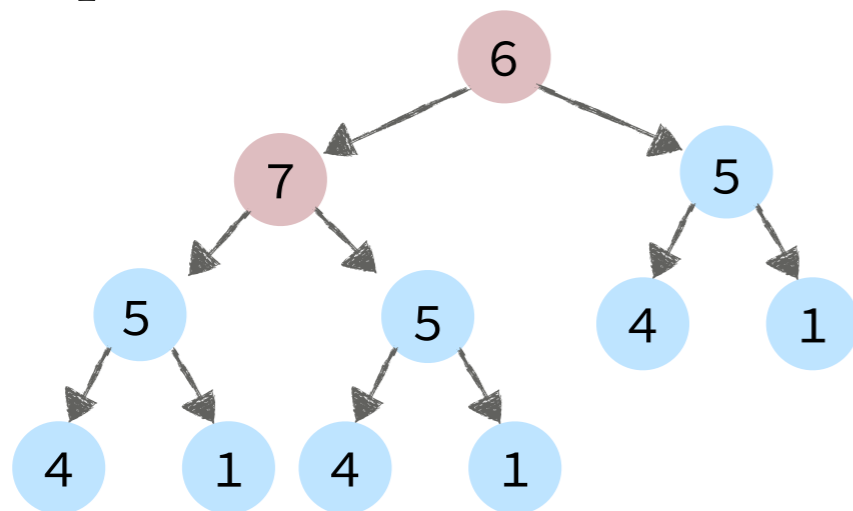


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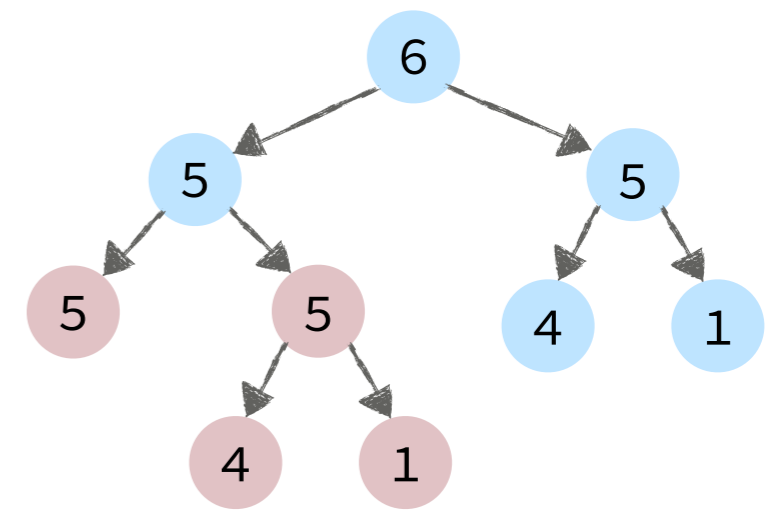
Examples:



Non-Examples:



order property violated



structure property violated

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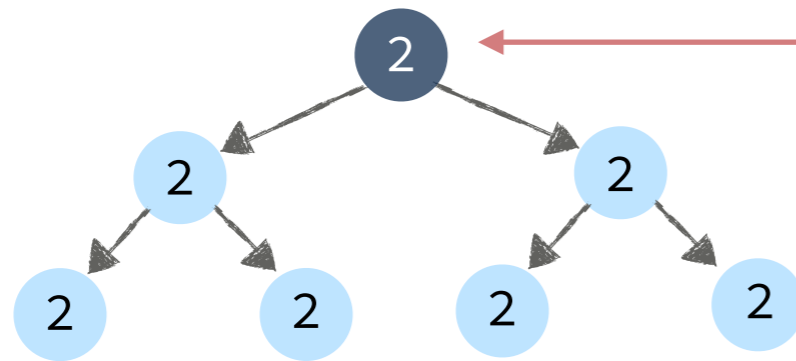
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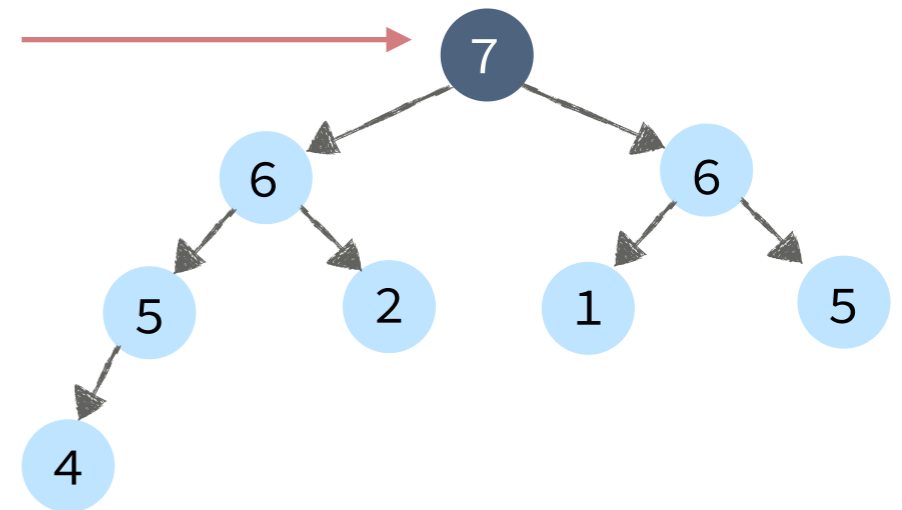


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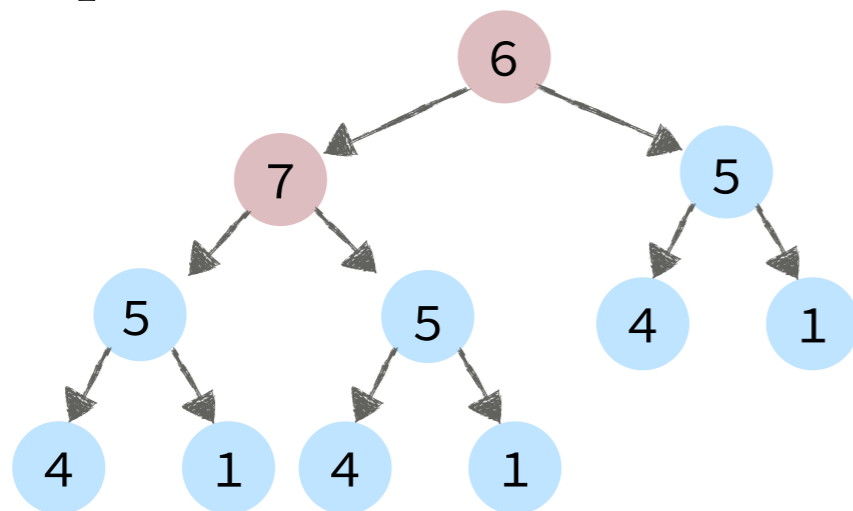
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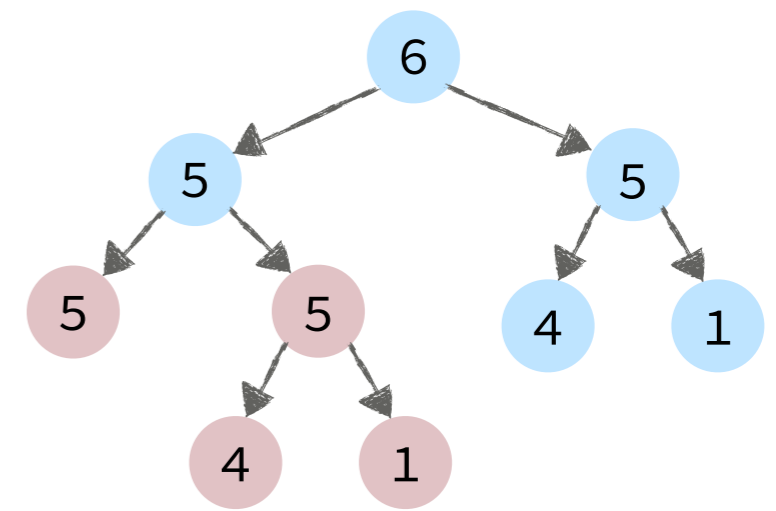
max is always at the root



Non-Examples:



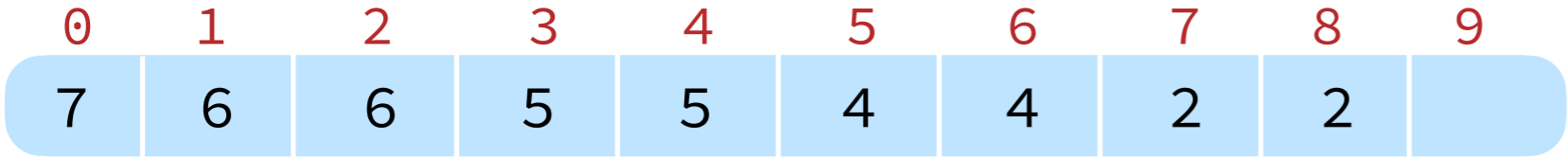
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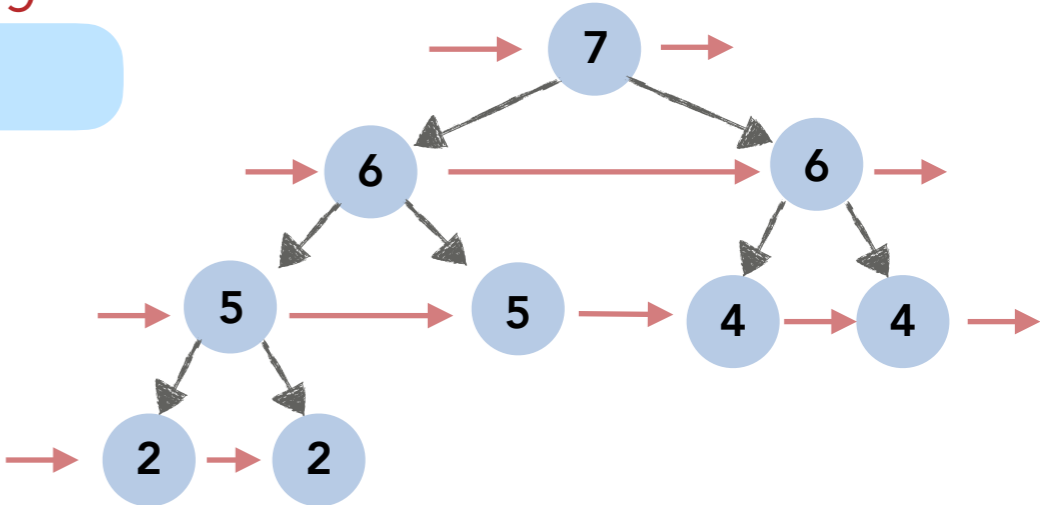
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Binary Heaps (Array Representation)

Binary Heap: (max-ordered)

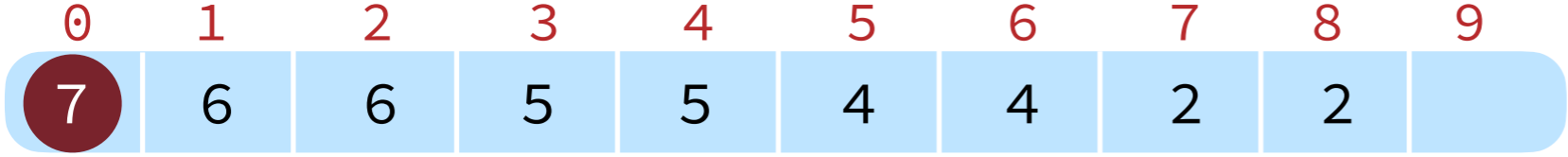


array has the tree nodes in **level-order**



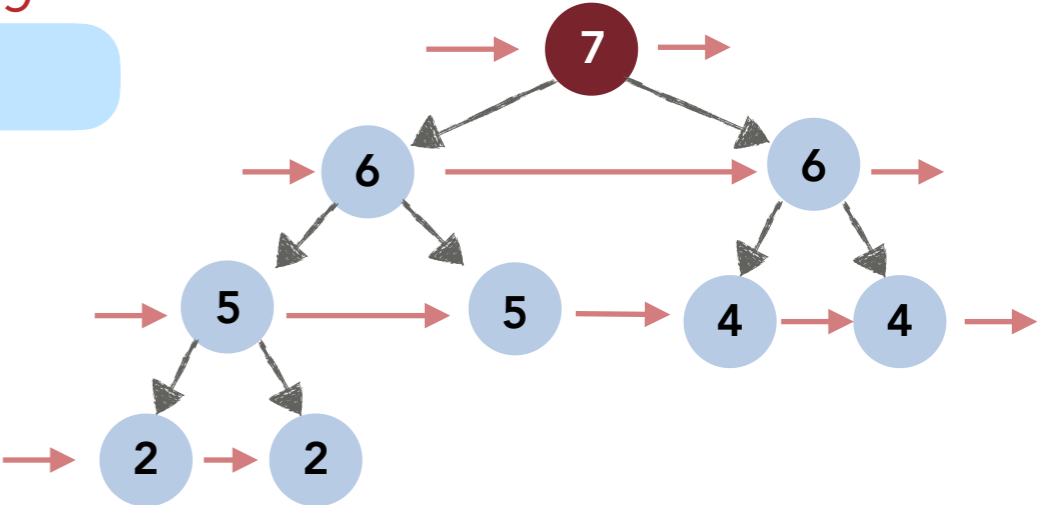
Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



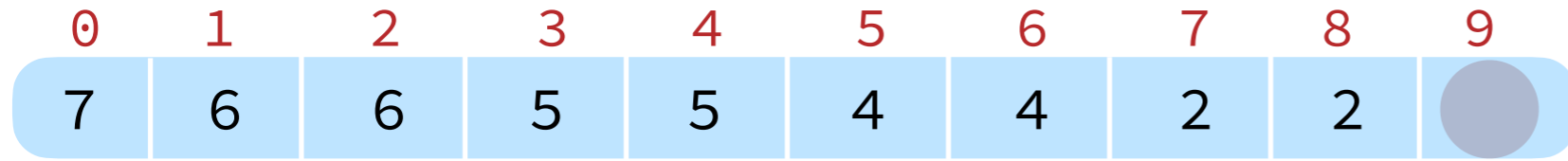
The root is always at index 0

array has the tree nodes in level-order

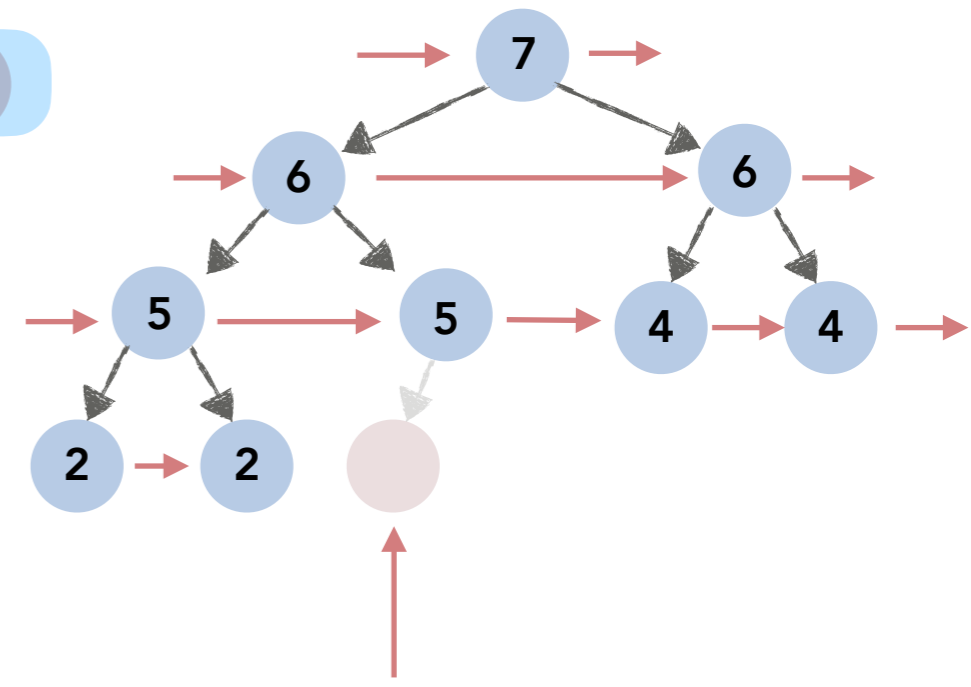


Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



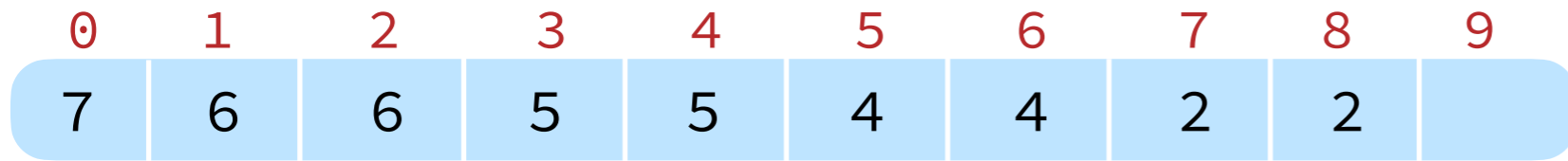
array has the tree nodes in **level-order**



The first empty node in the last level in the tree is the first empty cell in the array

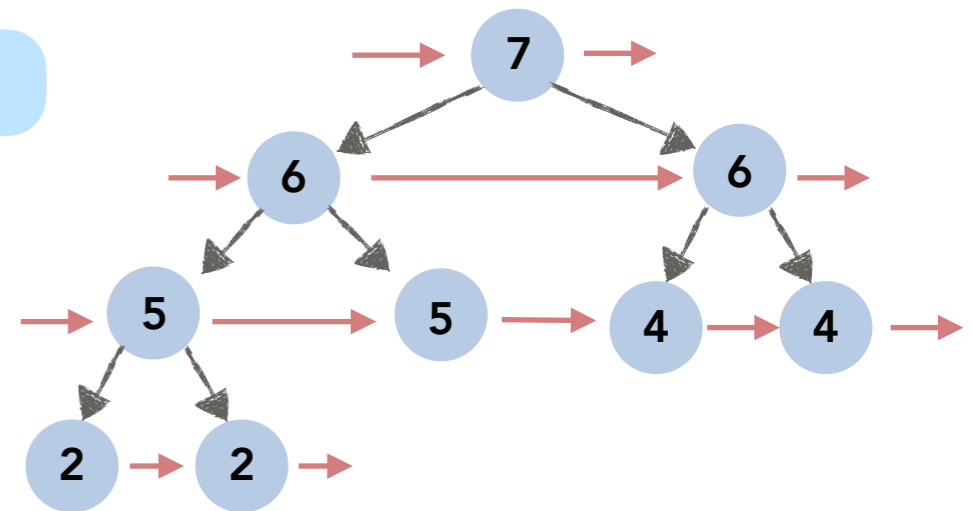
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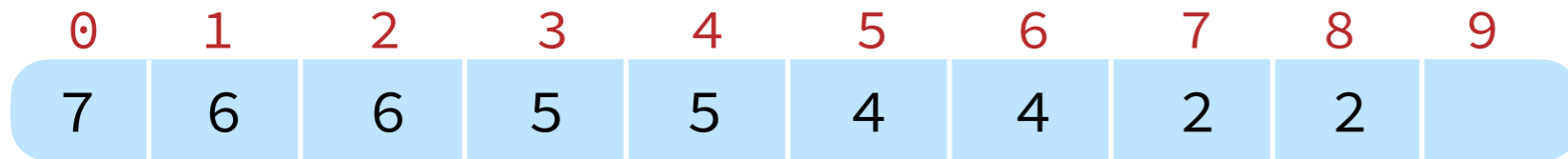
? Given the index i of an element, what are the indices of the **left** and **right** children of that element?

