

CS11313 - Spring 2022

Design & Analysis *of* Algorithms

Heapsort

Ibrahim Albluwi

Selection Sort?

```
SELECTION-SORT(array)
```

```
for  $i=n-1 \rightarrow 1$ :
```

```
    max = FIND-MAX(array, i, 0)
```

```
    swap(array[i], array[max])
```

scan this portion of
the array *linearly*.

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HEAP-SORT(array)

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prepare(array)  
for i=n-1  $\longrightarrow$  1:  
  max = FIND-MAX(array, i, 0)  
  insert array[max] into array[i])
```

rearrange the elements so that *finding the max* is easy!

find the maximum element *quickly*!

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Roadmap.

1. Review Max-Priority Queues and Heaps.
2. Learn about Heapsort.

Max-Priority Queue (Abstract Data Type)

Abstract Data Type (ADT): A specification of the possible operations on a set of values (independent of the implementation).

Examples.

ADT	Goal	operations
Stack	Remove the item most-recently added	PUSH, POP
Queue	Remove the item least-recently added	ENQUEUE, DEQUEUE

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Stack	Remove the item most-recently added	PUSH, POP	Singly-Linked List Doubly-Linked List Array-List
Queue	Remove the item least-recently added	ENQUEUE, DEQUEUE	Binary Search Tree Hash Table Linked-List, Array-List
Set	Search in a group of unique items	INSERT, DELETE, CONTAINS	Binary Search Tree Hash Table Linked-List, Array-List

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Max-PQ	Remove the largest item	INSERT, MAX, DEL-MAX	?

Max-Priority Queue (Abstract Data Type)

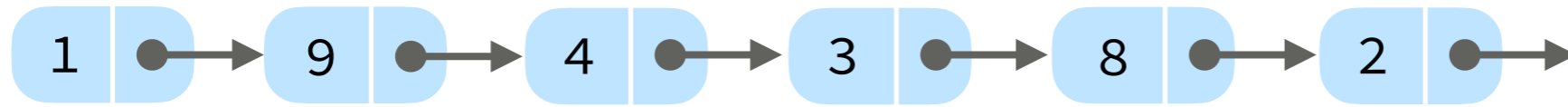
Unordered List:



Max-Priority Queue (Abstract Data Type)

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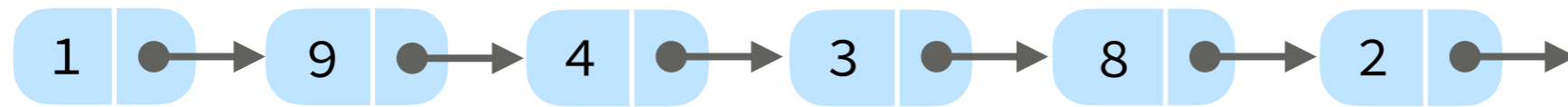
- **insert:** $\Theta(1)$ (insert to the end of the list; order does not matter)
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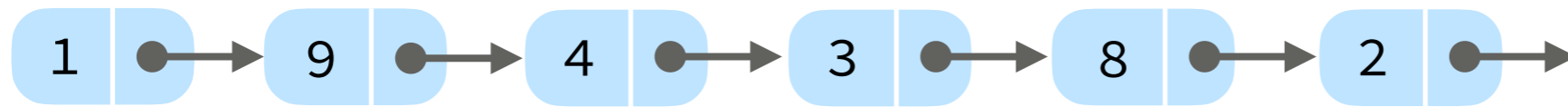
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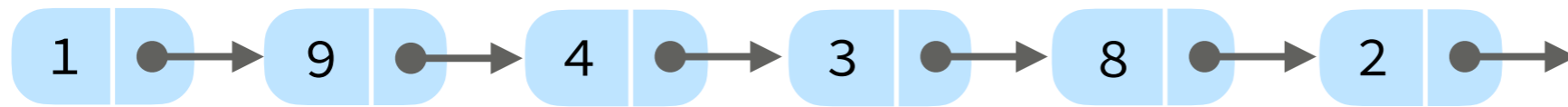
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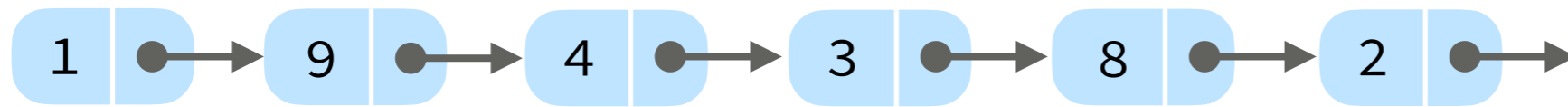
Binary Heap:

- **insert:** $O(\log n)$ (how?)
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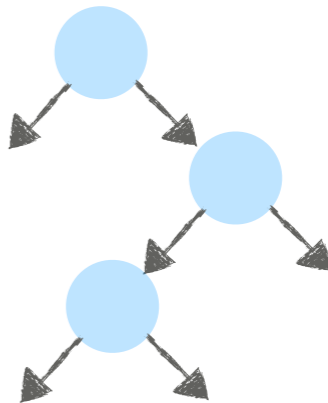
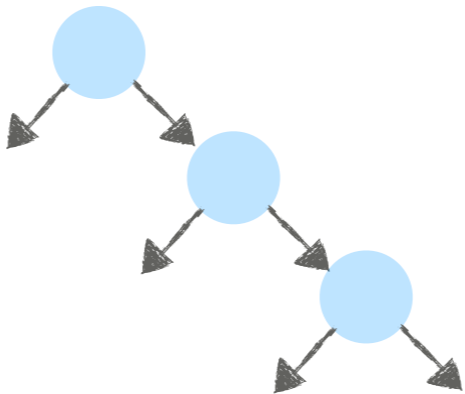
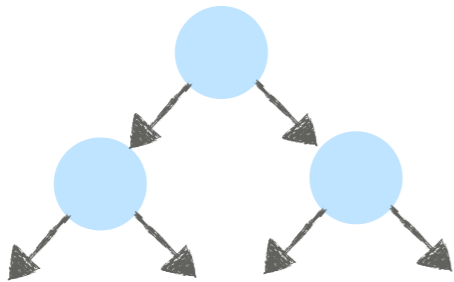
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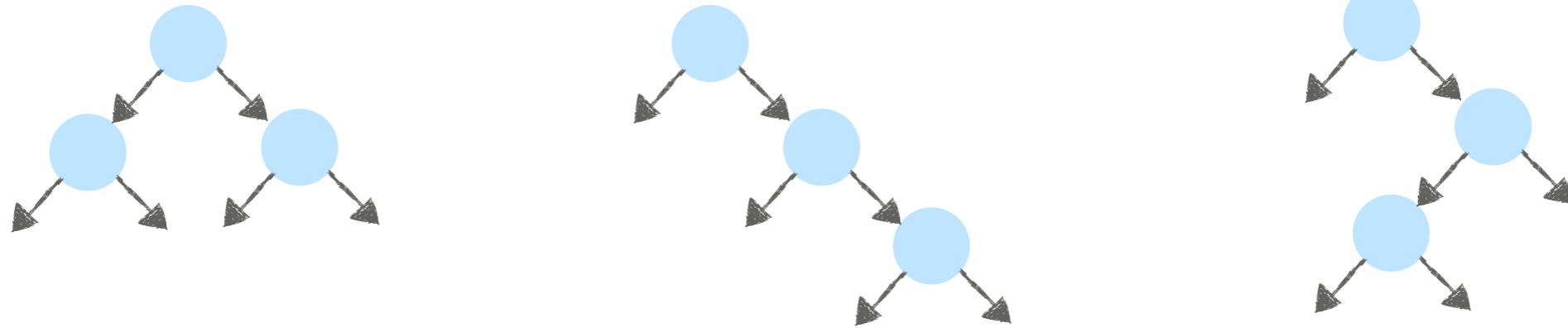
Binary Trees

Binary Tree: Empty or a node with links to left and right binary trees.