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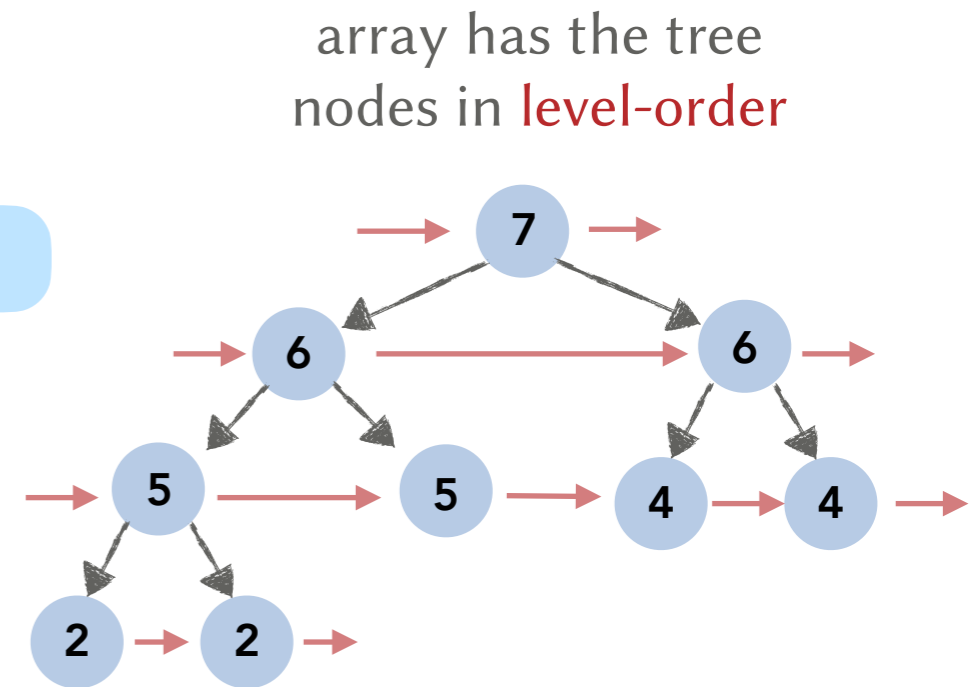


Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



? Given the index i of an element, what are the indices of the **left** and **right** children of that element?



Three simple functions.

```
int LEFT(int i)
```

```
return 2*i + 1;
```

```
int RIGHT(int i)
```

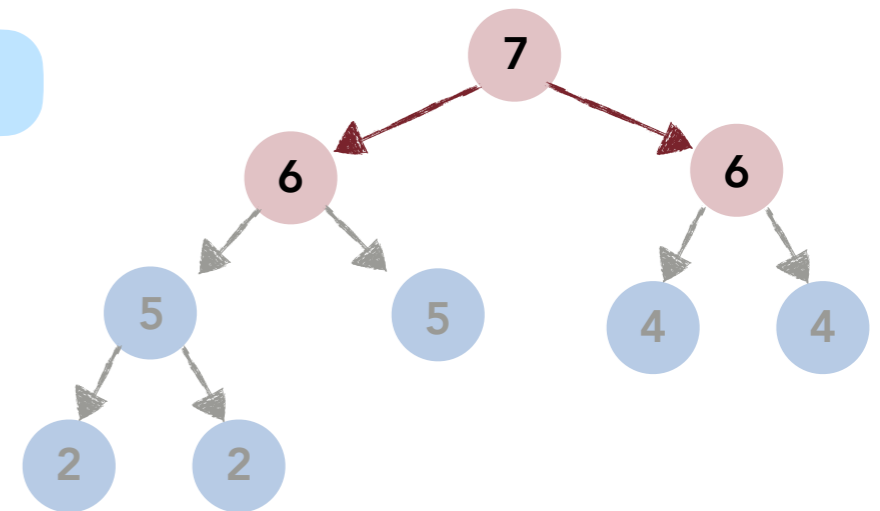
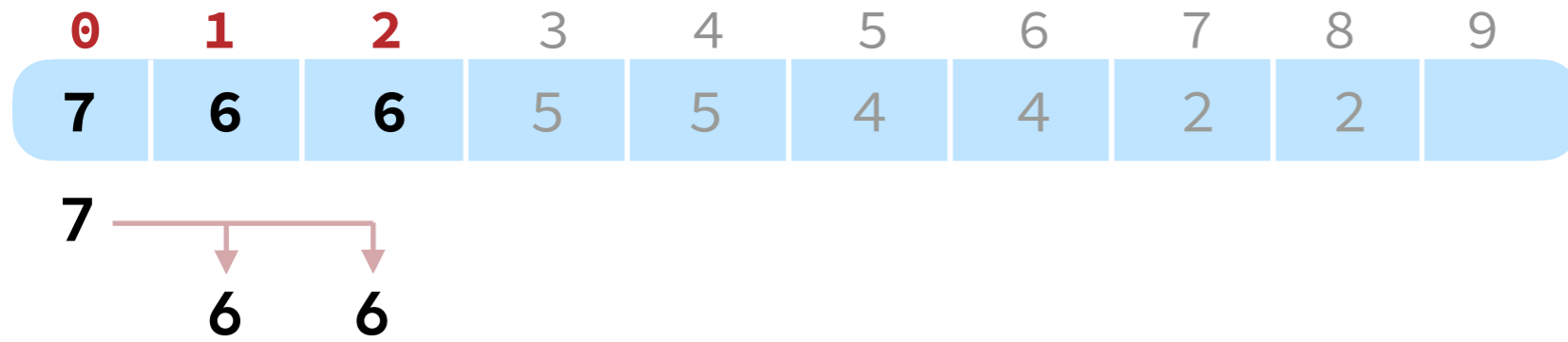
```
return 2*i + 2;
```

```
int PARENT(int i)
```

```
return (i-1) / 2;
```

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

```
int LEFT(int i)  
return 2*i + 1;
```

left child is at index
 $2*0 + 1 = 1$

```
int RIGHT(int i)  
return 2*i + 2;
```

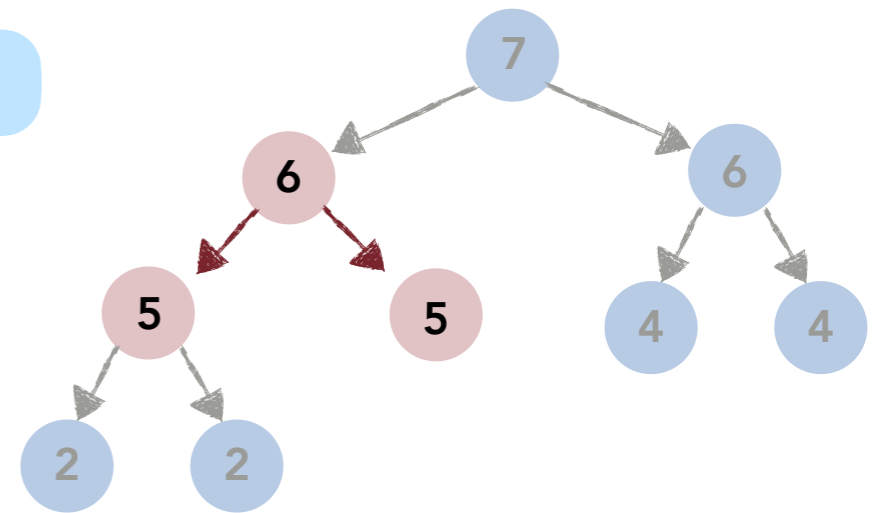
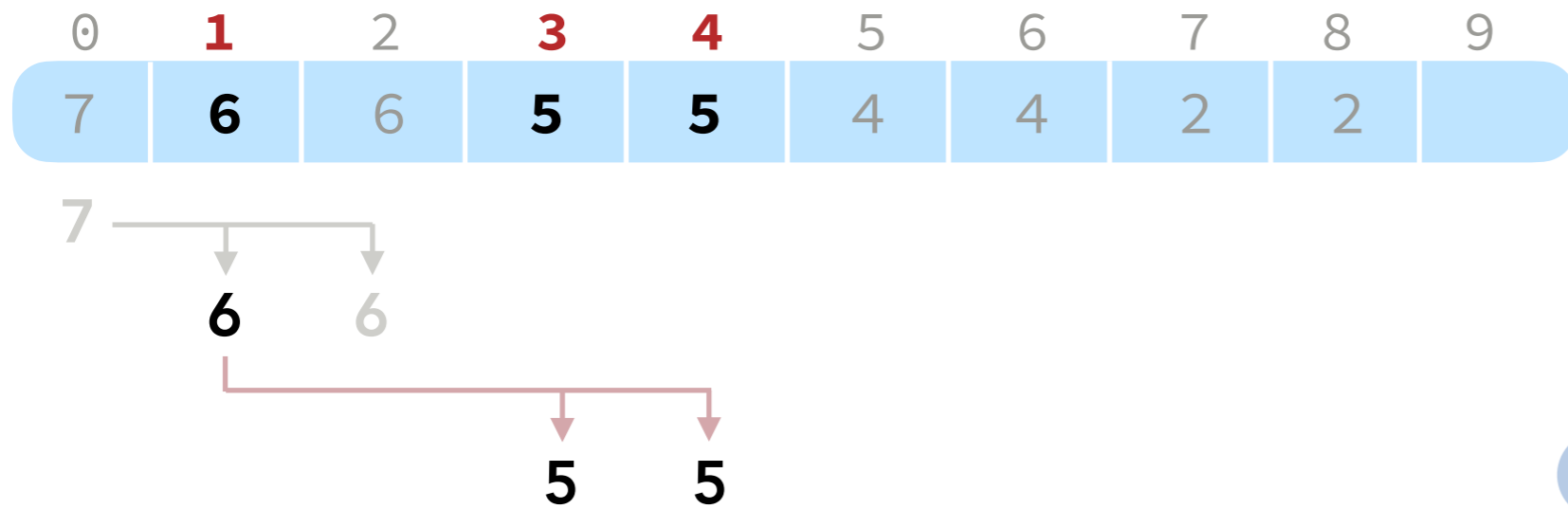
Right child is at index
 $2*0 + 2 = 2$

```
int PARENT(int i)  
return (i-1) / 2;
```

Parent of the node at 0 is 0
I.e. It has no parent

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

```
int LEFT(int i)
```

```
return 2*i + 1;
```

left child is at index
 $2*1 + 1 = 3$

```
int RIGHT(int i)
```

```
return 2*i + 2;
```

Right child is at index
 $2*1 + 2 = 4$

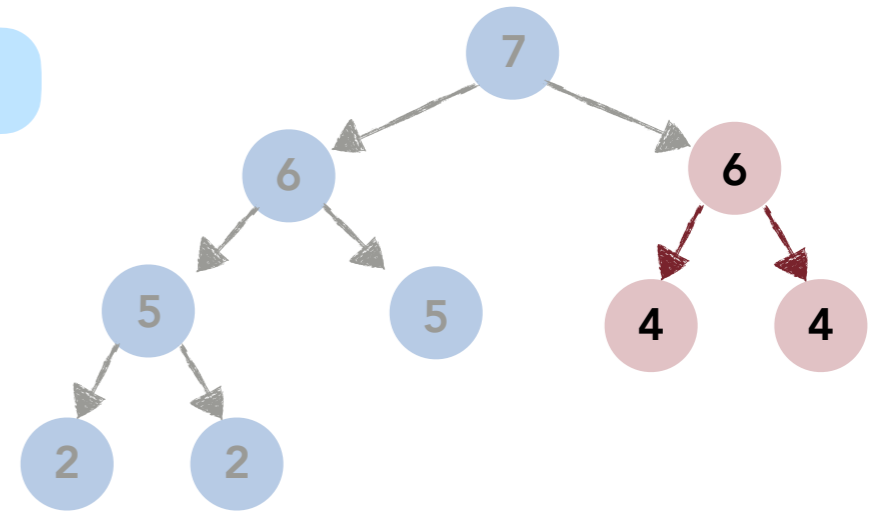
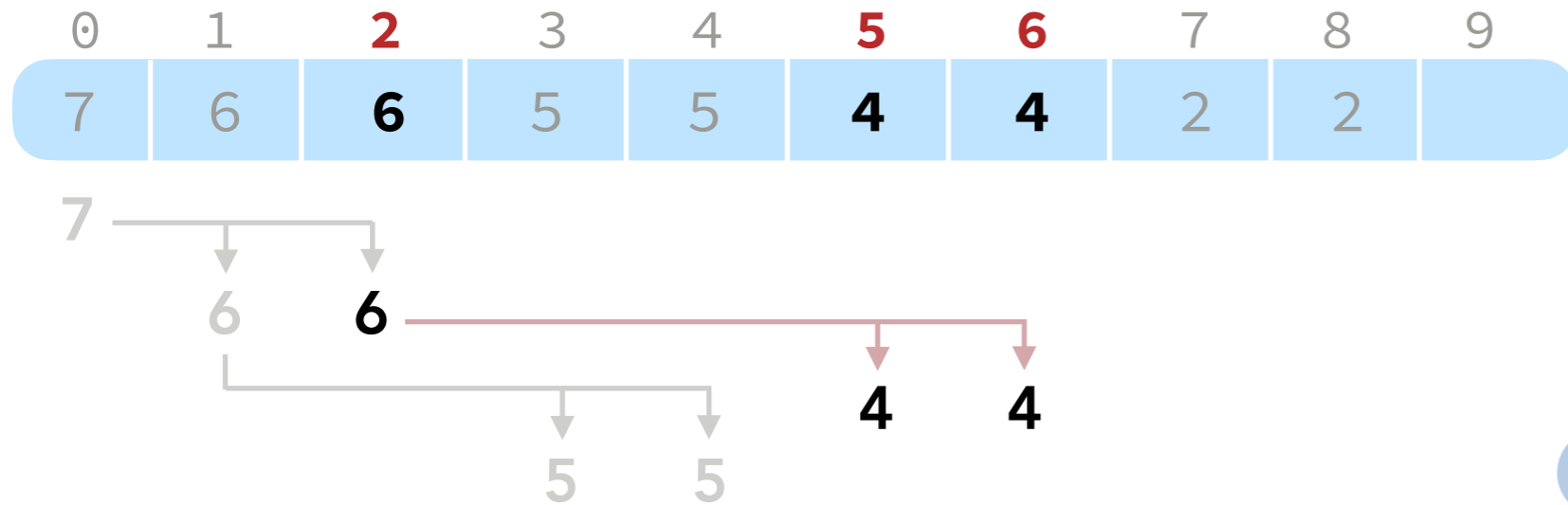
```
int PARENT(int i)
```

```
return (i-1) / 2;
```

Parent is at index
 $(1-1)/2 = 0$

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

```
int LEFT(int i)
```

```
return 2*i + 1;
```

left child is at index
 $2*2 + 1 = 5$

```
int RIGHT(int i)
```

```
return 2*i + 2;
```

Right child is at index
 $2*2 + 2 = 6$

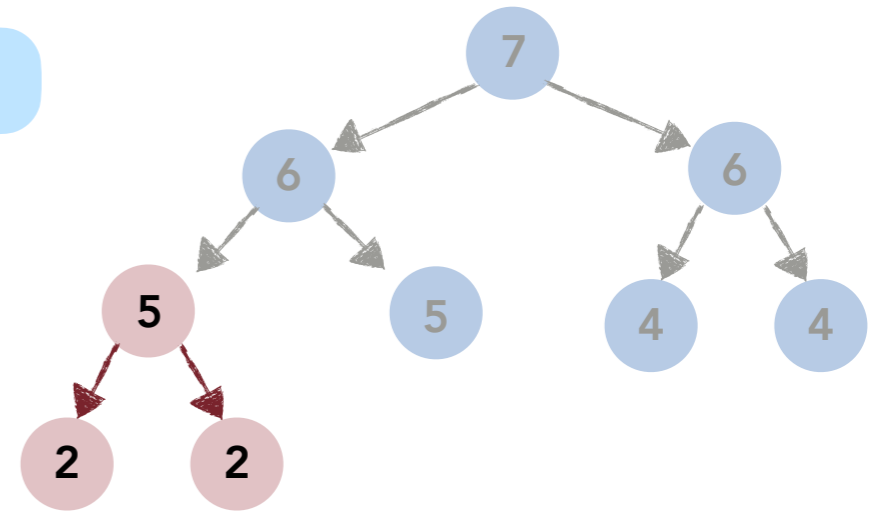
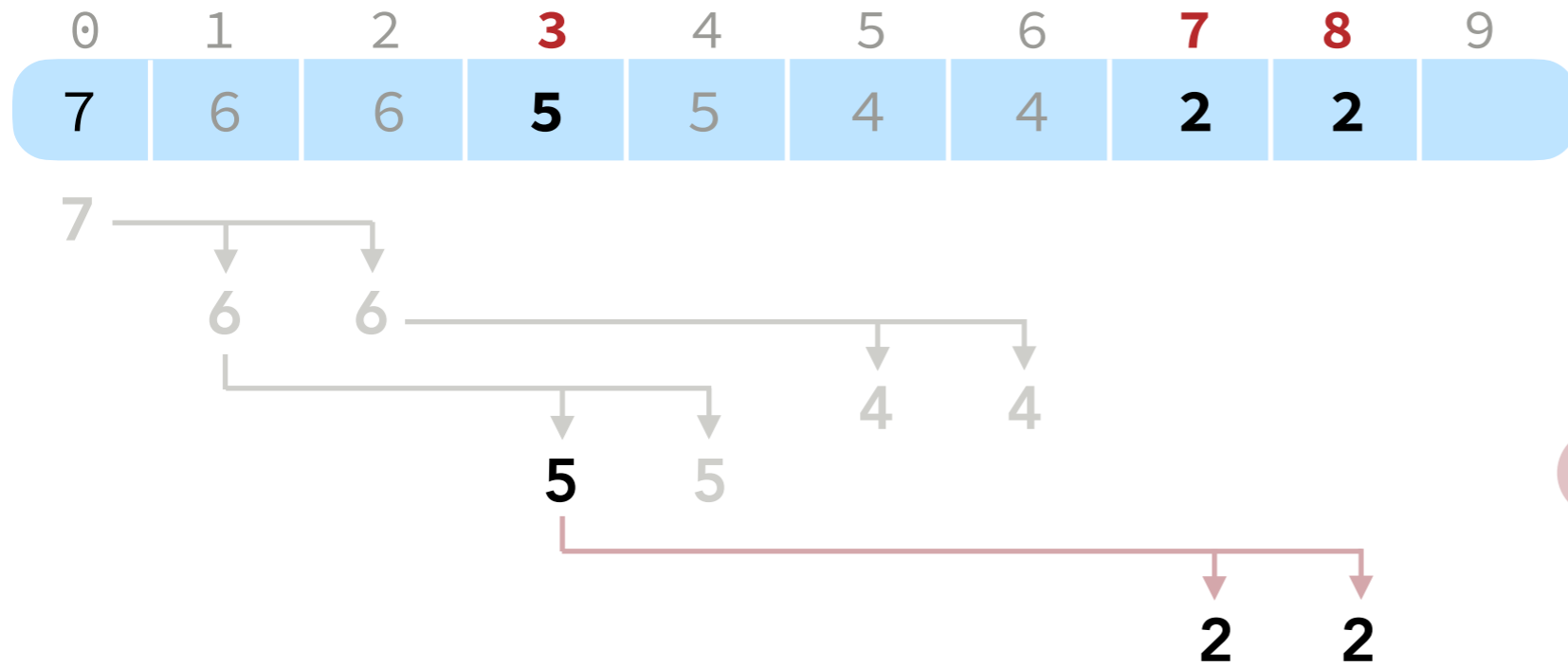
```
int PARENT(int i)
```

```
return (i-1) / 2;
```

Parent is at index
 $(2-1) / 2 = 0$

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

```
int LEFT(int i)
```

```
return 2*i + 1;
```

left child is at index
 $2*3 + 1 = 7$

```
int RIGHT(int i)
```

```
return 2*i + 2;
```

Right child is at index
 $2*3 + 2 = 8$

```
int PARENT(int i)
```

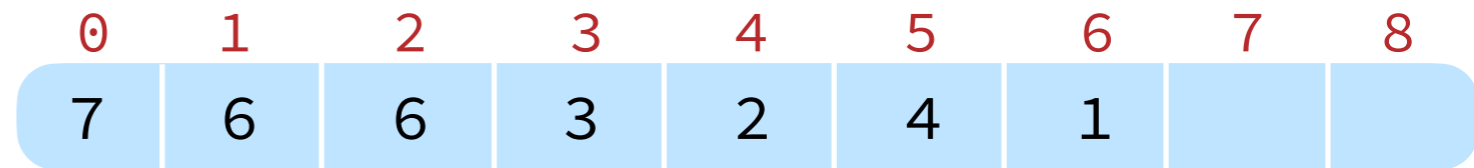
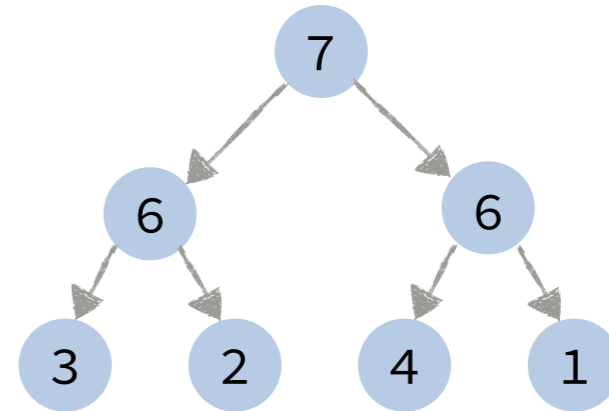
```
return (i-1) / 2;
```

Parent is at index
 $(3-1) / 2 = 1$

Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

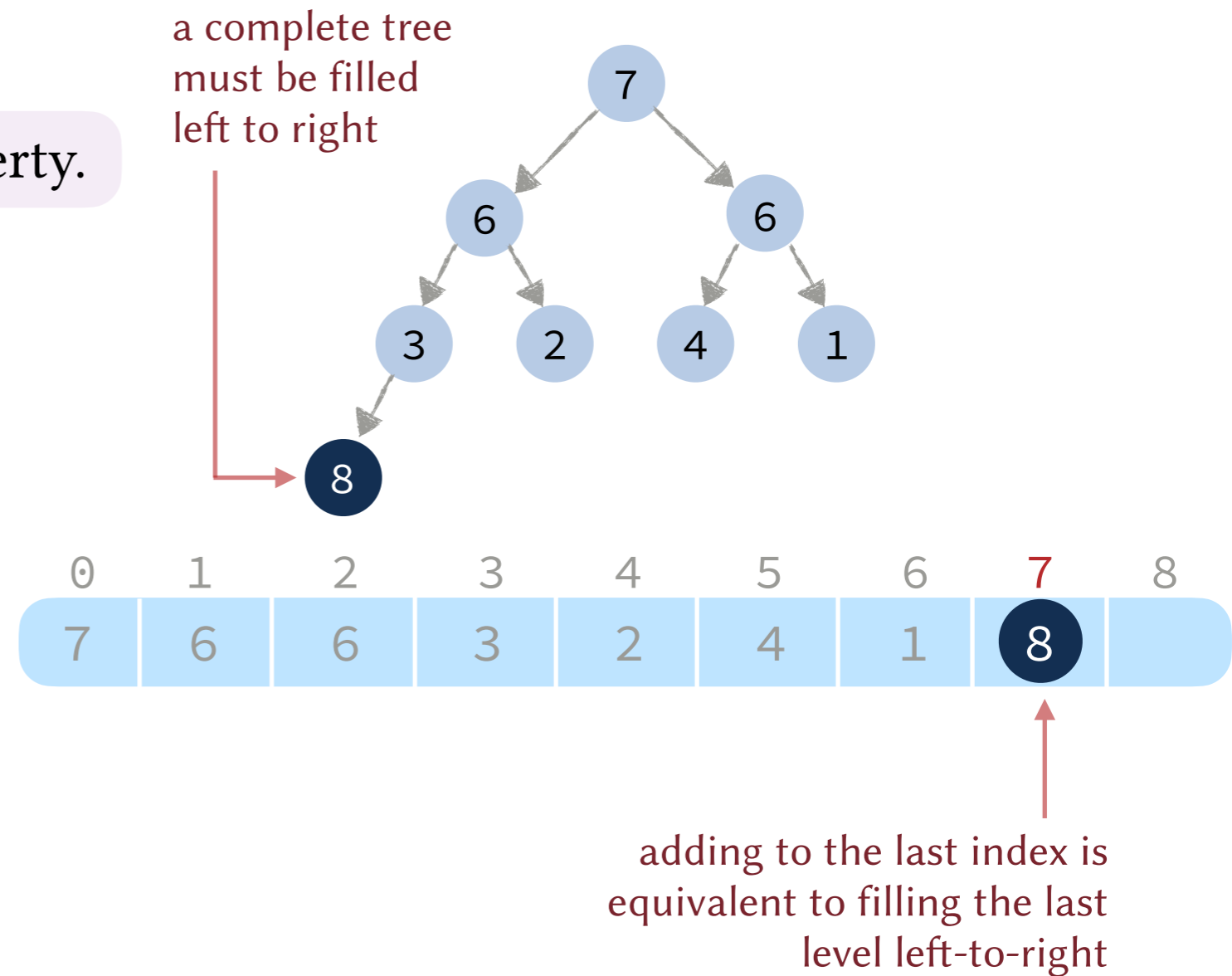


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

Example. Insert **8**

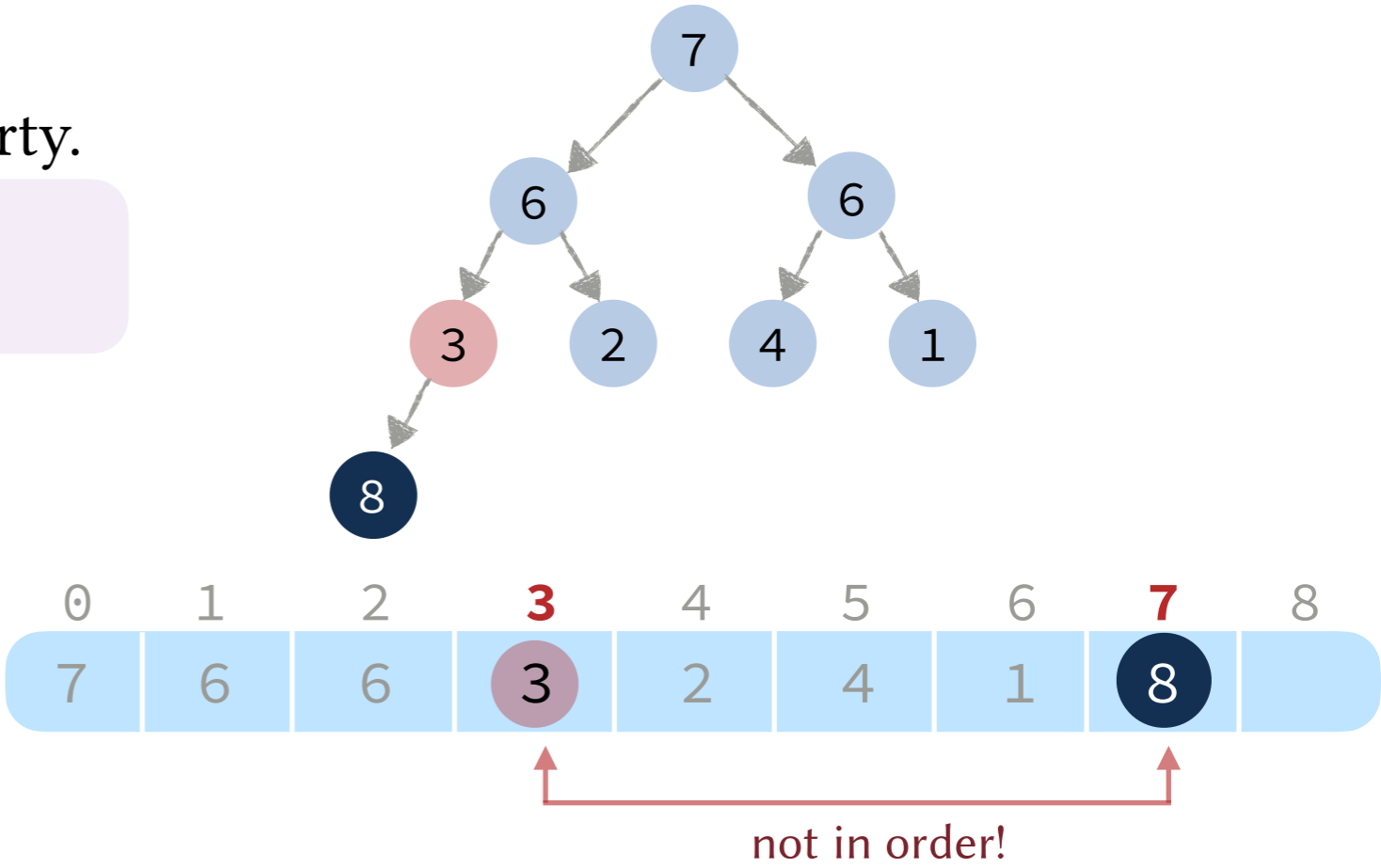


Binary Heaps: Insertion

Basic Plan.

- 1. Insert respecting the *structure* property.
- 2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