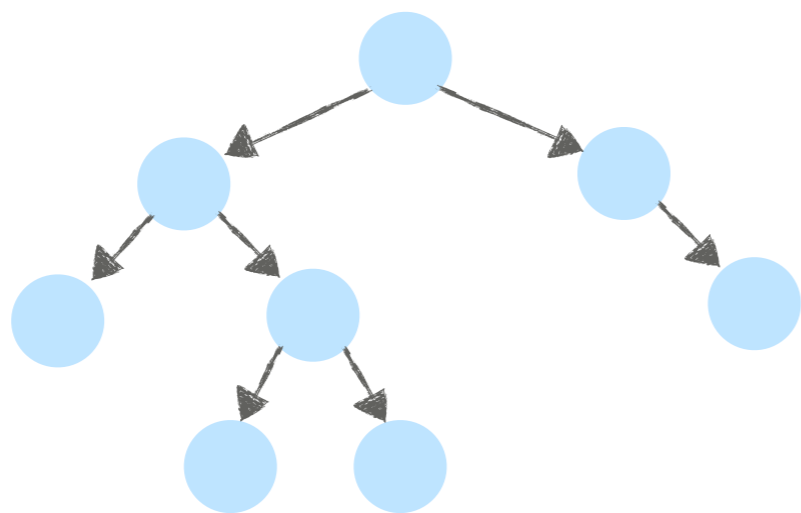
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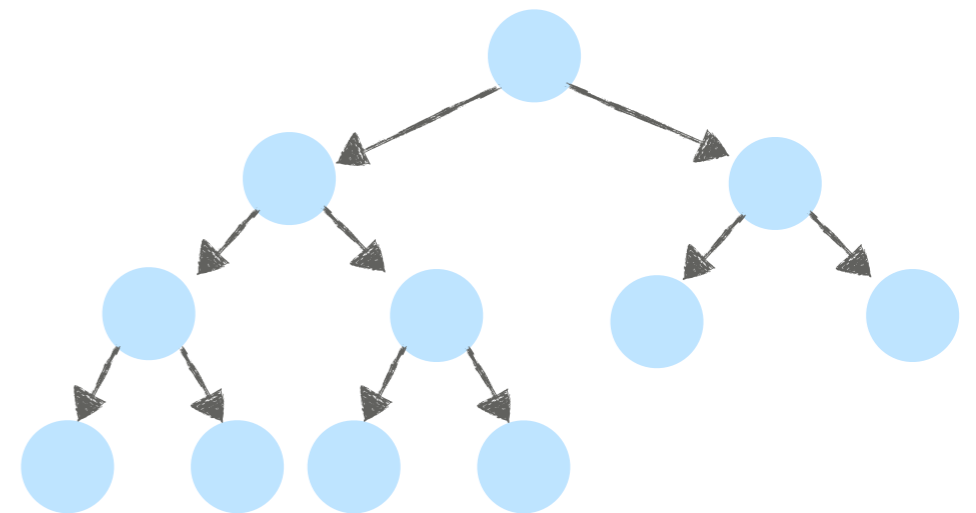


Complete Binary Tree:

- All levels are full (except possibly the last level).
- Last level is filled left-to-right.



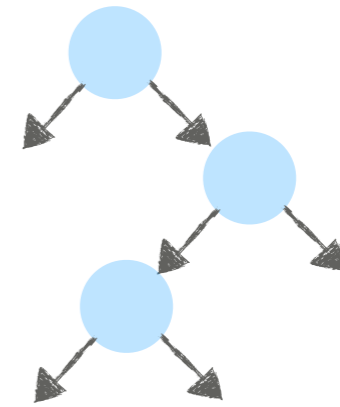
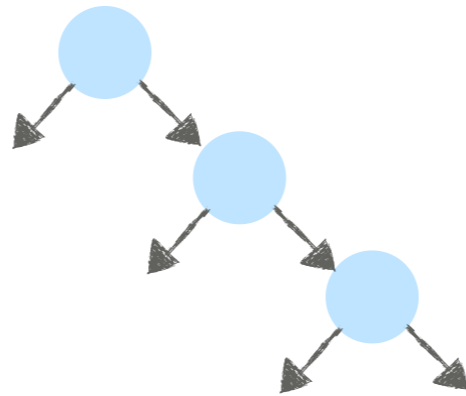
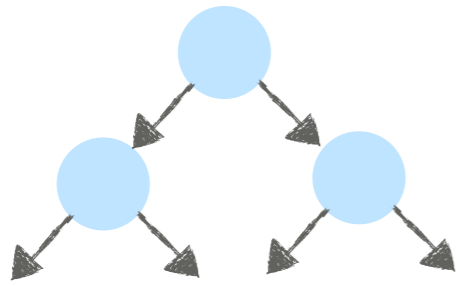
not complete



complete

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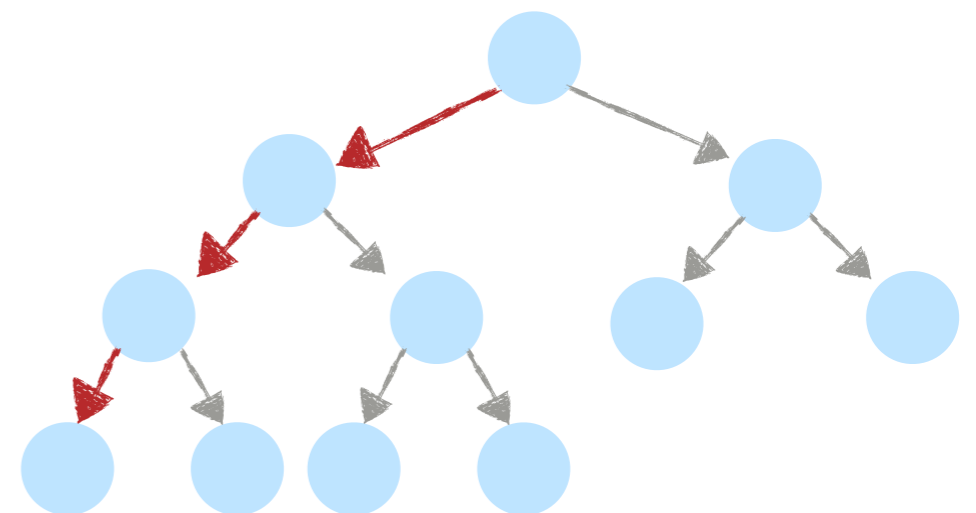


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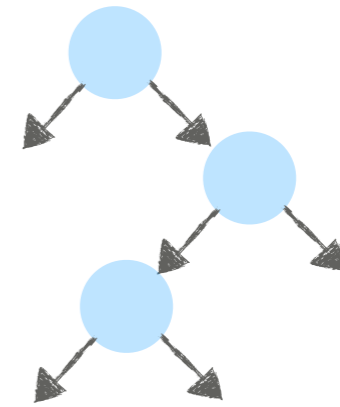