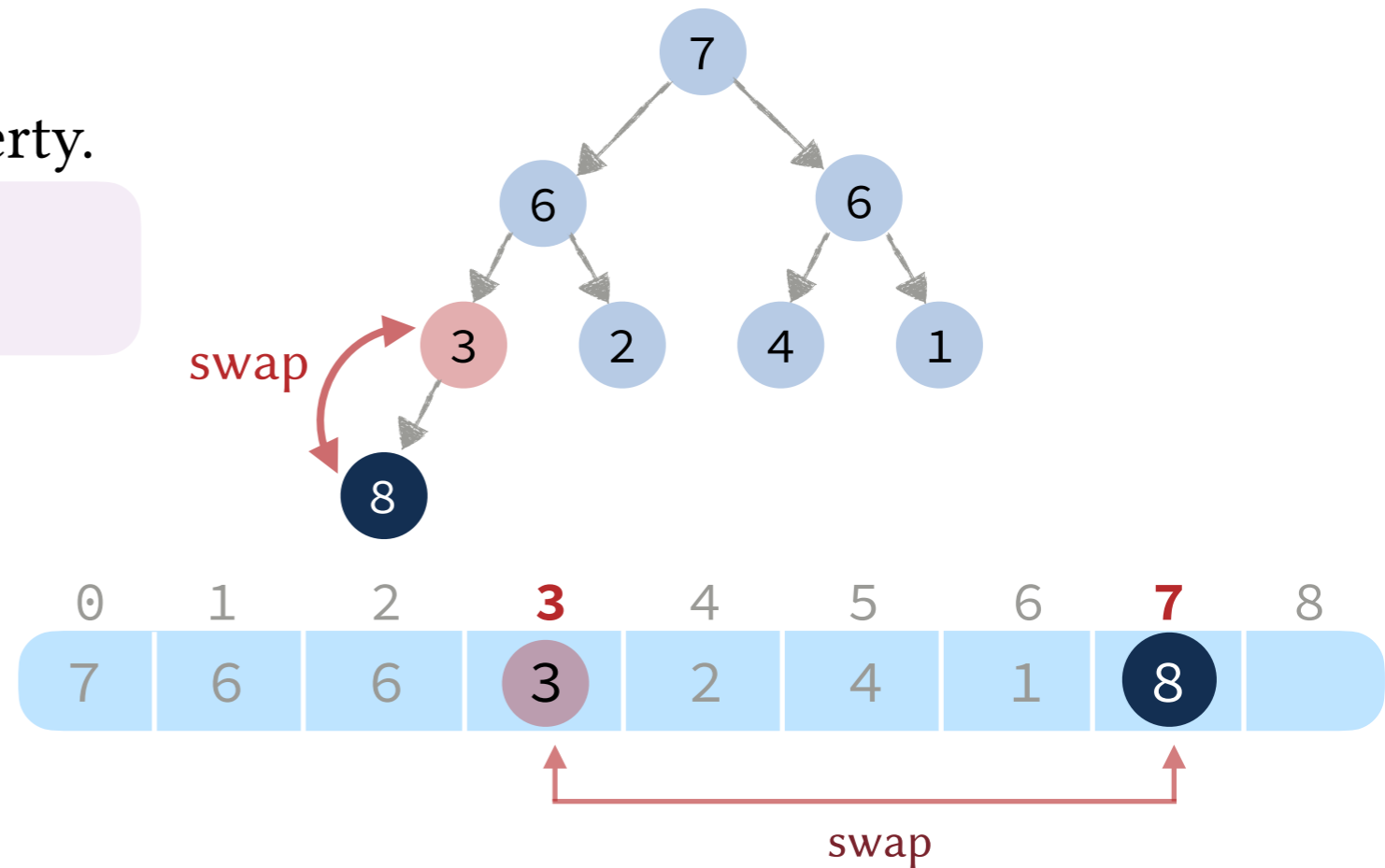


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

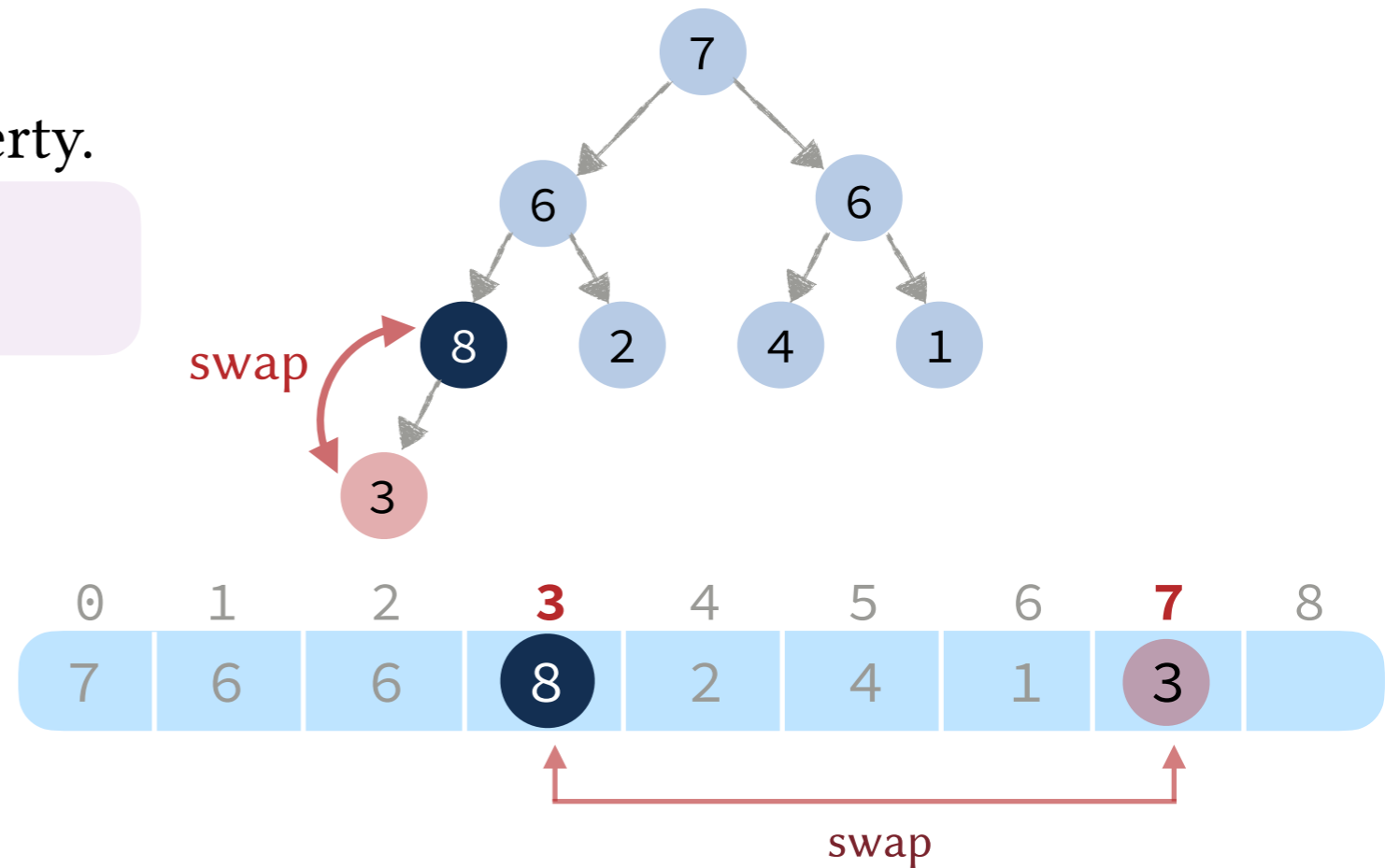


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

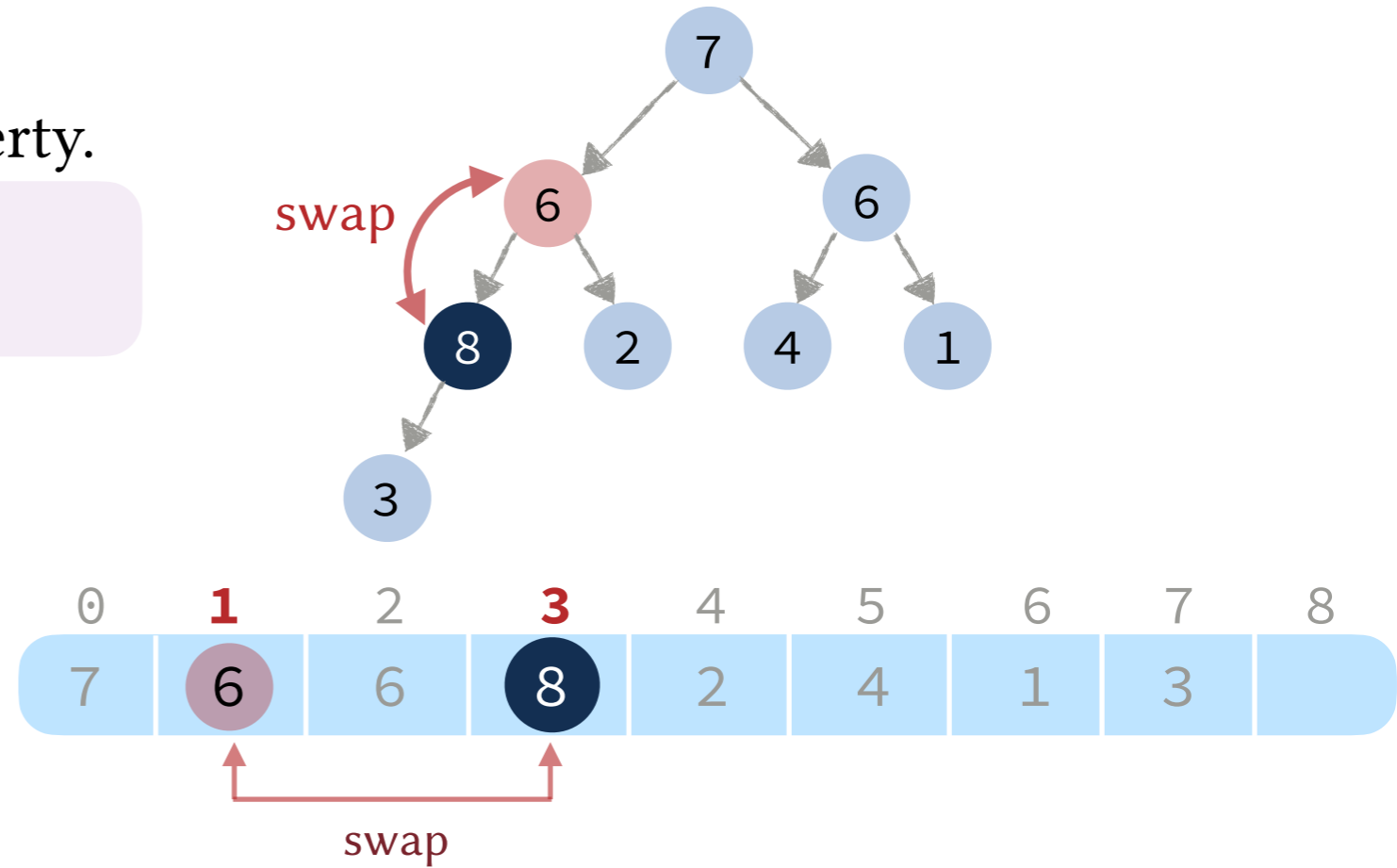


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

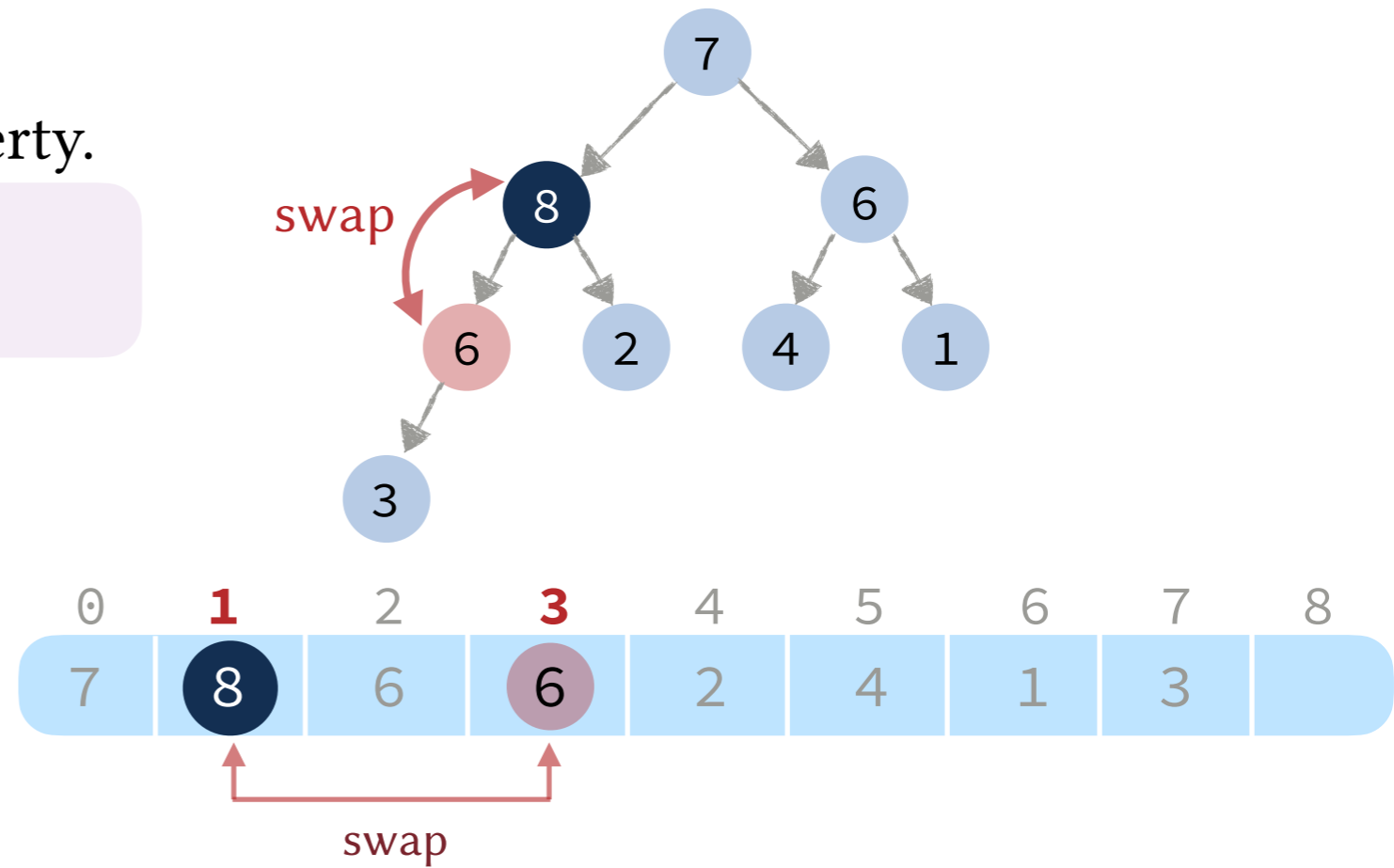


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

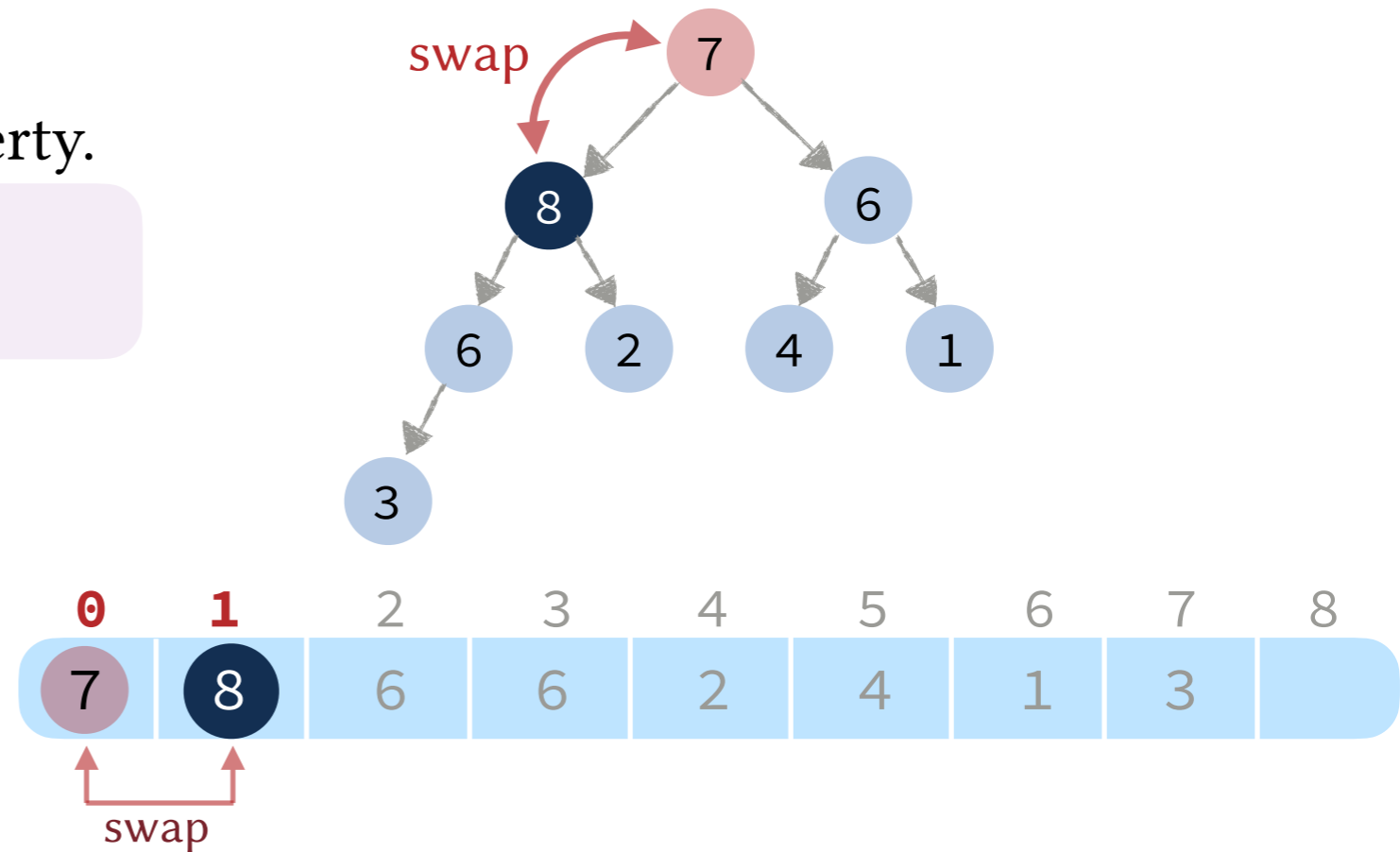


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.
swap up until the heap is fixed

Example. Insert **8**

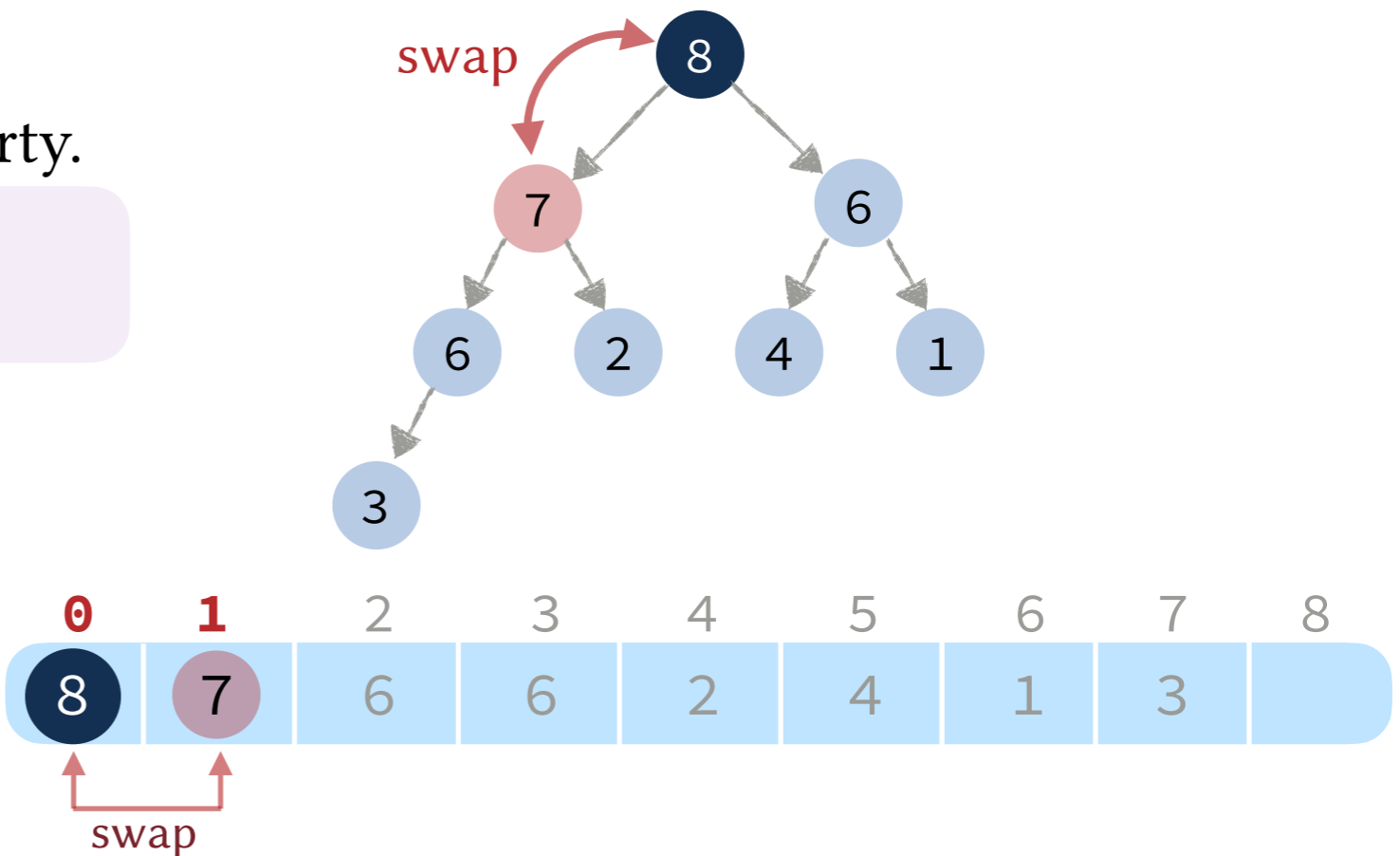


Binary Heaps: Insertion

Basic Plan.

- 1. Insert respecting the *structure* property.
- 2. Maintain the *order* property.
swap up until the heap is fixed