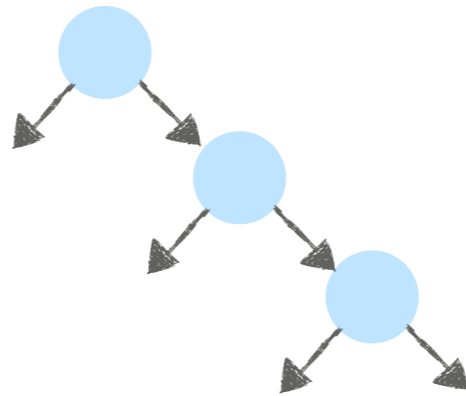
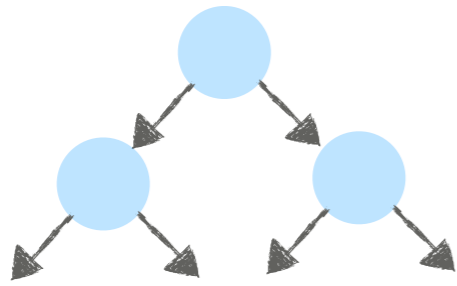
- **Height** if there are n nodes: $h = \lfloor \log_2 n \rfloor$



$$h = \lfloor \log_2 11 \rfloor = \lfloor 3.459 \rfloor = 3$$

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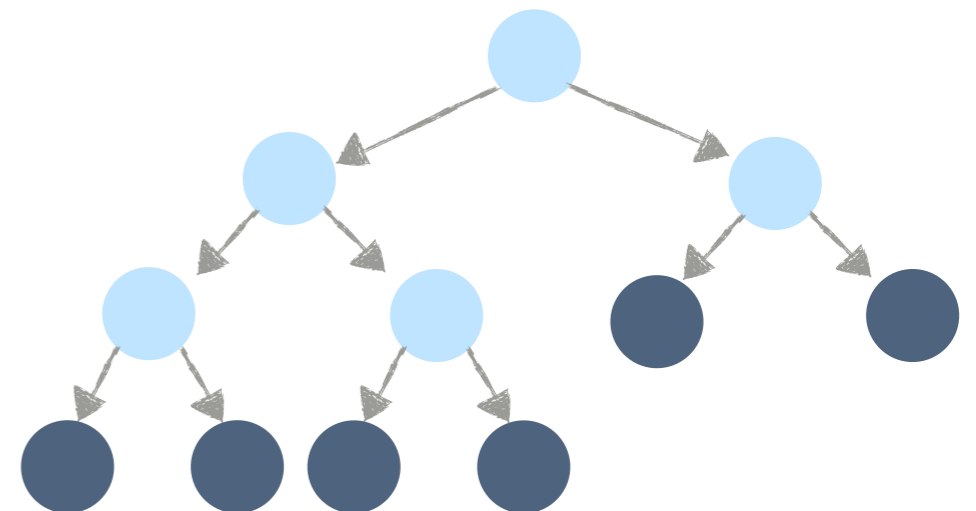


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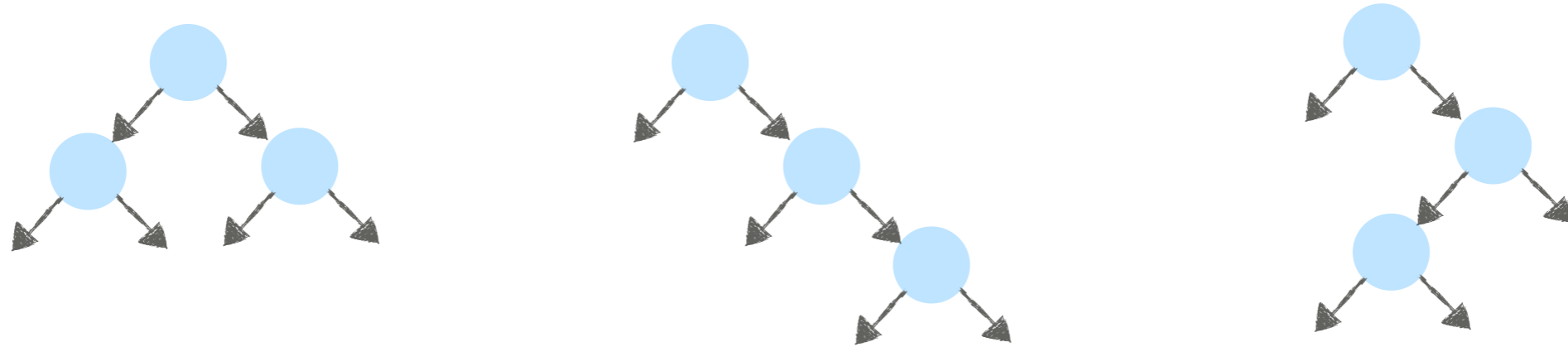
- **Height** if there are n nodes: $h = \lceil \log_2 n \rceil$
- There are $\lfloor \frac{n+1}{2} \rfloor$ leaves.