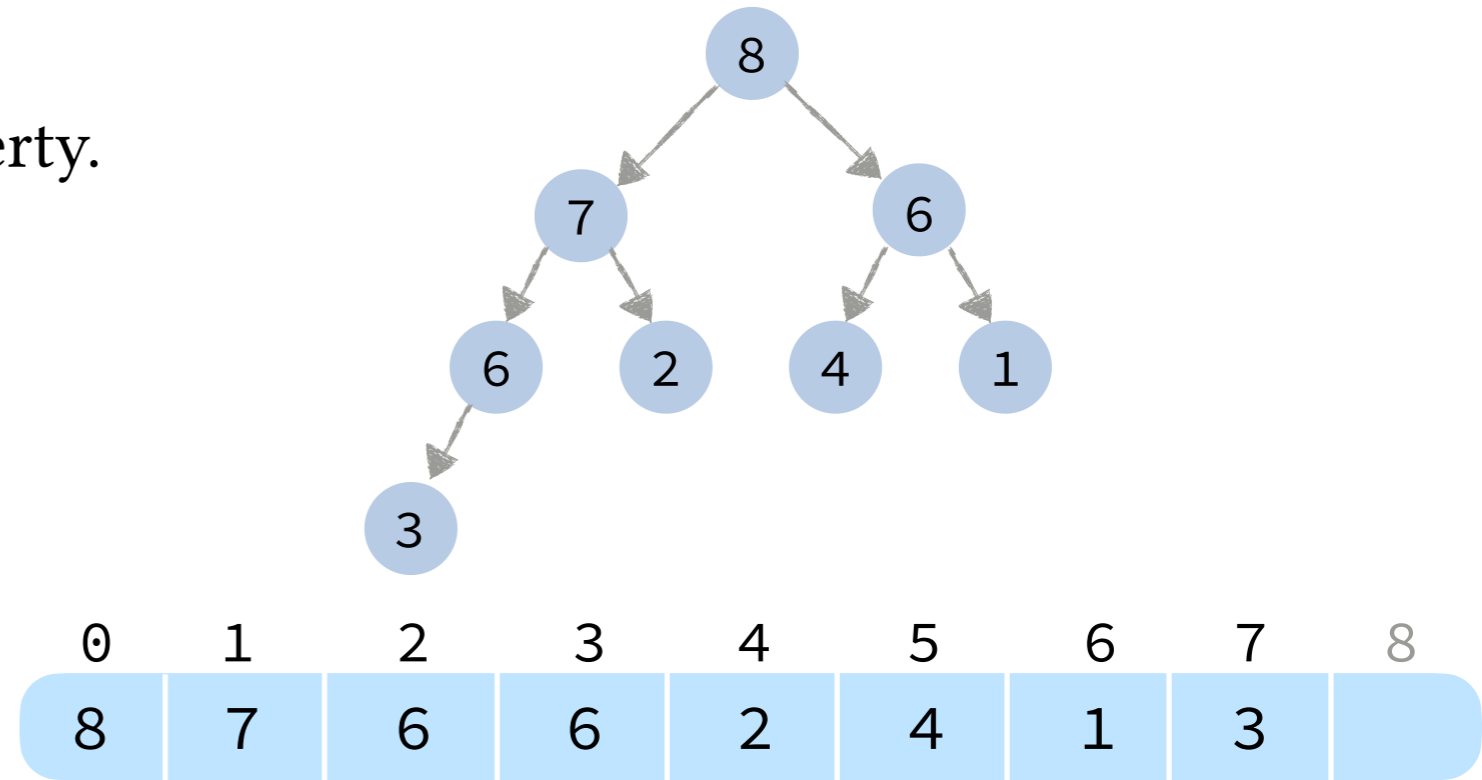
Example. Insert **8**



Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

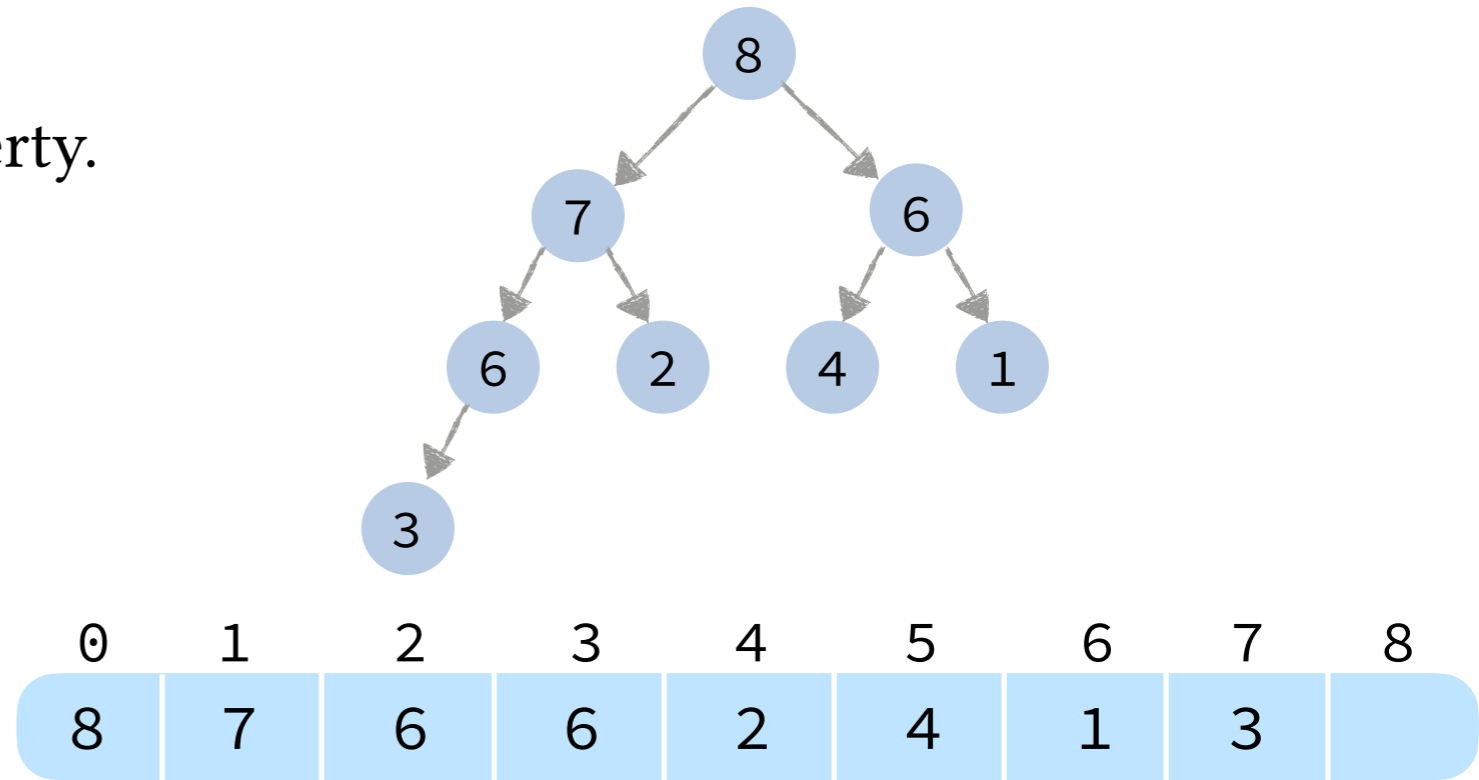


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

Example. Insert **5**

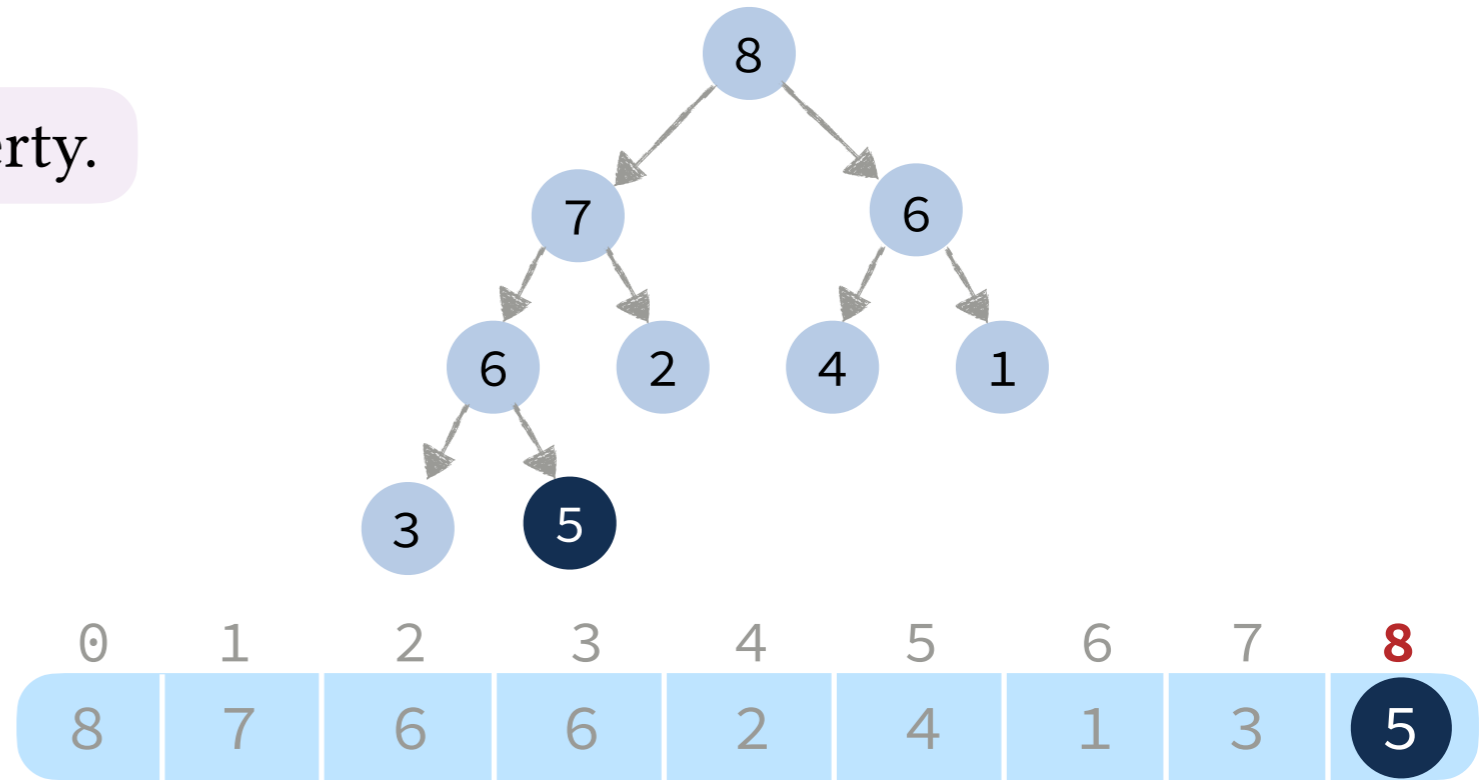


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

Example. Insert **5**

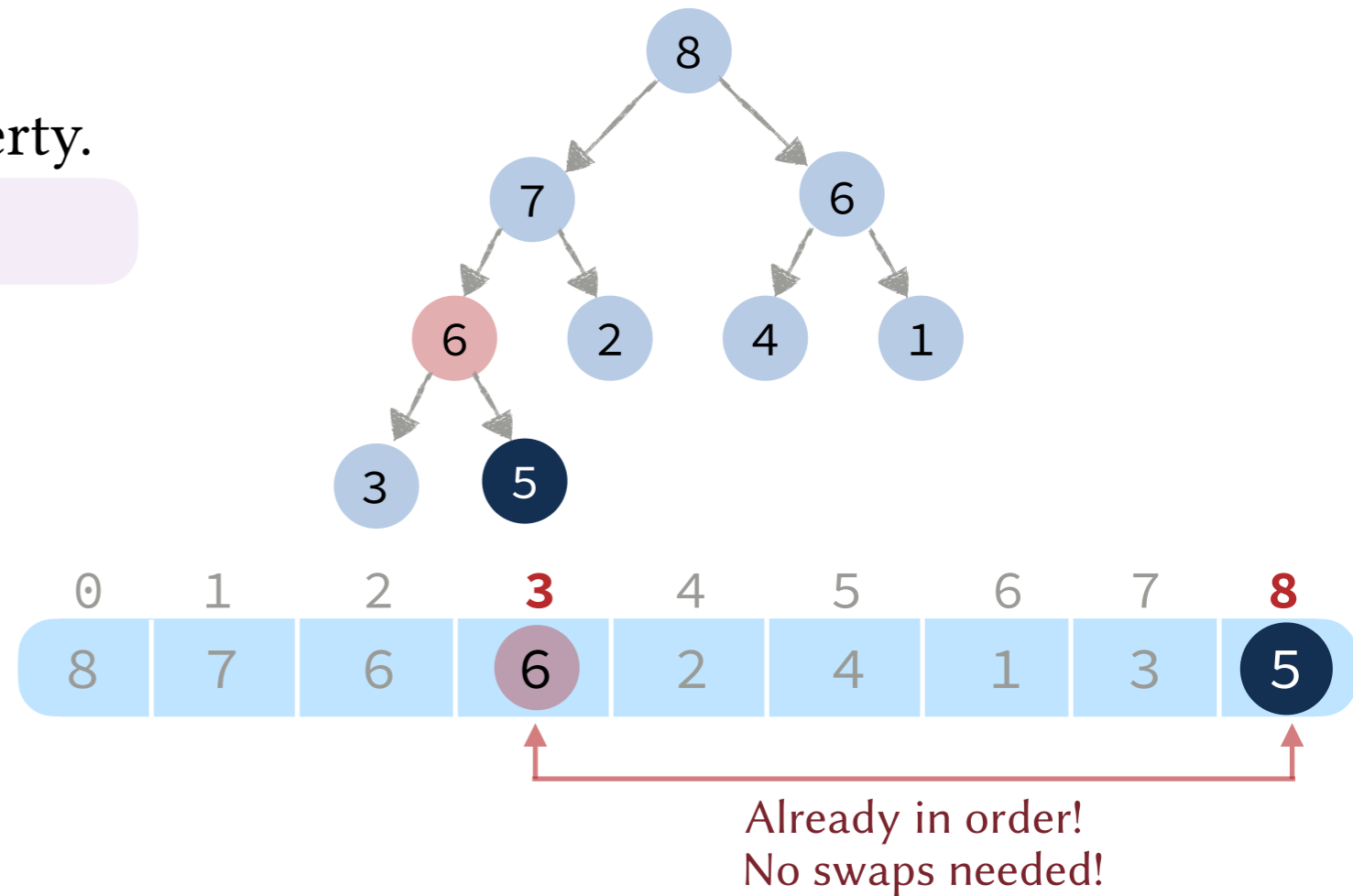


Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.

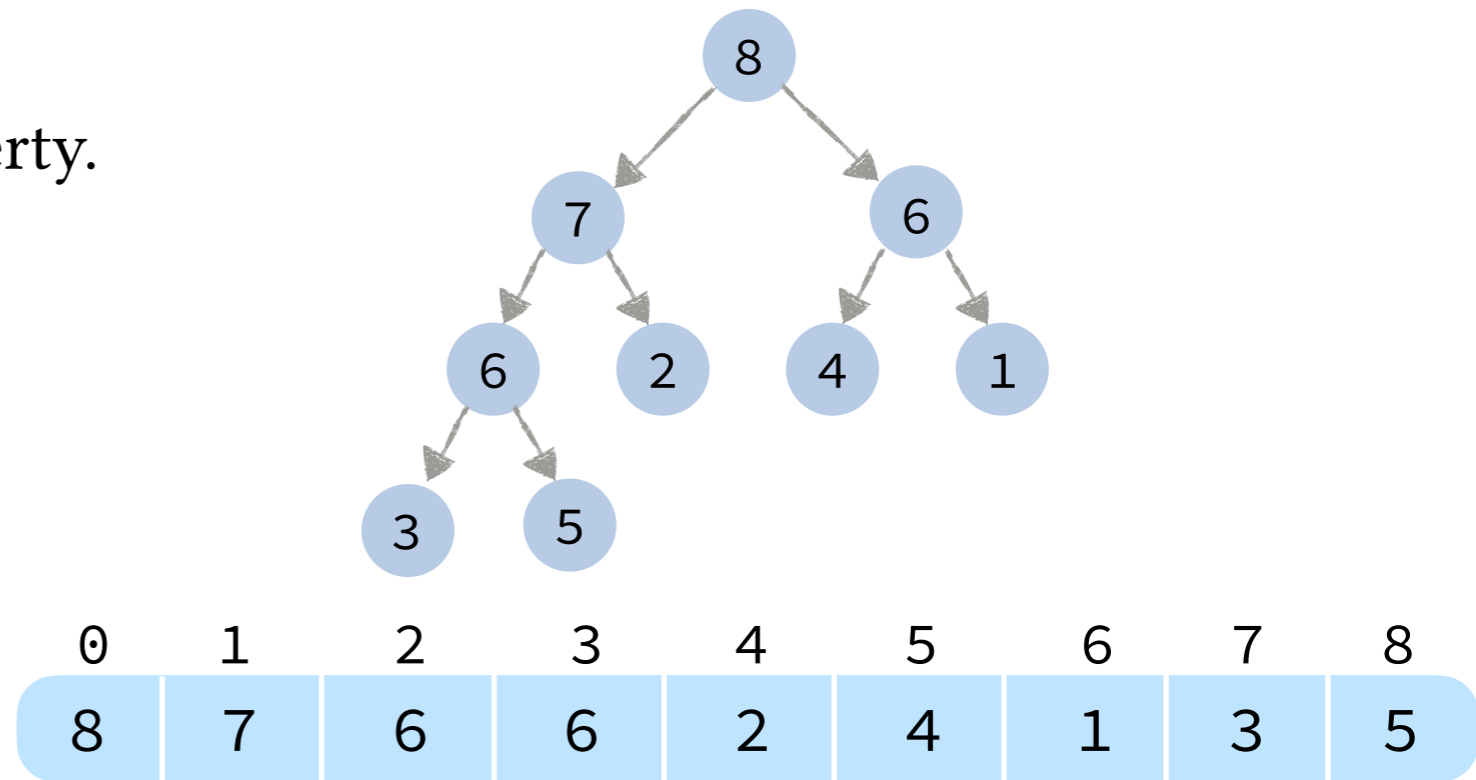
Example. Insert **5**



Binary Heaps: Insertion

Basic Plan.

1. Insert respecting the *structure* property.
2. Maintain the *order* property.



```
void insert(int a[], int& size, int val) {  
    a[size++] = val;  
    int i = size-1;  
    while (i > 0 && a[i] > a[PARENT(i)]) {  
        swap(a[i], a[PARENT(i)]);  
        i = PARENT(i);  
    }  
}
```

optional

Binary Heaps: Insertion

Basic Plan.

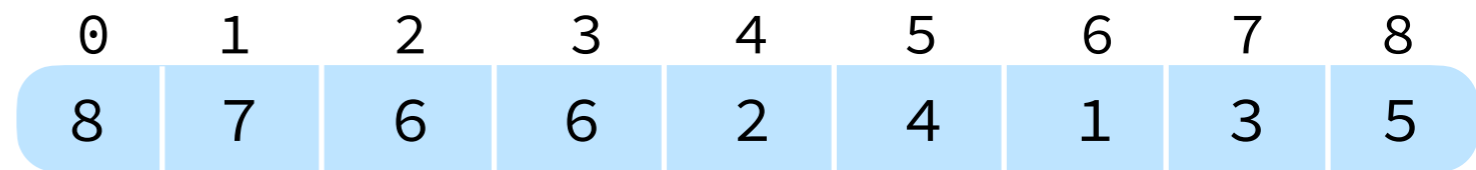
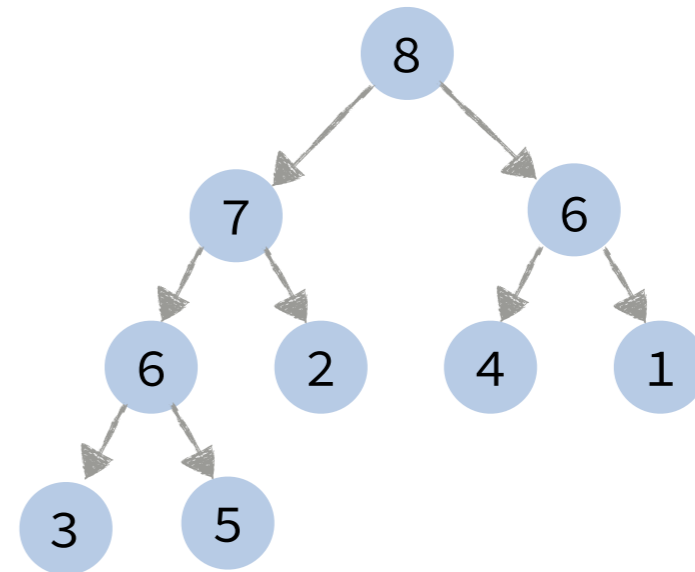
1. Insert respecting the *structure* property.
2. Maintain the *order* property.



Running Time.

Best Case: 0 swaps and 1 data compare.

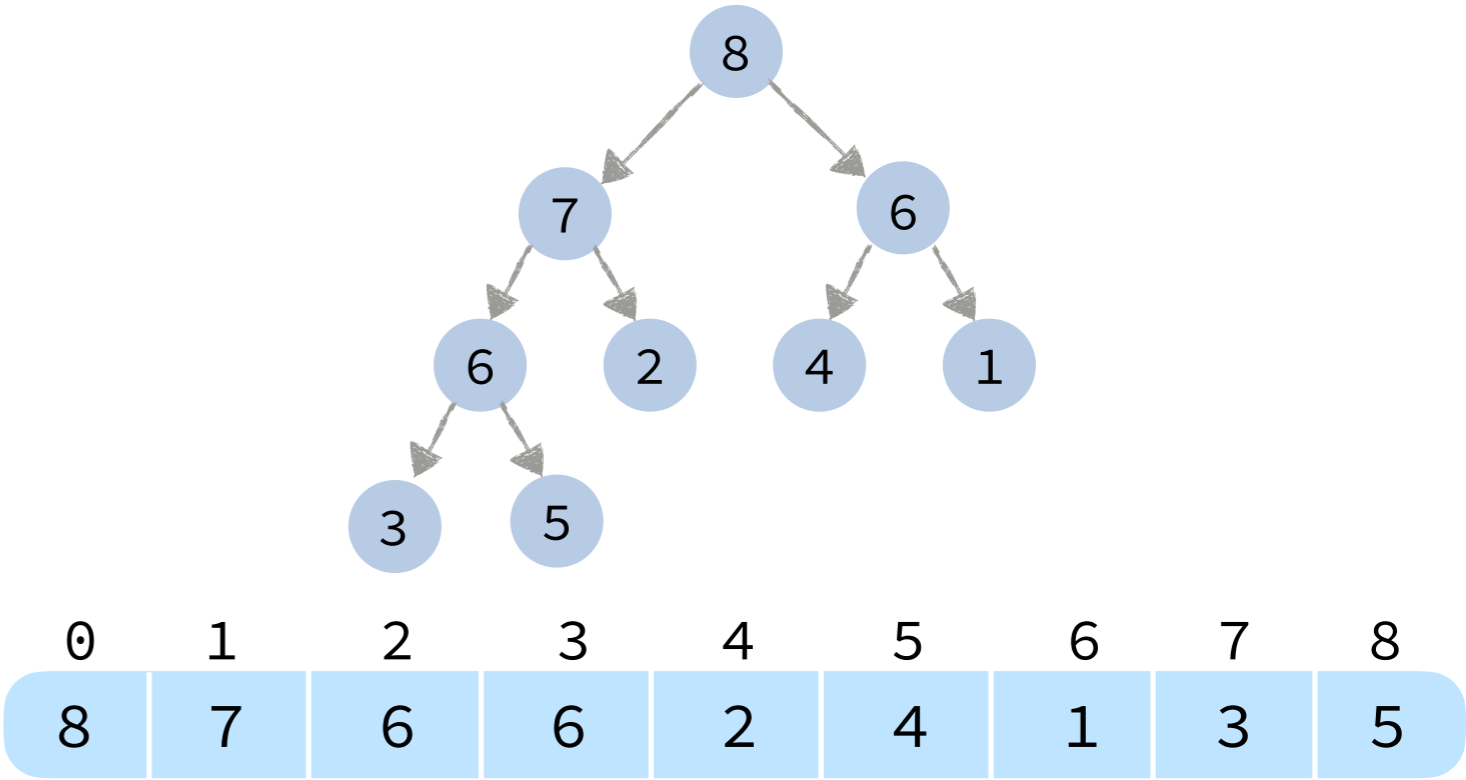
Worst Case: $\lfloor \log_2 n \rfloor$ swaps and $\lfloor \log_2 n \rfloor$ data compares.



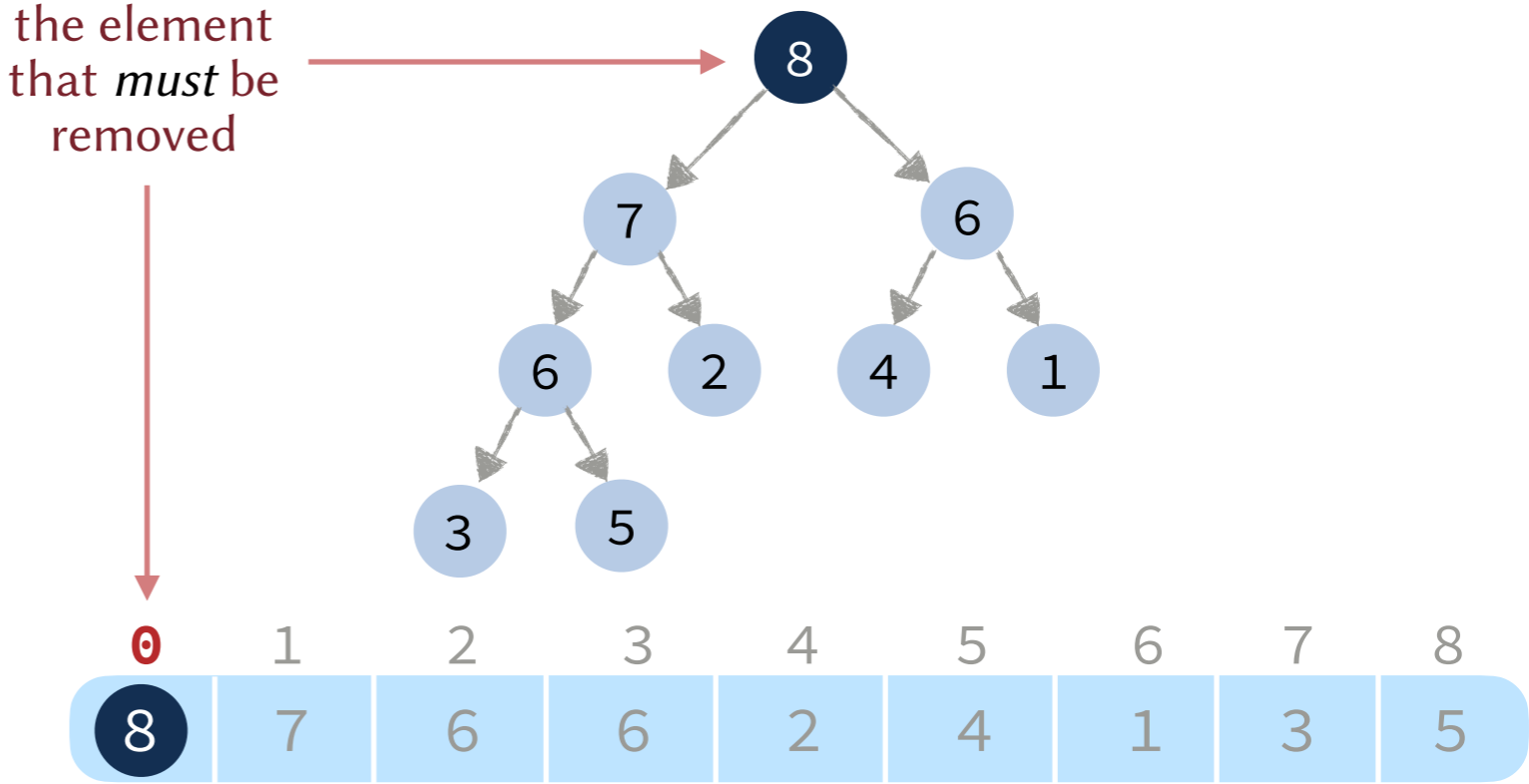
```
void insert(int a[], int& size, int val) {  
    a[size++] = val;  
    int i = size-1;  
    while (i > 0 && a[i] > a[PARENT(i)]) {  
        swap(a[i], a[PARENT(i)]);  
        i = PARENT(i);  
    }  
}
```