$$\left\lfloor \frac{11+1}{2} \right\rfloor = 6$$

Binary Trees

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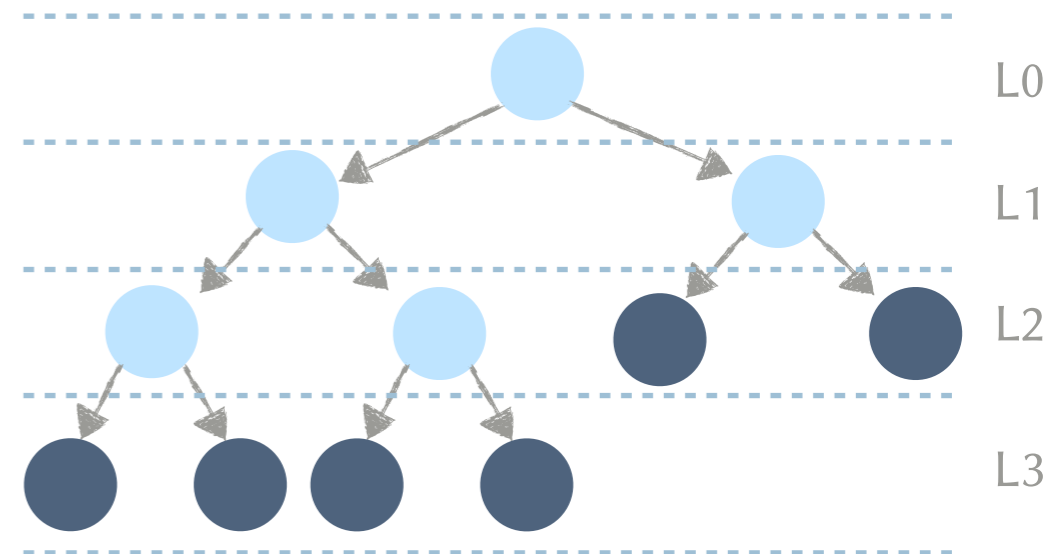


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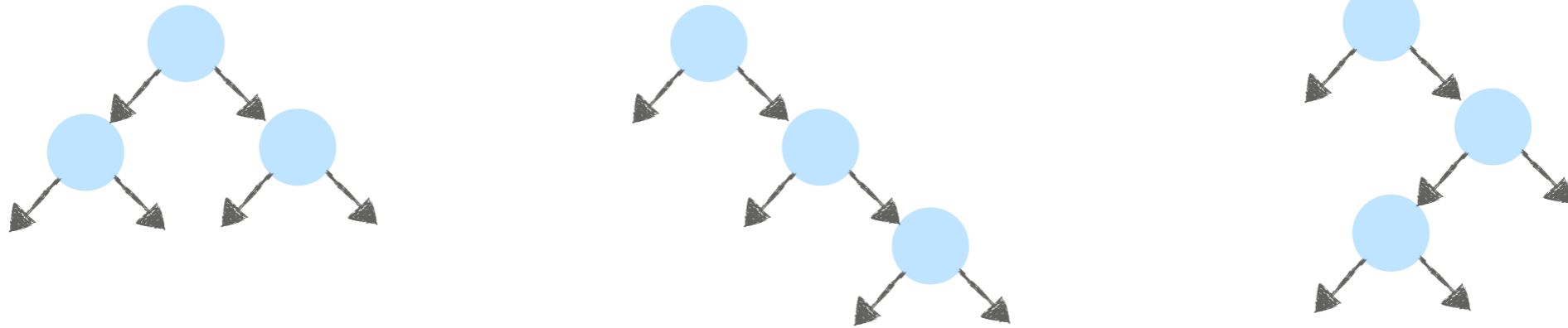
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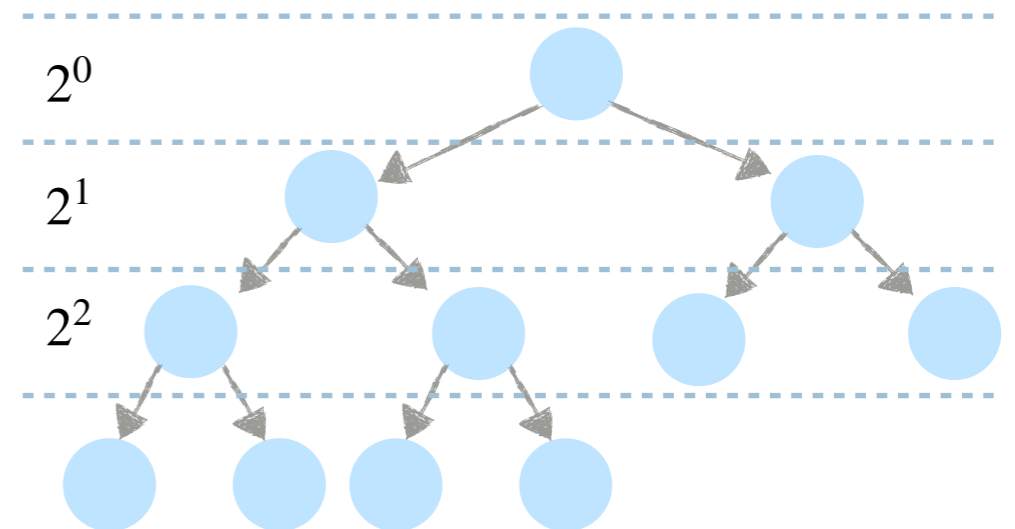


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- Number of nodes at *internal* level $i = 2^i$



Binary Heaps (Tree Representation)

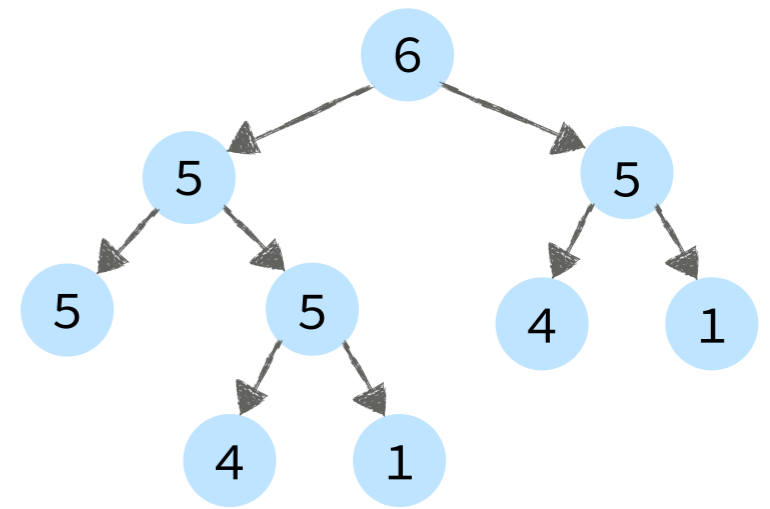
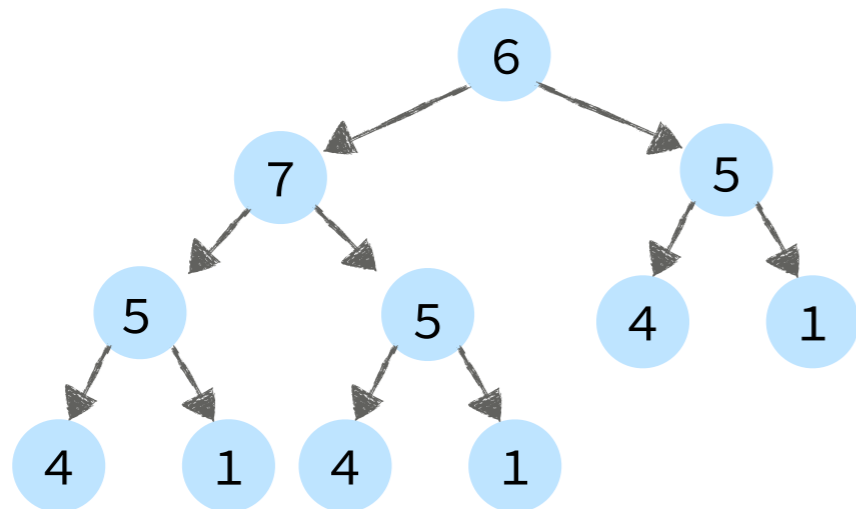
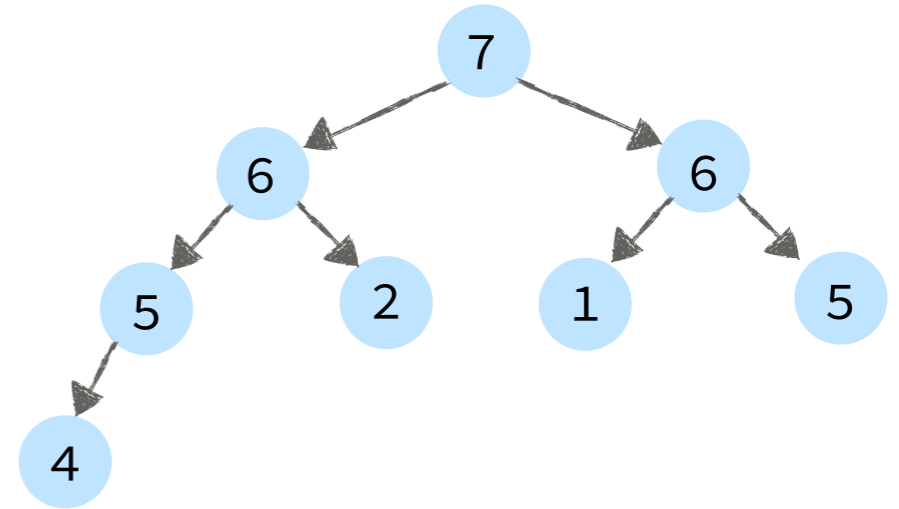
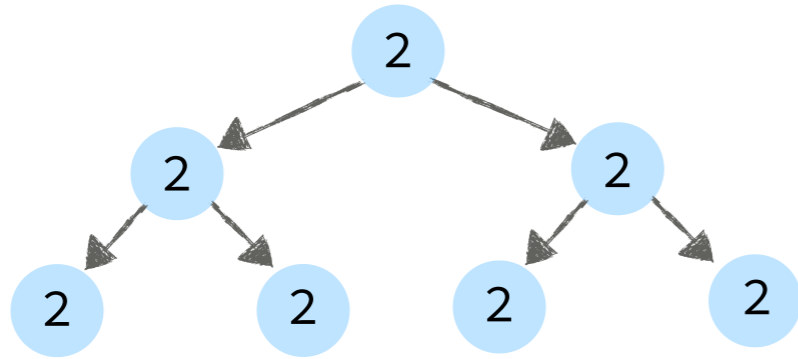
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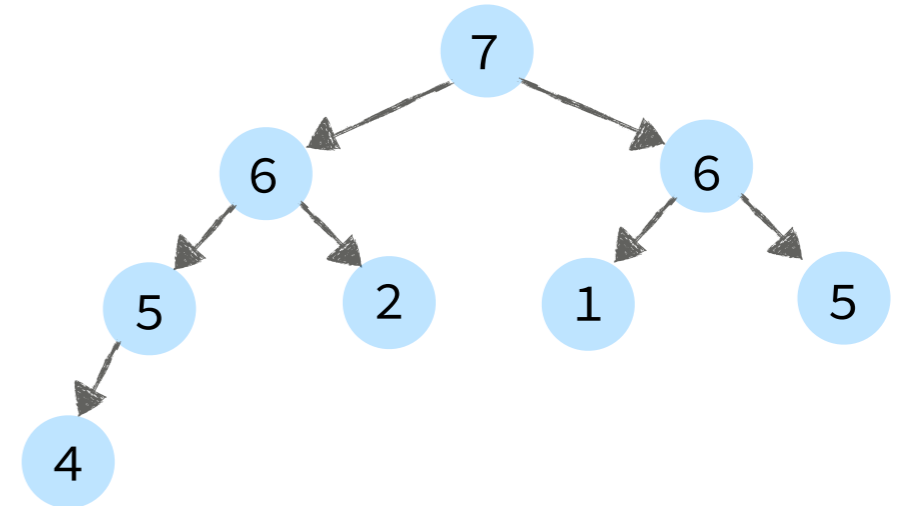
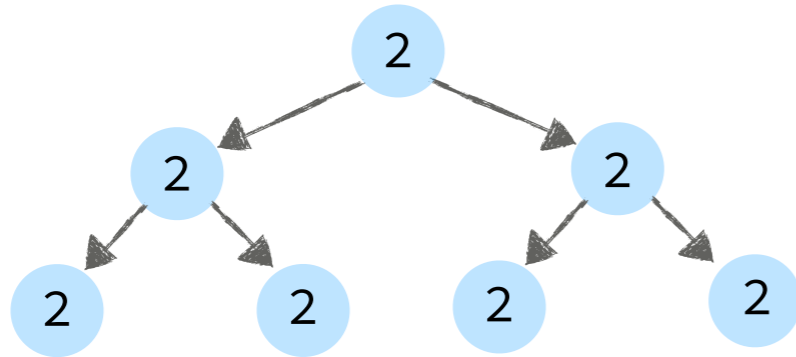


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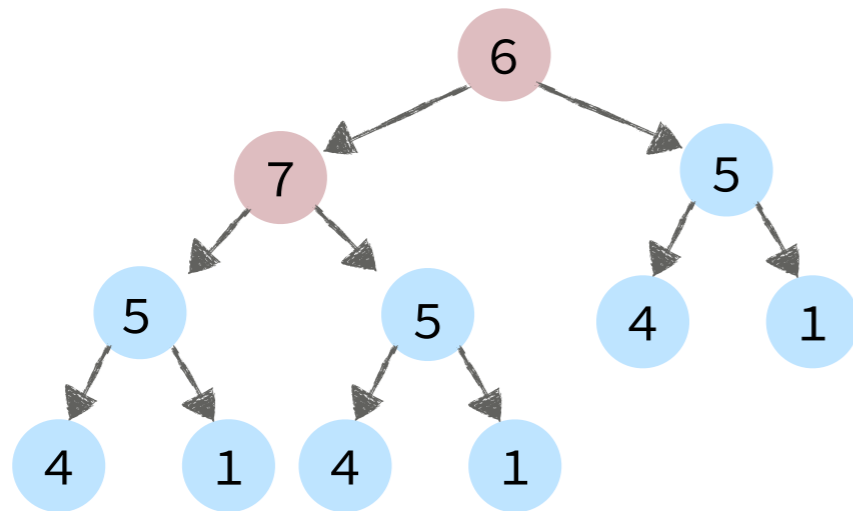
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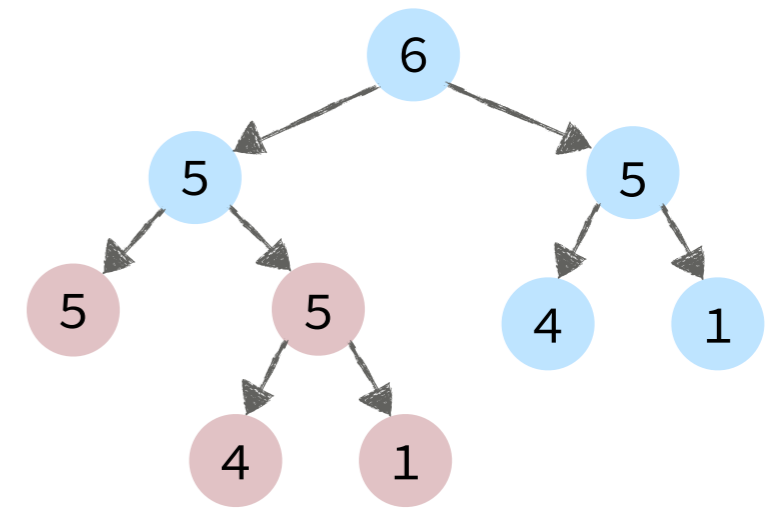
Examples:



Non-Examples:



order property violated



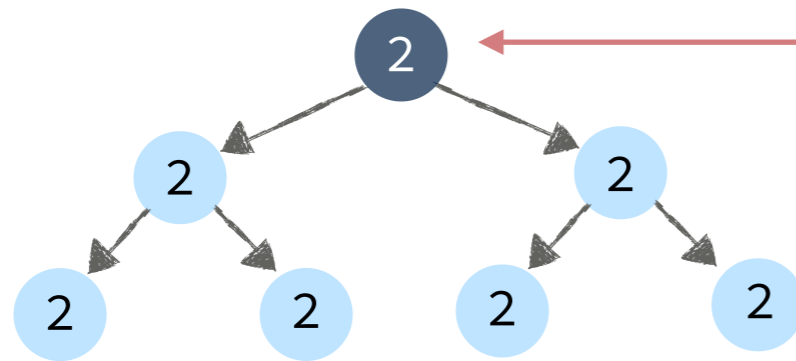
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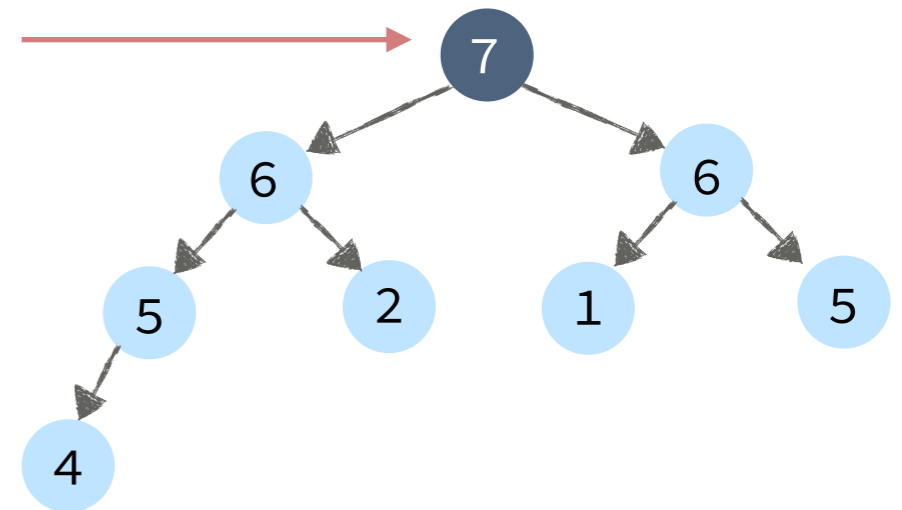