optional

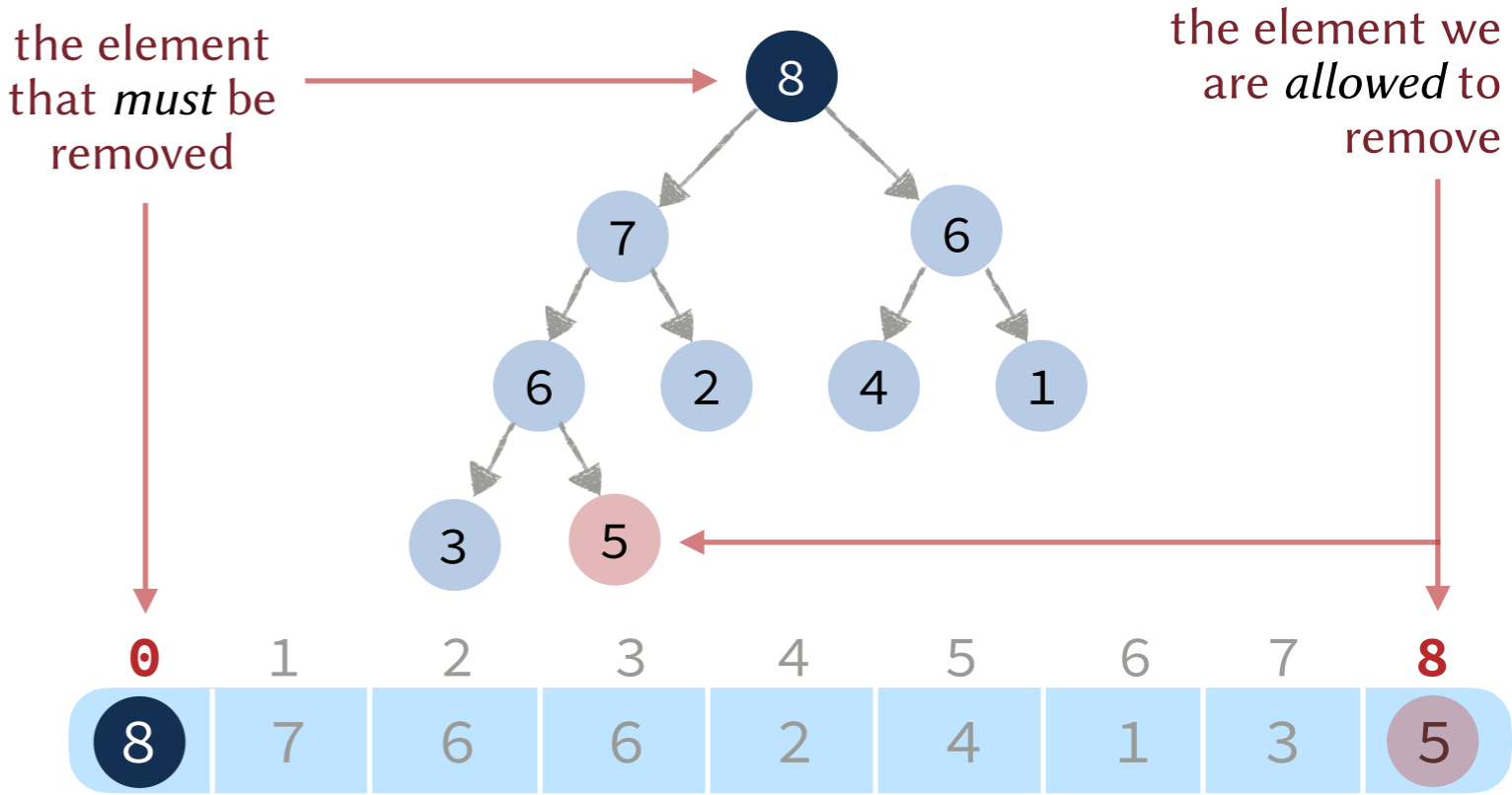
Binary Heaps: Deletion



Binary Heaps: Deletion



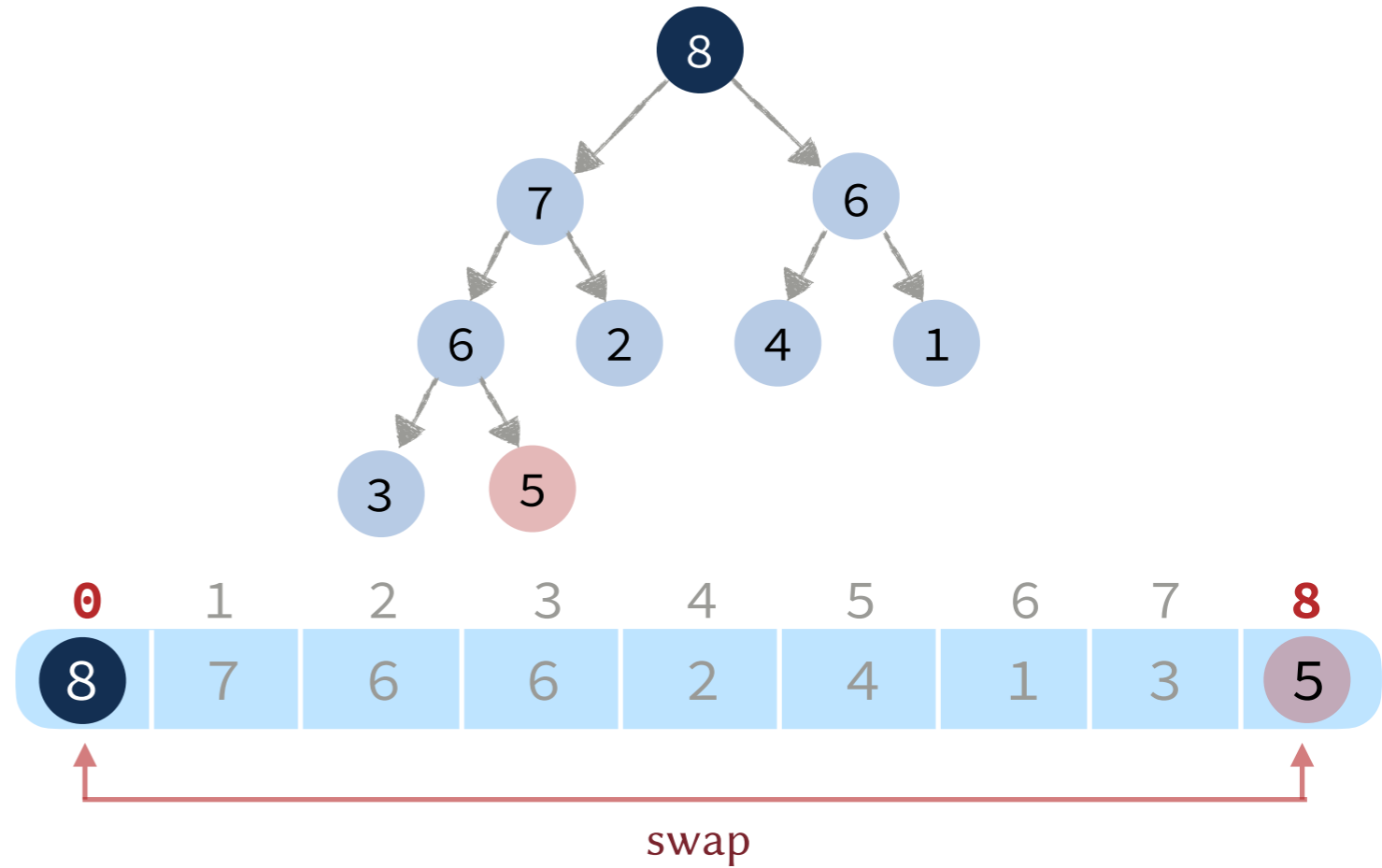
Binary Heaps: Deletion



Binary Heaps: Deletion

Basic Plan.

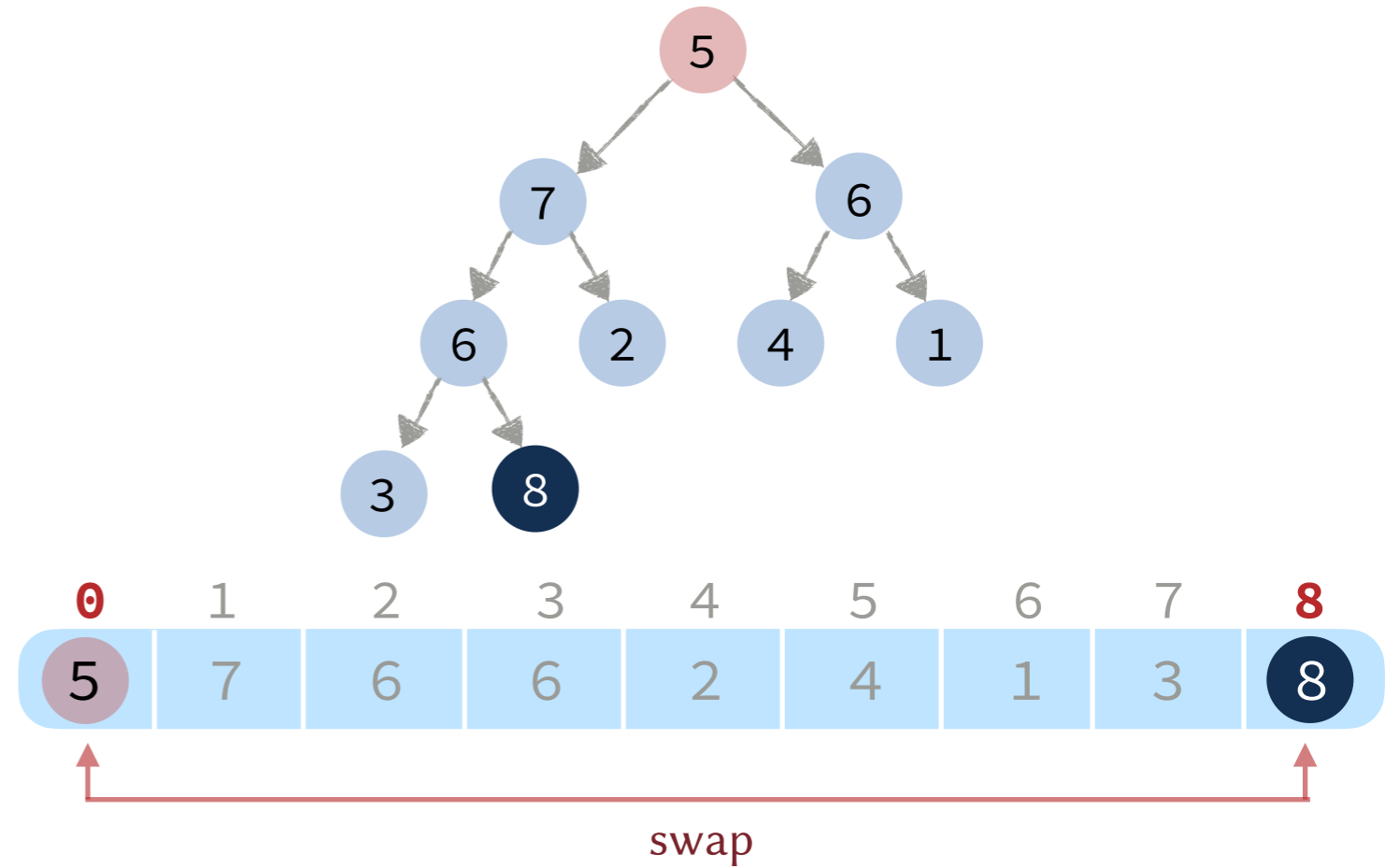
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

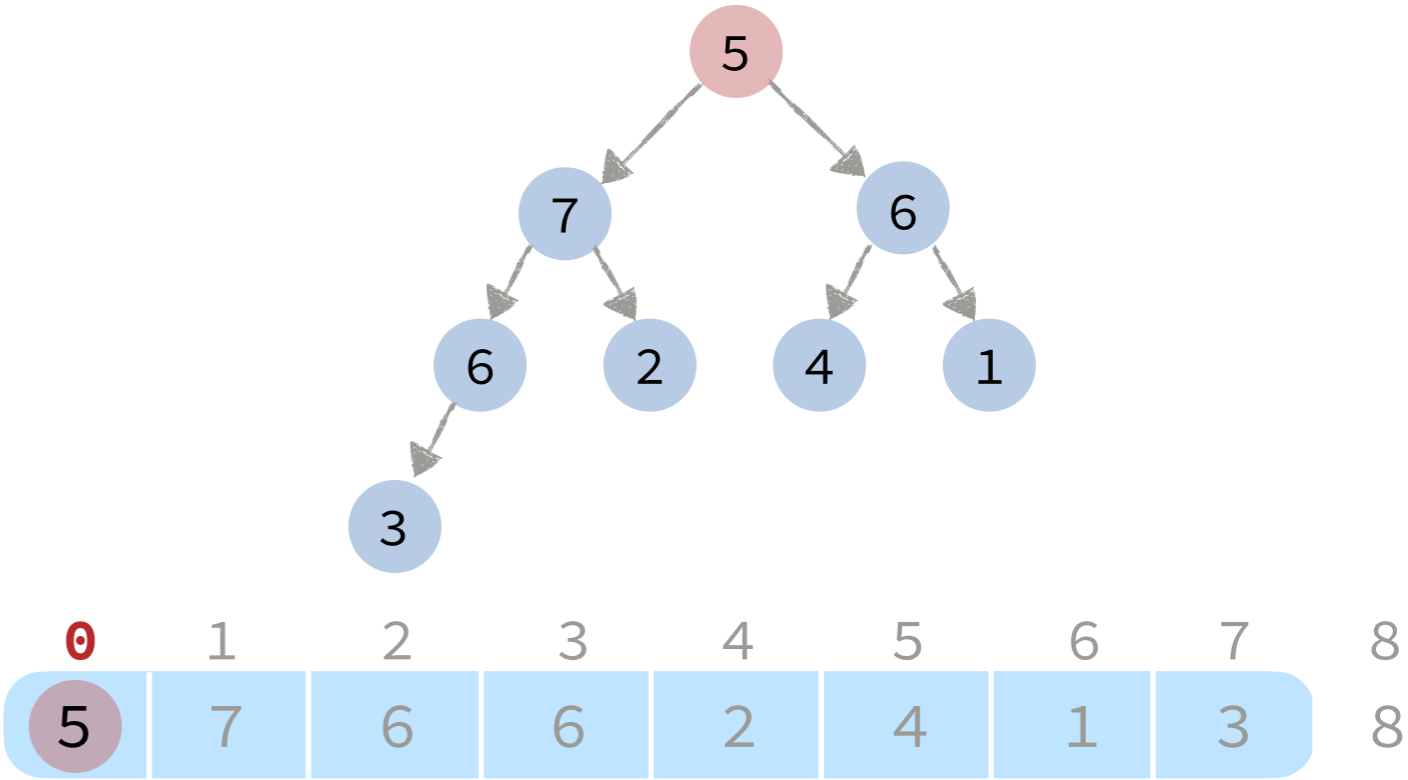
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

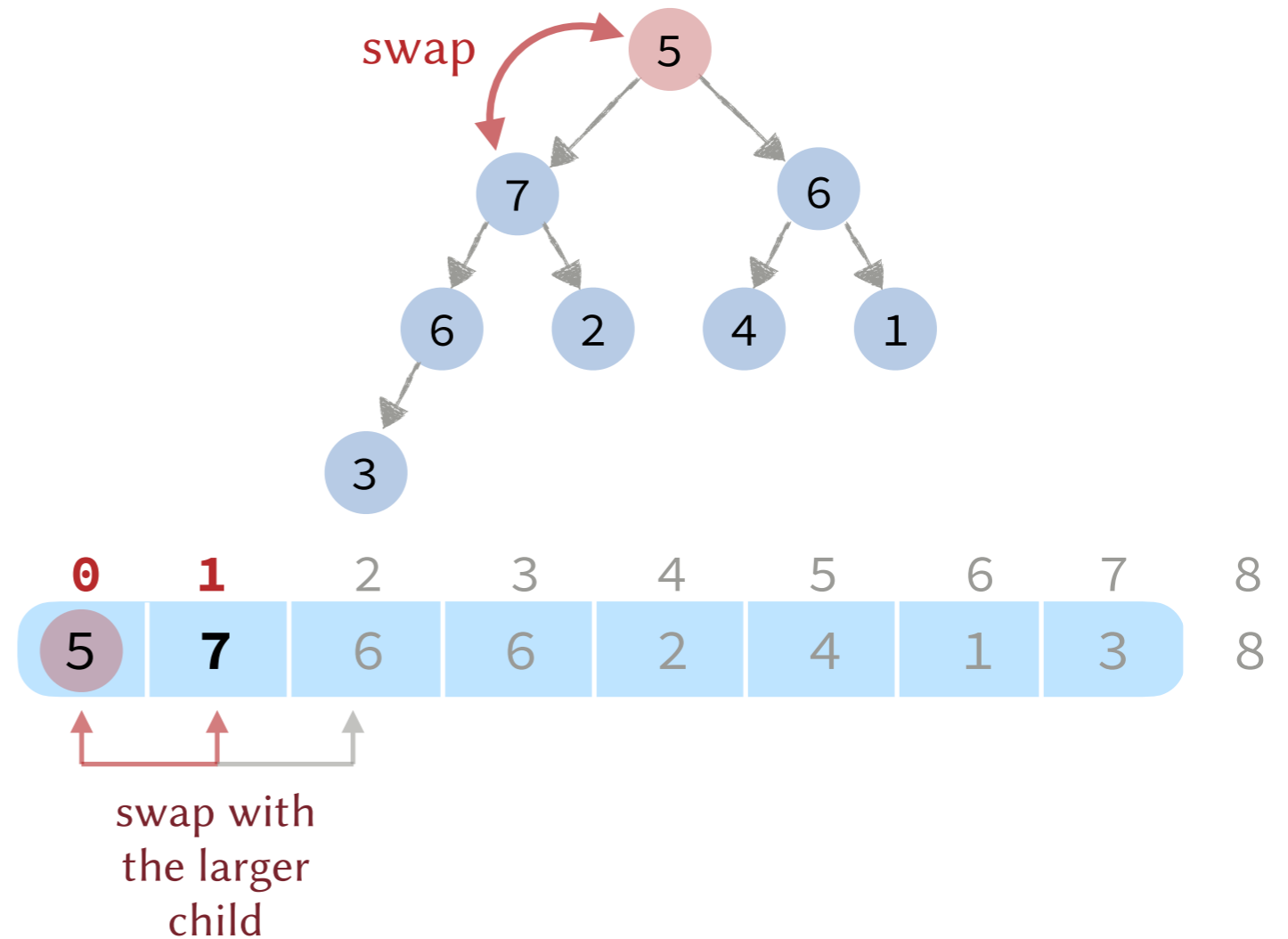
- 1. Swap the first and last elements in the heap.
- 2. Delete the last element.
- 3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

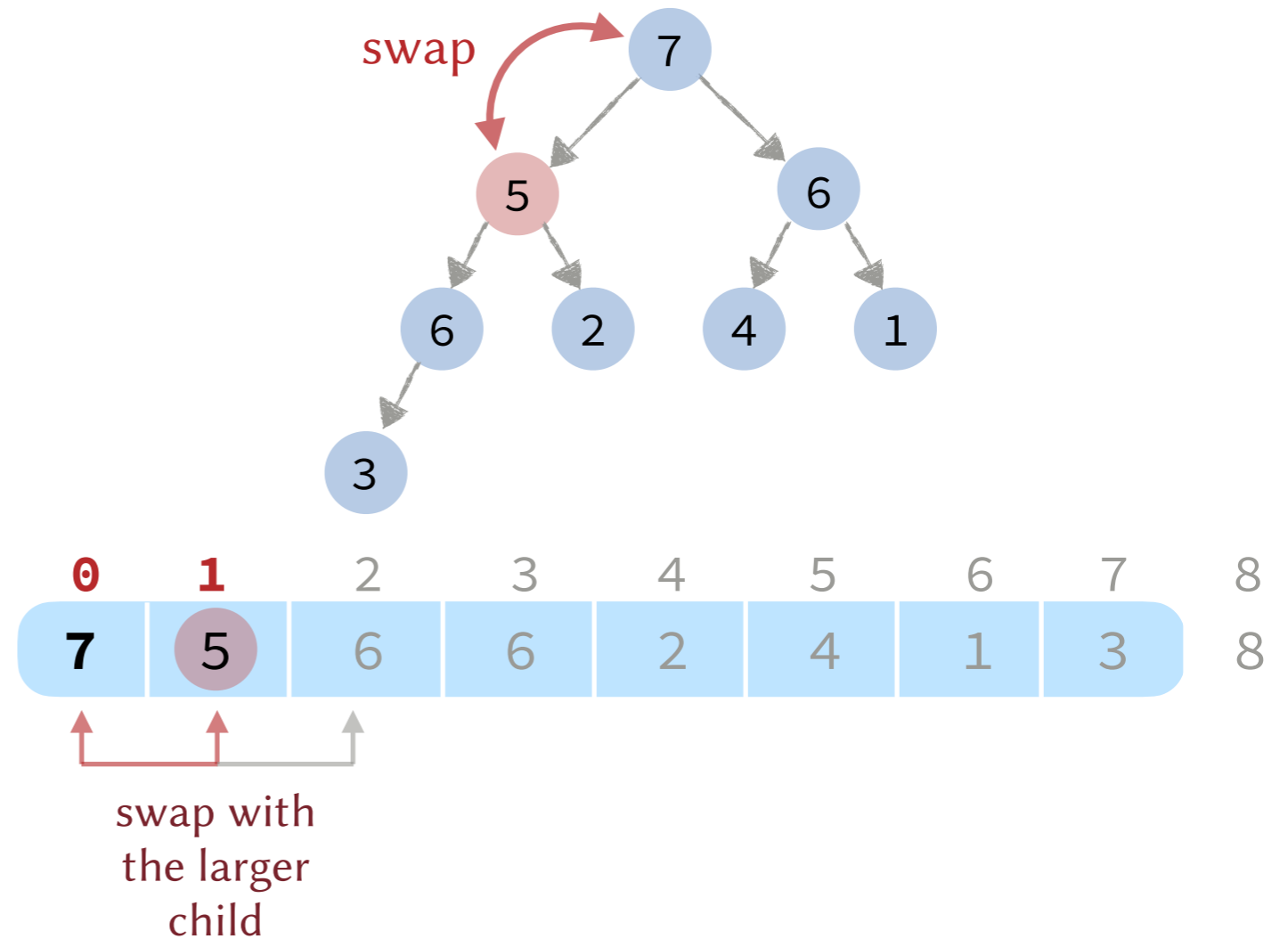
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