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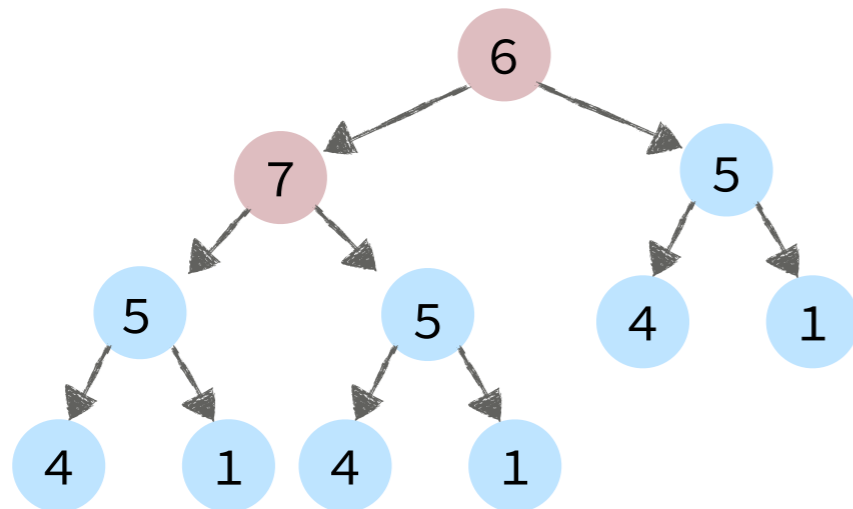
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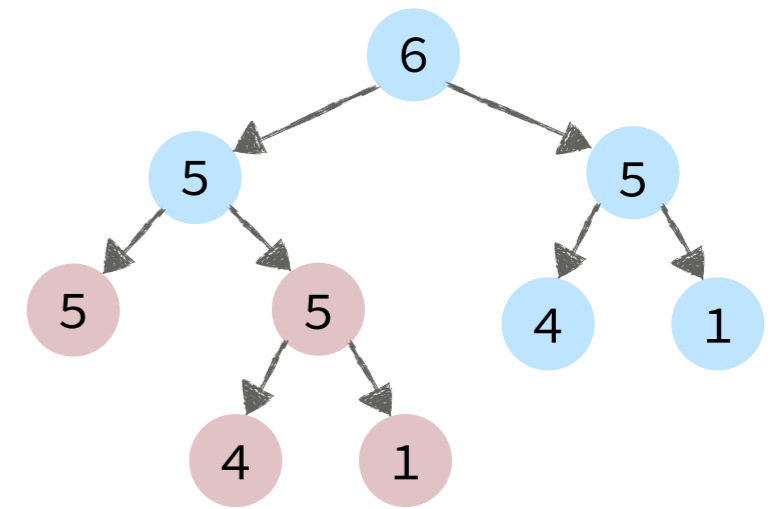
max is always
at the root



Non-Examples:



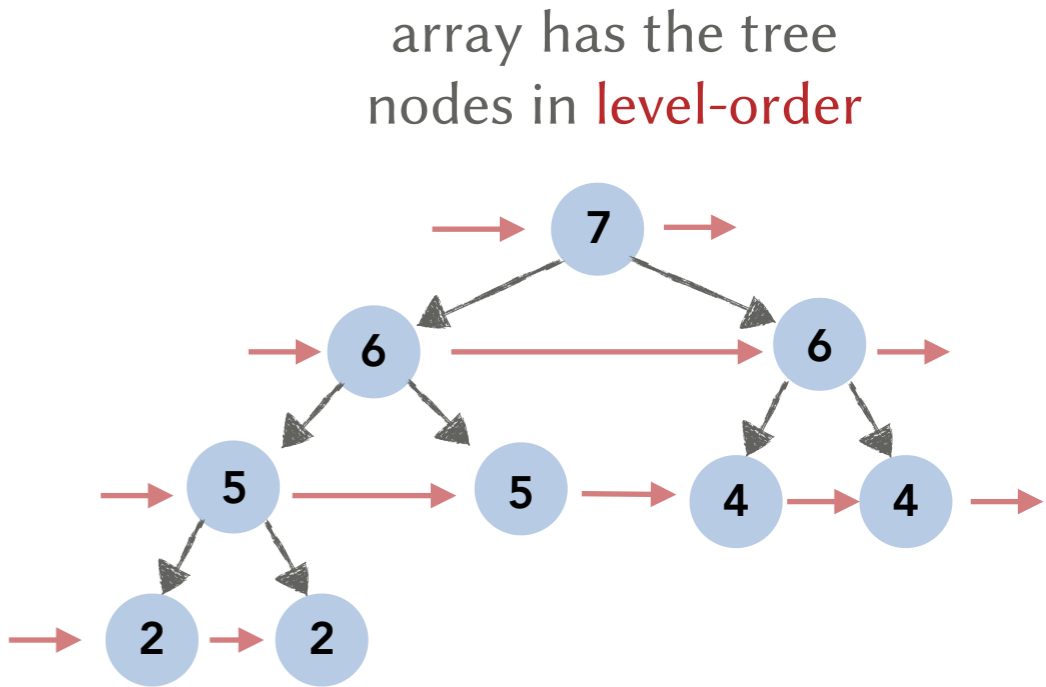
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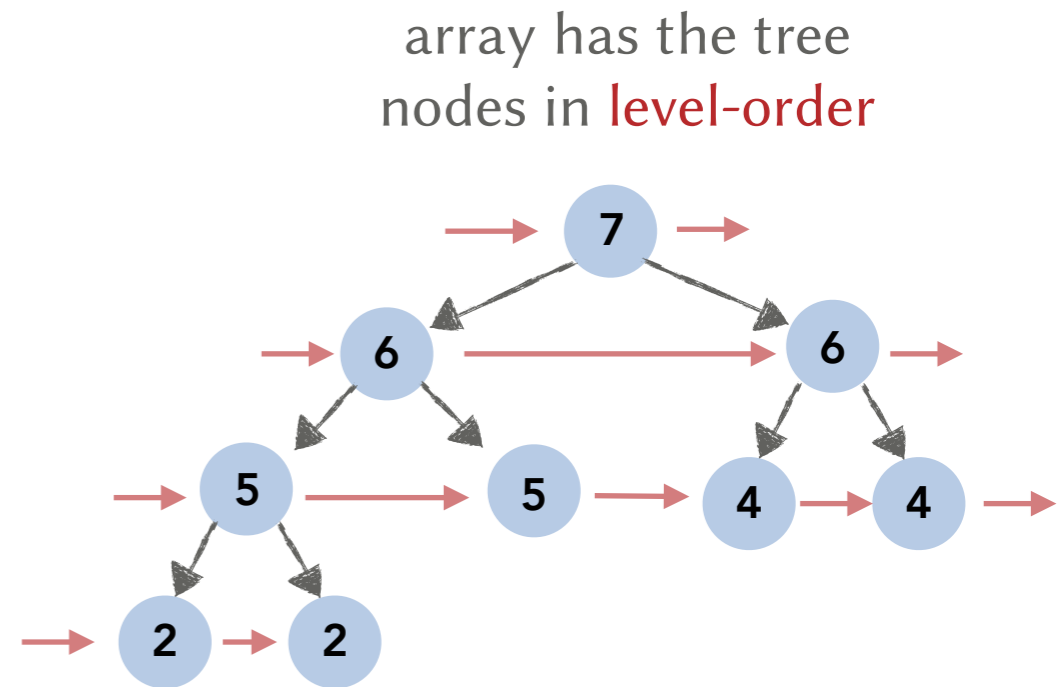
Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



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Binary Heap: (max-ordered)



Three simple functions.