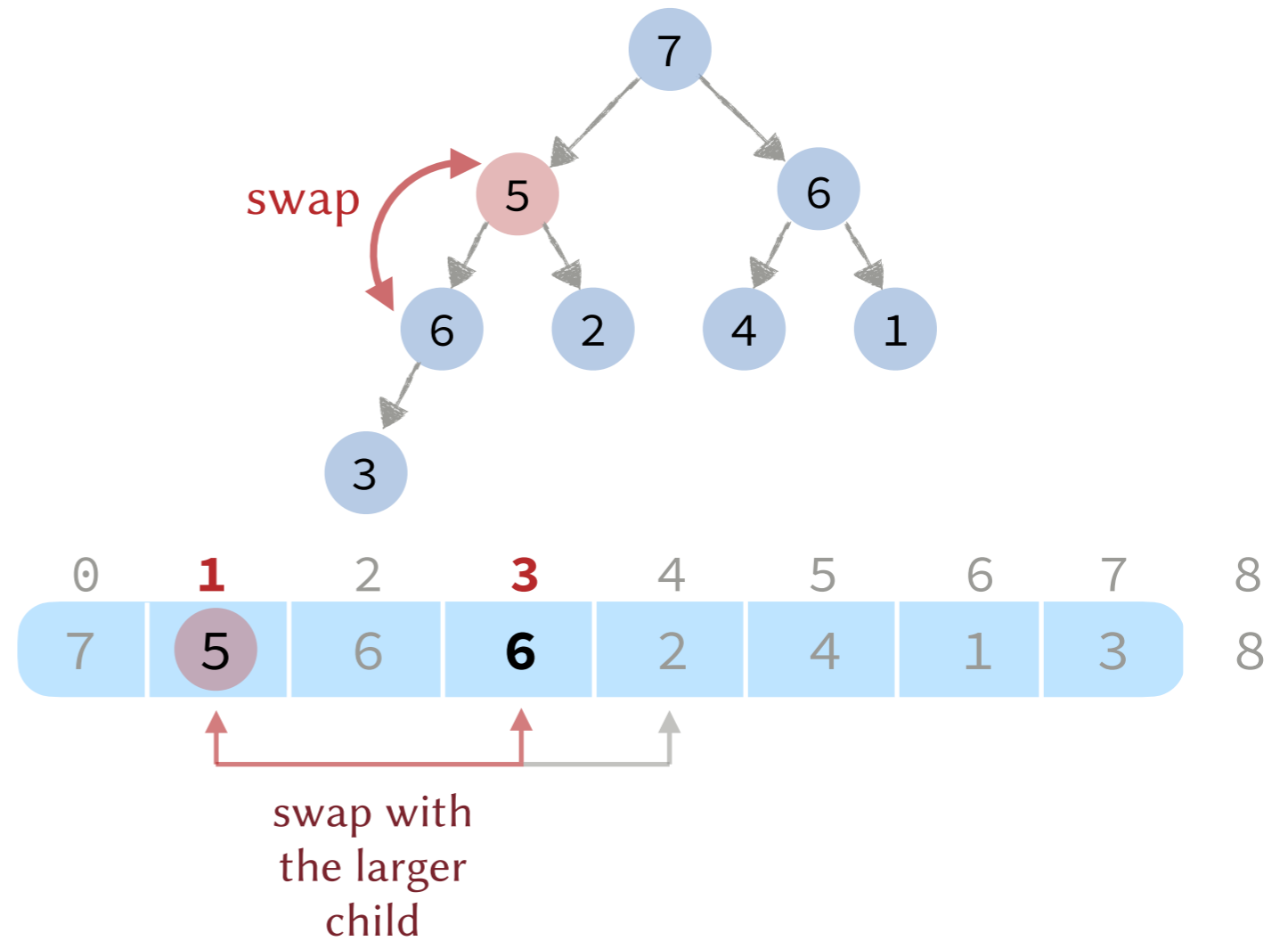
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

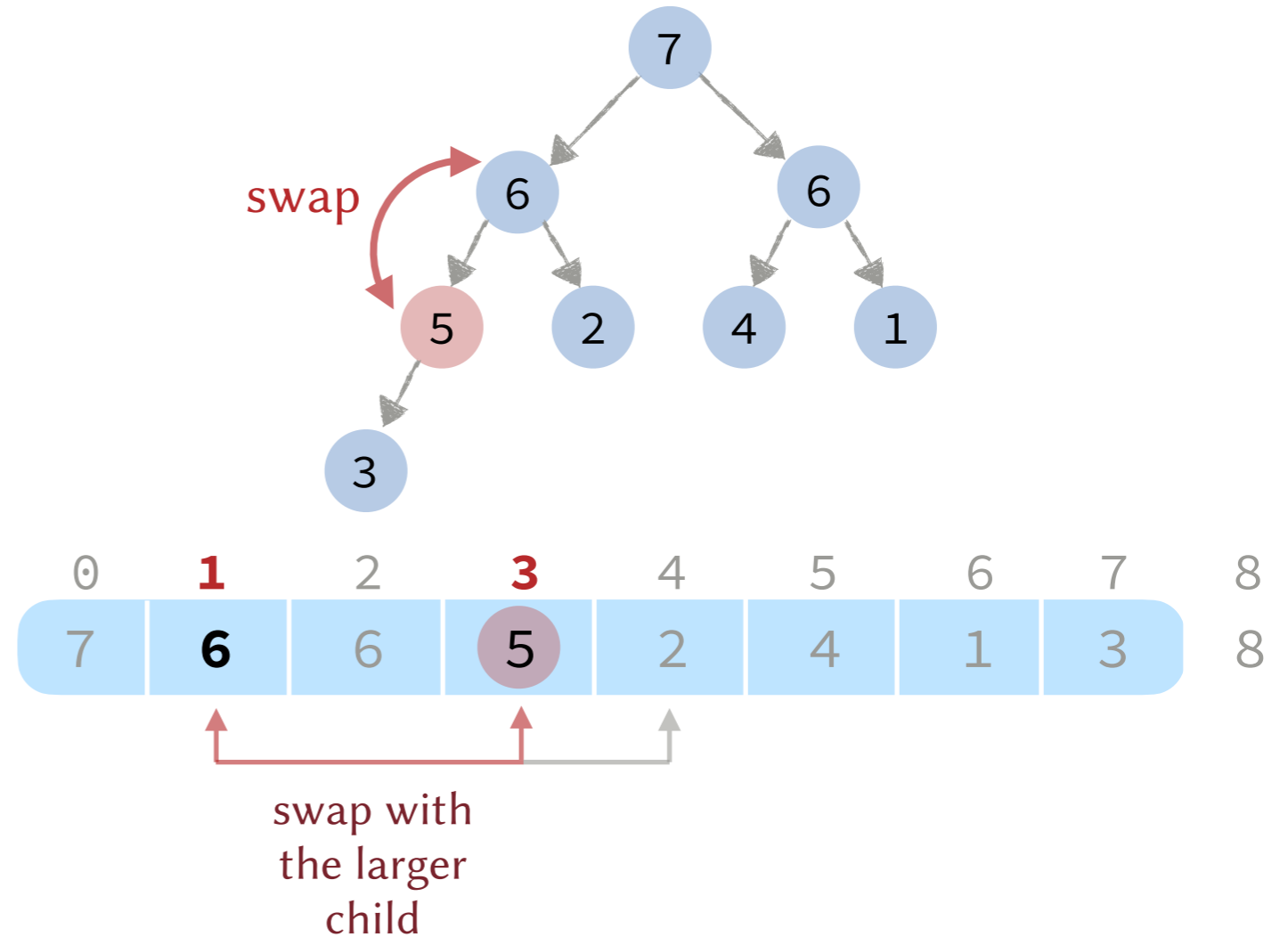
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

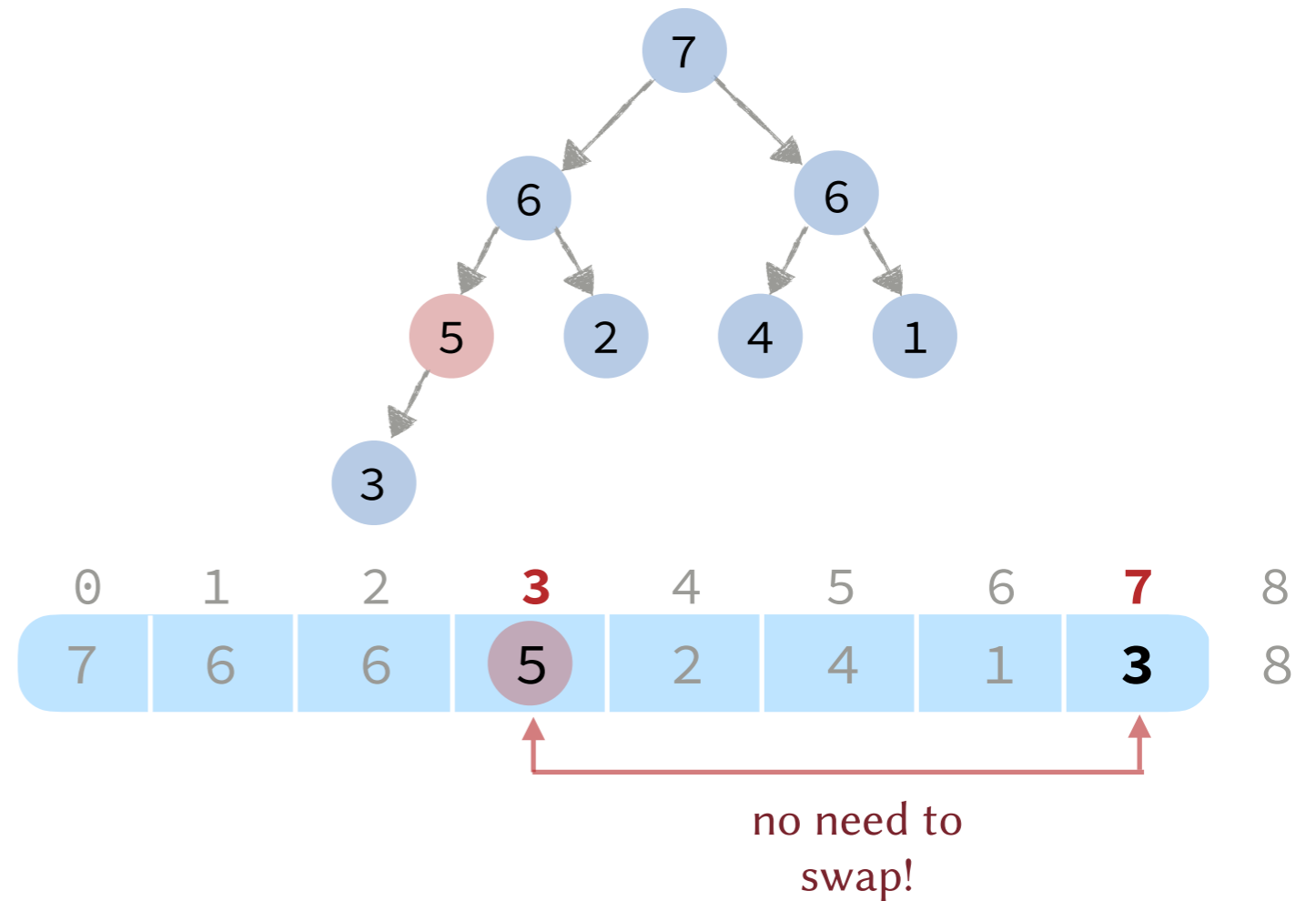
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

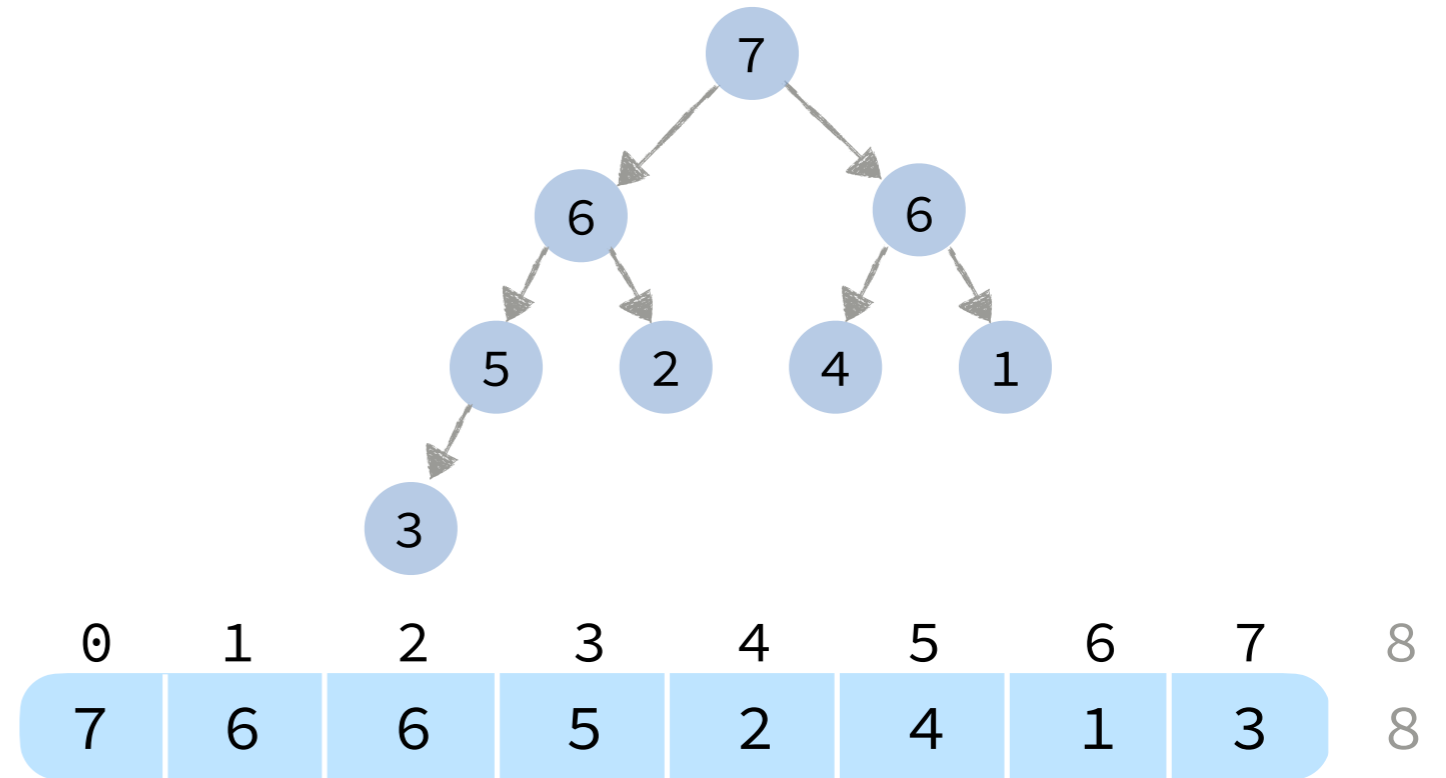
1. Swap the first and last elements in the heap.
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3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

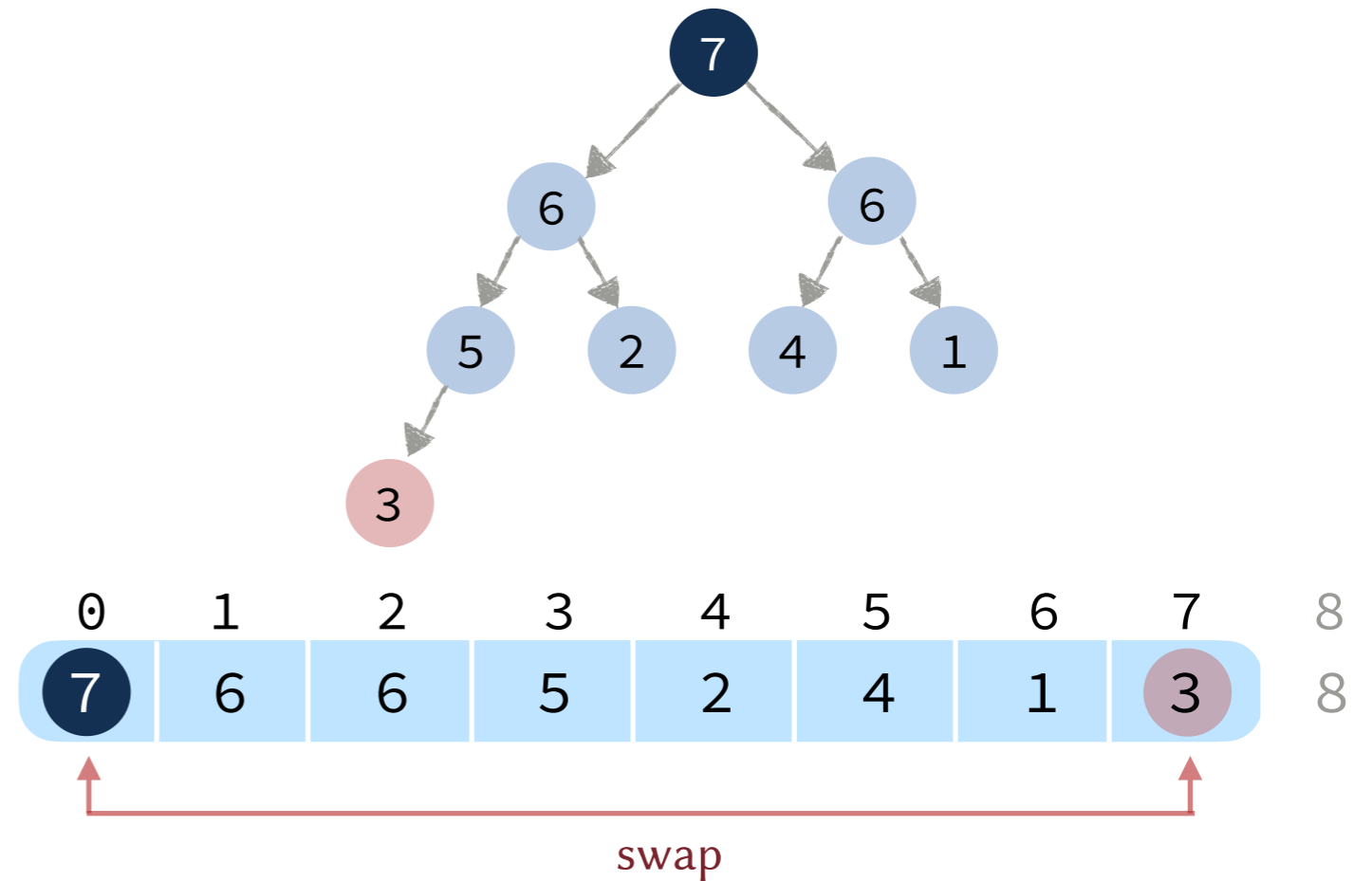
1. Swap the first and last elements in the heap.
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3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

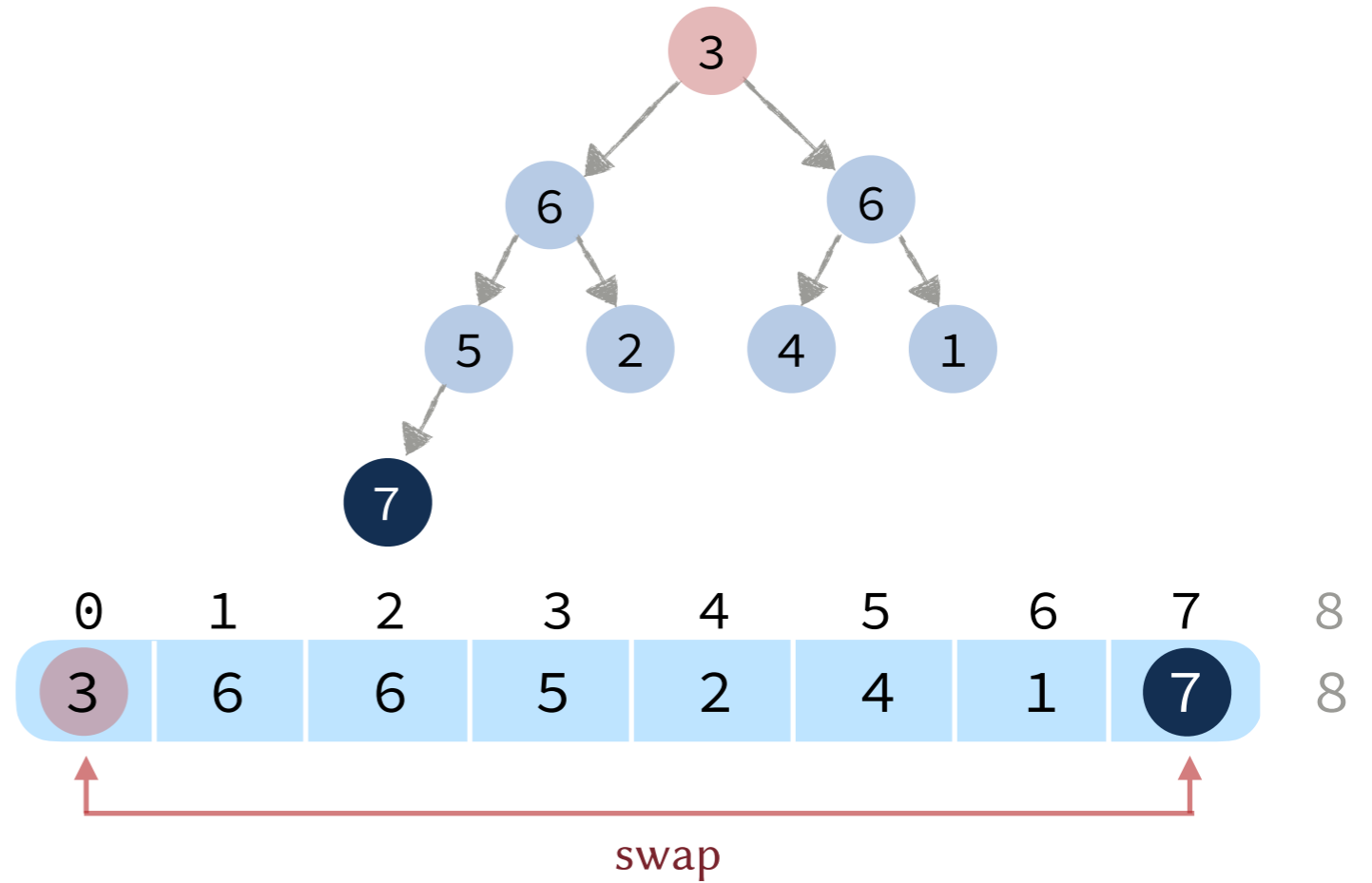
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