LEFT(i)

return $2*i + 1$

RIGHT(i)

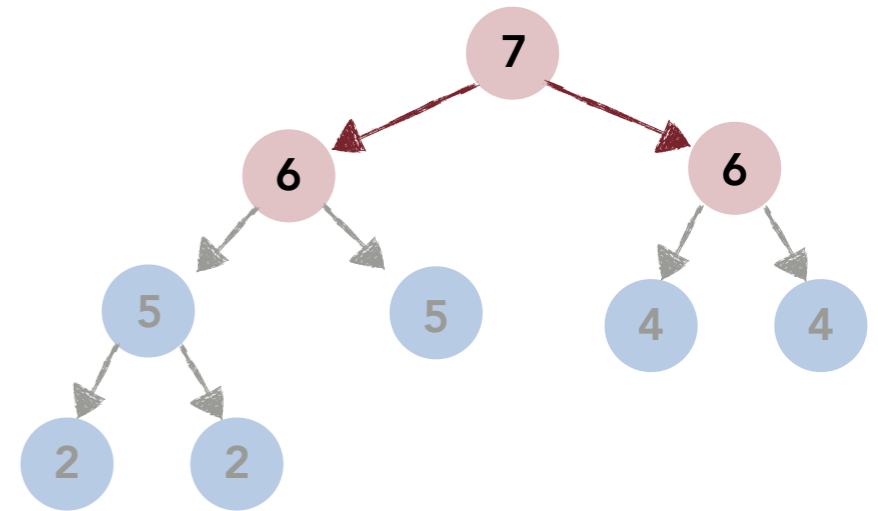
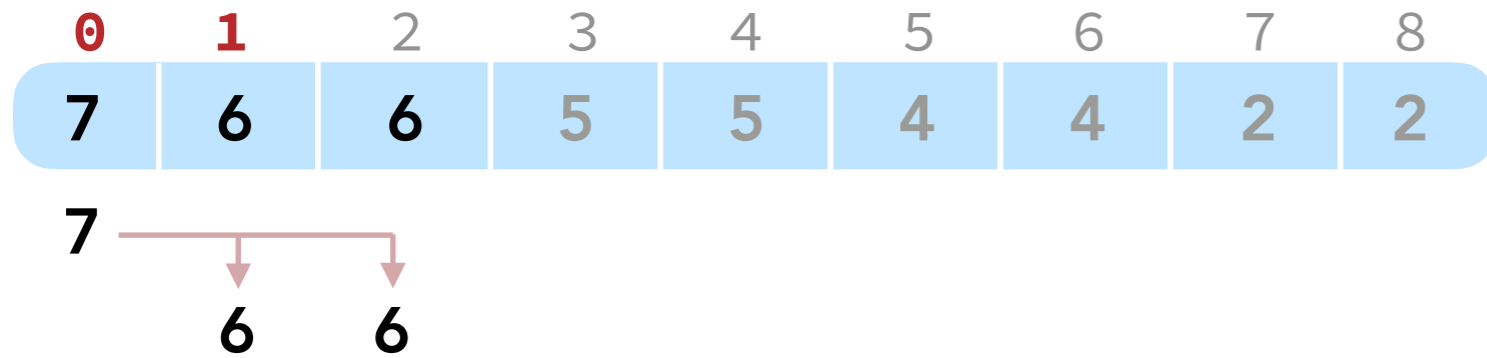
return $2*i + 2$

PARENT(i)

return $(i-1)/2$

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

LEFT(i)

return $2*i + 1$

left child is at index
 $2*0 + 1 = 1$

RIGHT(i)

return $2*i + 2$

Right child is at index
 $2*0 + 2 = 2$

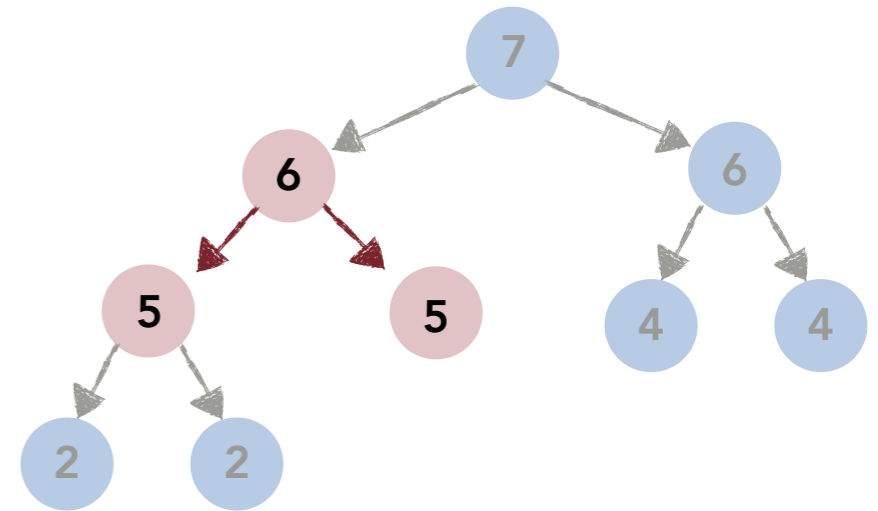
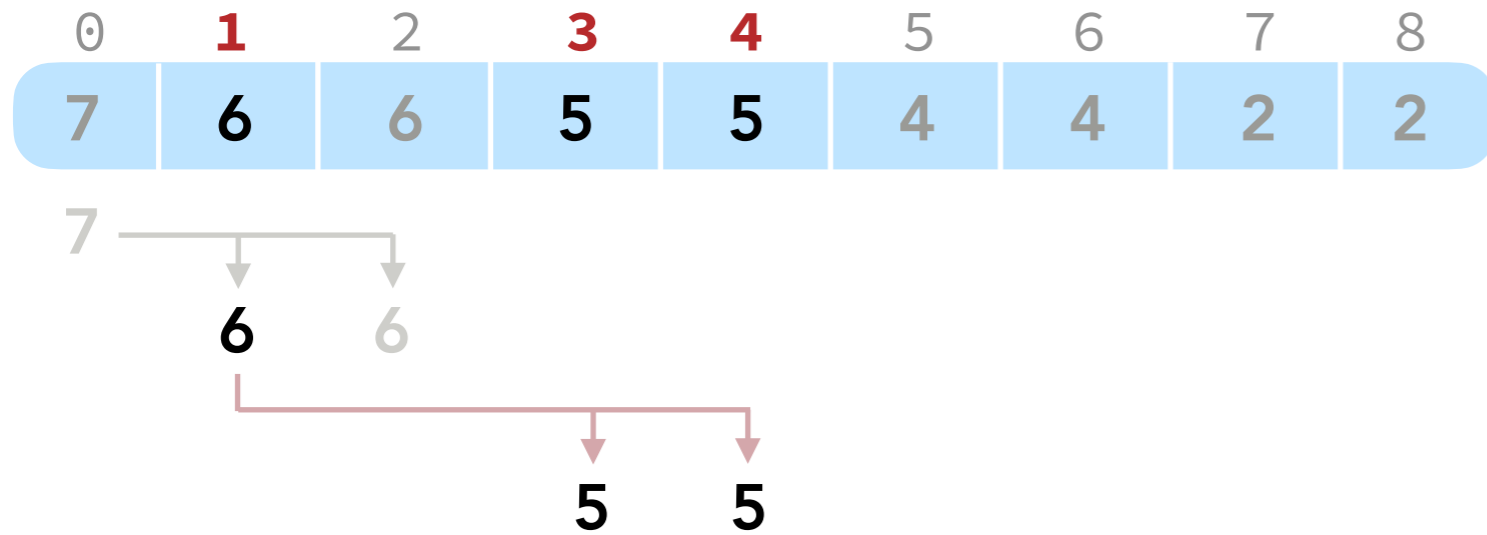
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return $(i-1)/2$

Parent of the node at 0
is negative (no parent)