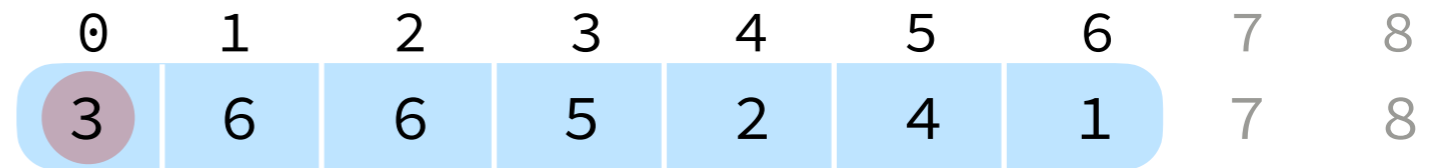
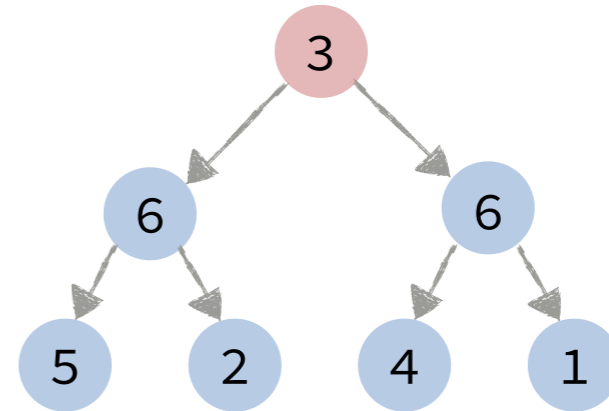
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

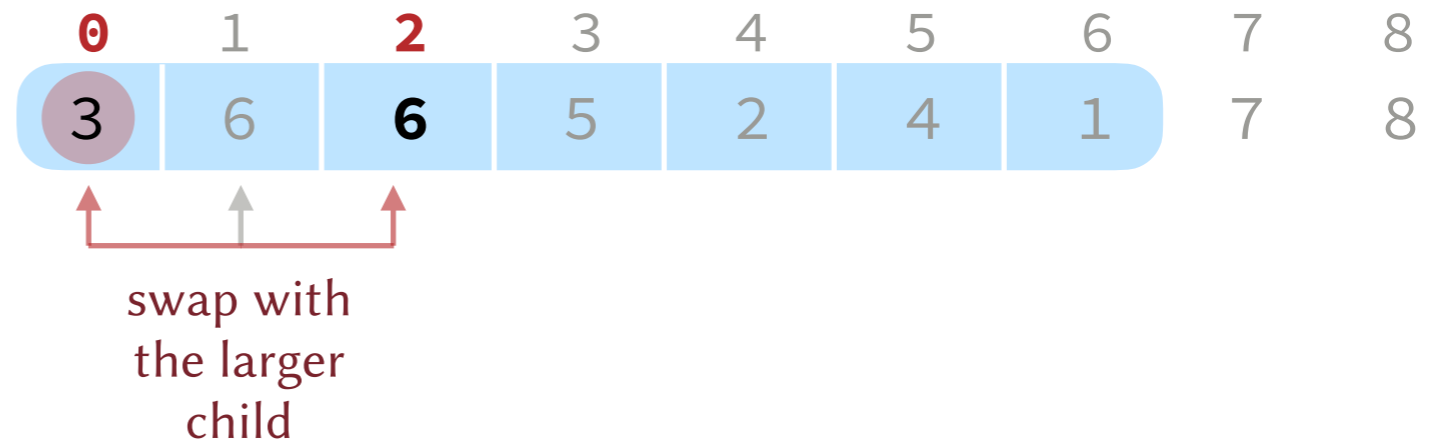
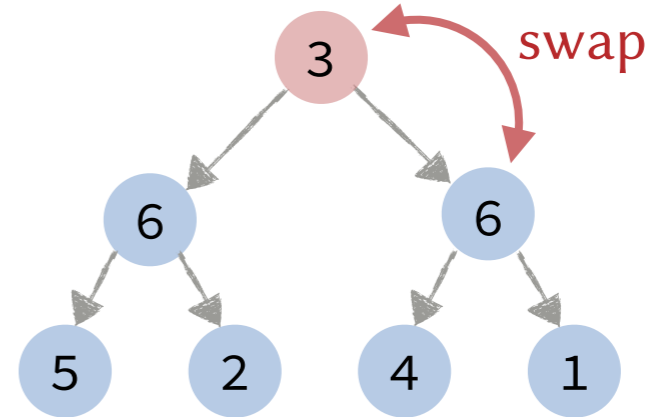
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

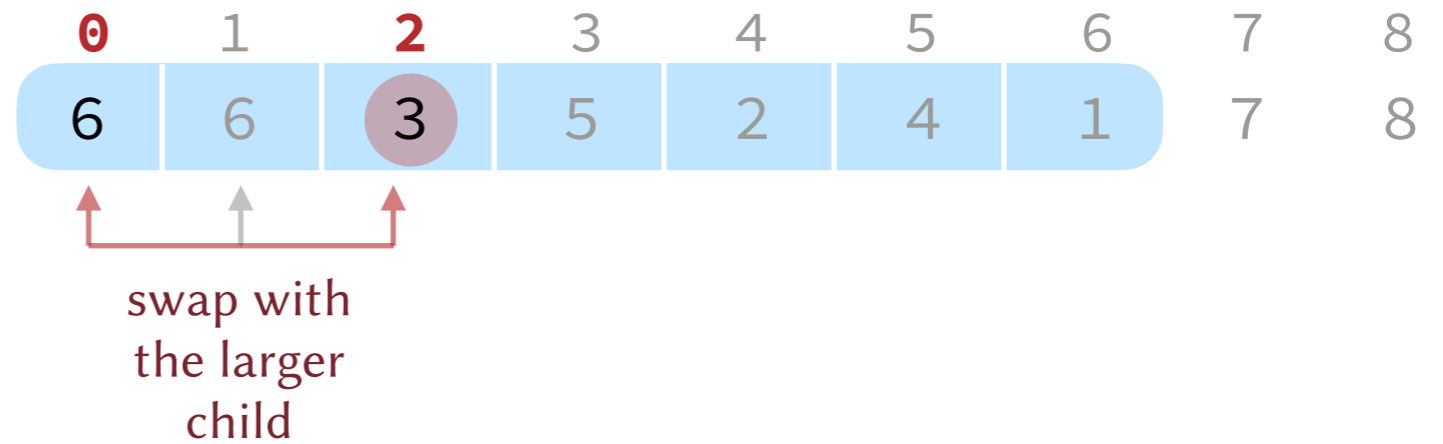
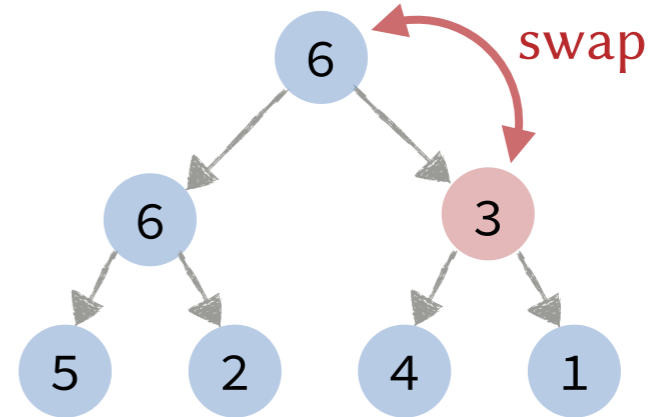
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

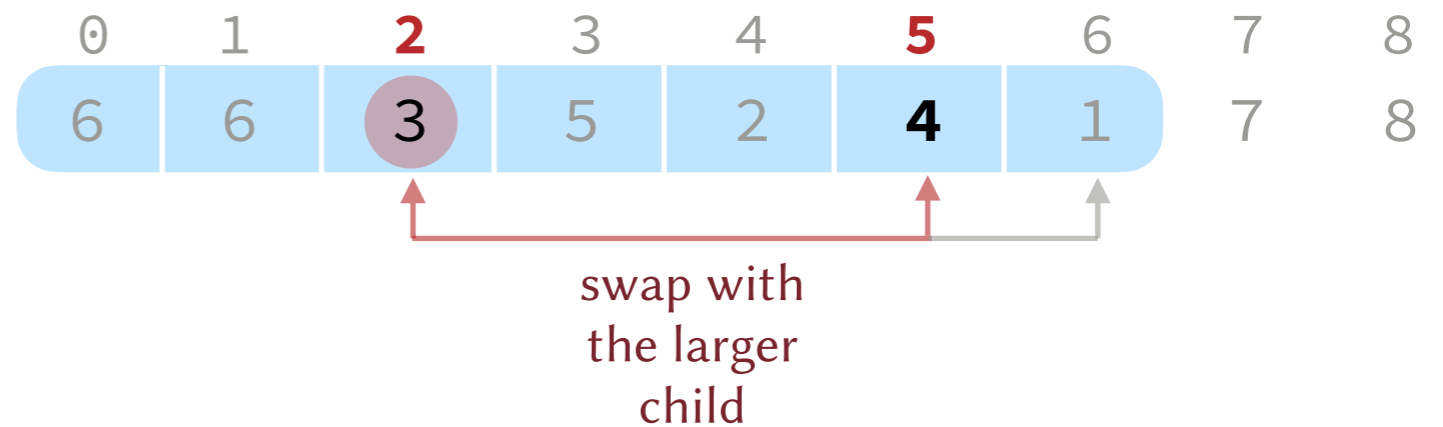
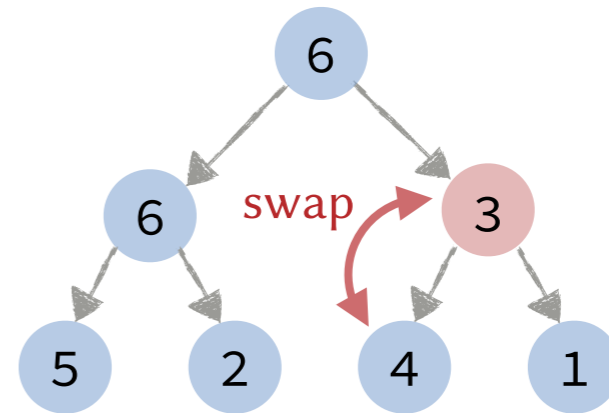
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

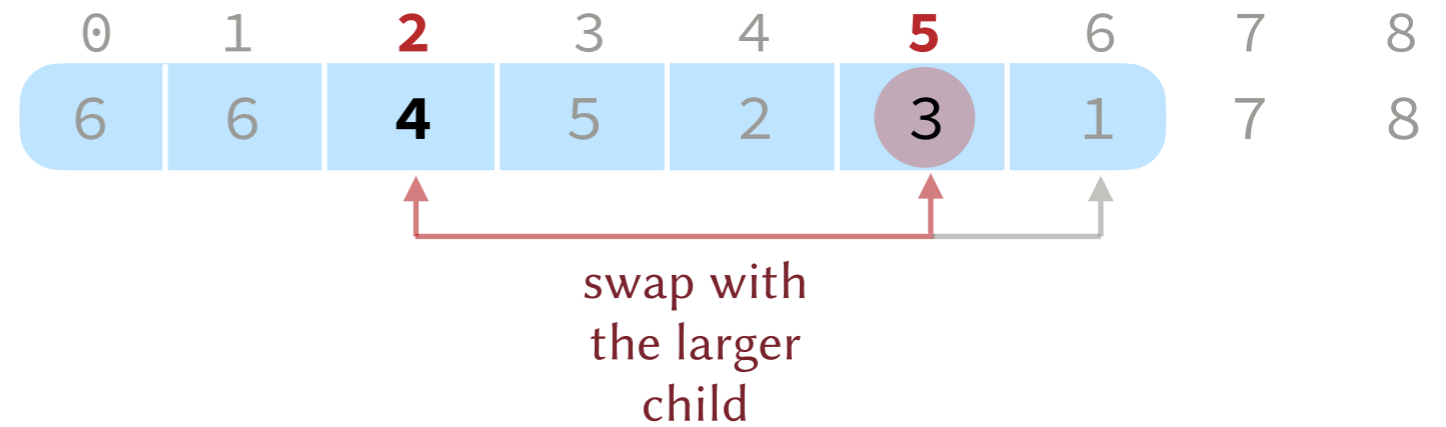
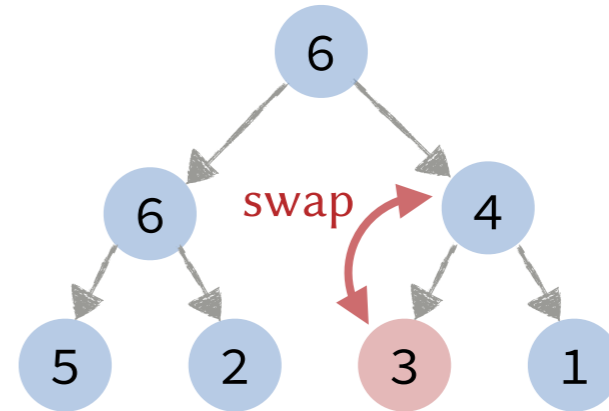
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

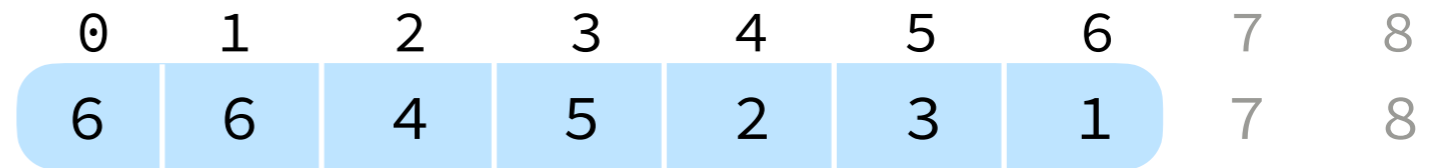
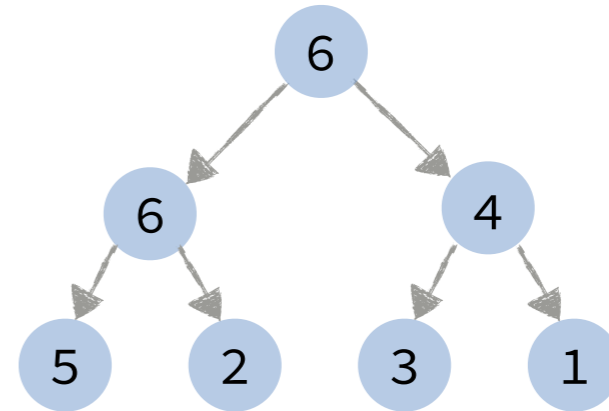
1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Binary Heaps: Deletion

Basic Plan.

1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



Running Time.

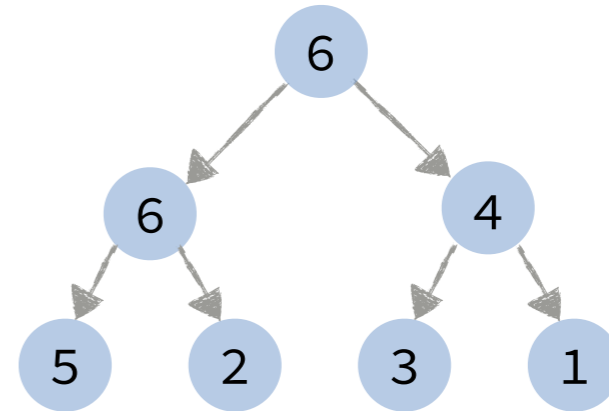
Best Case: 1 swap and 2 data compares.

Worst Case: $1 + \lfloor \log_2 n \rfloor$ swaps and $2 \lfloor \log_2 n \rfloor$ data compares.

Binary Heaps: Deletion

Basic Plan.

1. Swap the first and last elements in the heap.
2. Delete the last element.
3. Fix the heap.
swap down until the heap is fixed.



```
int remove_max(int a[],  
               int& size) {  
    swap(a[size-1], a[0]);  
    size--;  
    sink(a, 0, size);  
    return a[size];  
}
```

```
void sink(int a[], int i, int size) {  
    while (LEFT(i) < size) {  
        int k = LEFT(i);  
        if (RIGHT(i) < size)  
            if (a[k] < a[RIGHT(i)])  
                k = RIGHT(i);  
        if (a[i] < a[k])  
            swap(a[i], a[k]);  
            i = k;  
        else break;  
    }  
}
```

optional

A *Better* Selection Sort ??

```
void selection_sort(T a[], int n)
```

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
    MaxHeap<T> heap;
```

```
    for (int i = 0; i < n; i++)
```

```
        heap.insert(a[i]);
```

```
    for (int i = n-1; i >= 0; i--) {
```

```
        a[i] = heap.get_max();
```

```
        heap.remove_max();
```

```
    }
```

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
    MaxHeap<T> heap;
```

```
    for (int i = 0; i < n; i++)  
        heap.insert(a[i]);
```

```
    for (int i = n-1; i >= 0; i--) {  
        a[i] = heap.get_max();  
        heap.remove_max();  
    }
```

1

insert all the array elements
into a max-heap

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
MaxHeap<T> heap;
```

```
for (int i = 0; i < n; i++)  
    heap.insert(a[i]);
```

```
for (int i = n-1; i >= 0; i--) {  
    a[i] = heap.get_max();  
    heap.remove_max();  
}
```

1 insert all the array elements into a max-heap

2 copy all the elements back from the heap to the array (in order)

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
MaxHeap<T> heap;
```

```
for (int i = 0; i < n; i++)  
    heap.insert(a[i]);
```

```
for (int i = n-1; i >= 0; i--) {  
    a[i] = heap.get_max();  
    heap.remove_max();  
}
```

1 insert all the array elements into a max-heap

2 copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!)$

↑
insert the second
element into the a
heap of size 1

↑
insert the last
element into a
heap of size $n-1$

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
MaxHeap<T> heap;
```

```
for (int i = 0; i < n; i++)  
    heap.insert(a[i]);
```

```
for (int i = n-1; i >= 0; i--) {  
    a[i] = heap.get_max();  
    heap.remove_max();  
}
```

1 insert all the array elements into a max-heap

2 copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!) = O(n \log n)$
- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1))$
 $\leq 2 \times \log_2(n!)$

A Better Selection Sort ??

```
void use_heap_to_sort(T a[], int n)
```

```
MaxHeap<T> heap;
```

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 $\leq 2 \times \log_2(n!) = O(n \log n)$

swapping down the heap requires
2 compares to identify the larger child!

A Better Selection Sort ??

```
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Running Time. (number of compares in the worst case)

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- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1))$
 $\leq 2 \times \log_2(n!) = O(n \log n)$
- Total. $O(n \log n)$

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