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

LEFT(i)

return $2*i + 1$

left child is at index
 $2*1 + 1 = 3$

RIGHT(i)

return $2*i + 2$

Right child is at index
 $2*1 + 2 = 4$

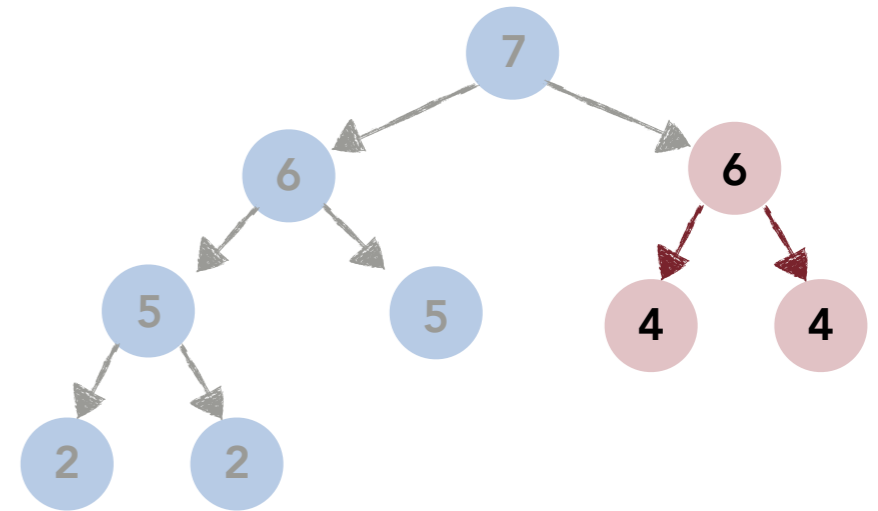
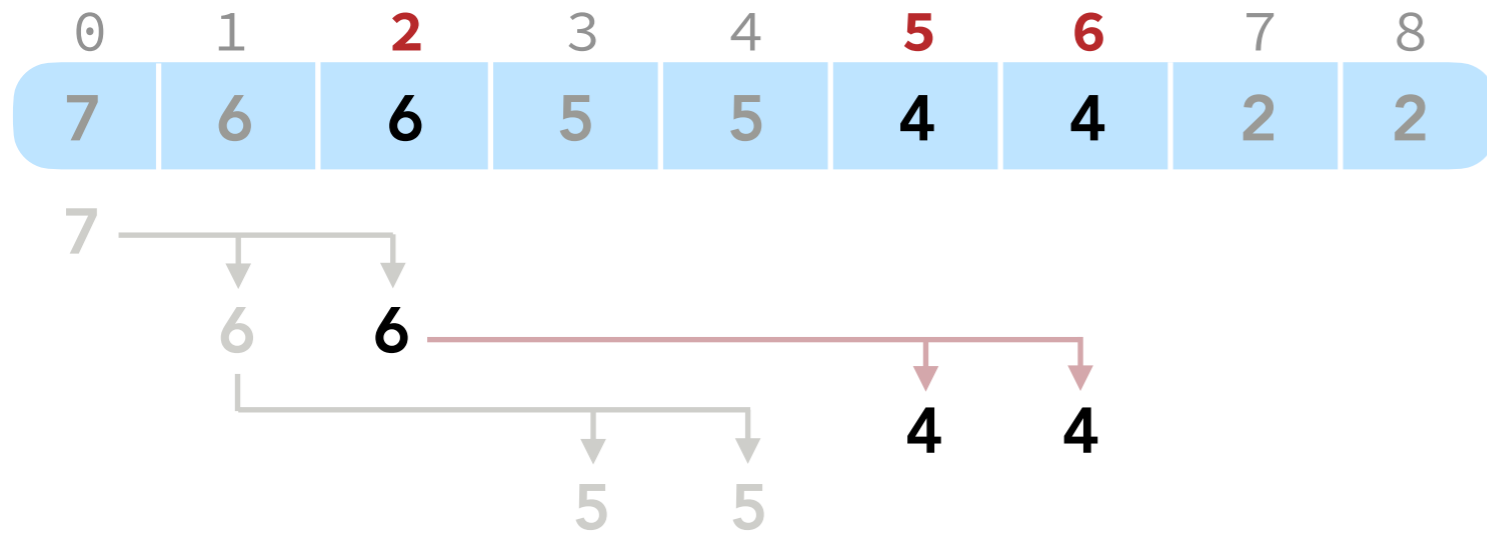
PARENT(i)

return $(i-1)/2$

Parent is at index
 $(1-1)/2 = 0$

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

LEFT(i)

return $2*i + 1$

left child is at index
 $2*2 + 1 = 5$

RIGHT(i)

return $2*i + 2$

Right child is at index
 $2*2 + 2 = 6$

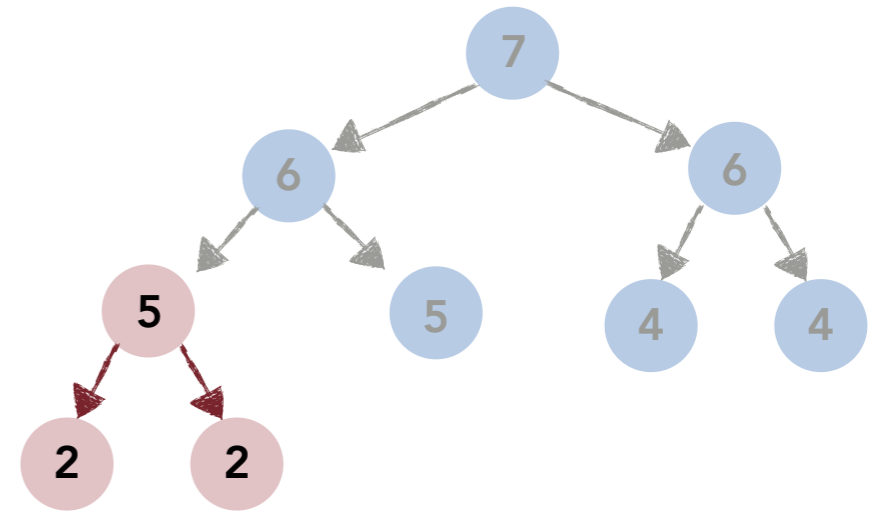
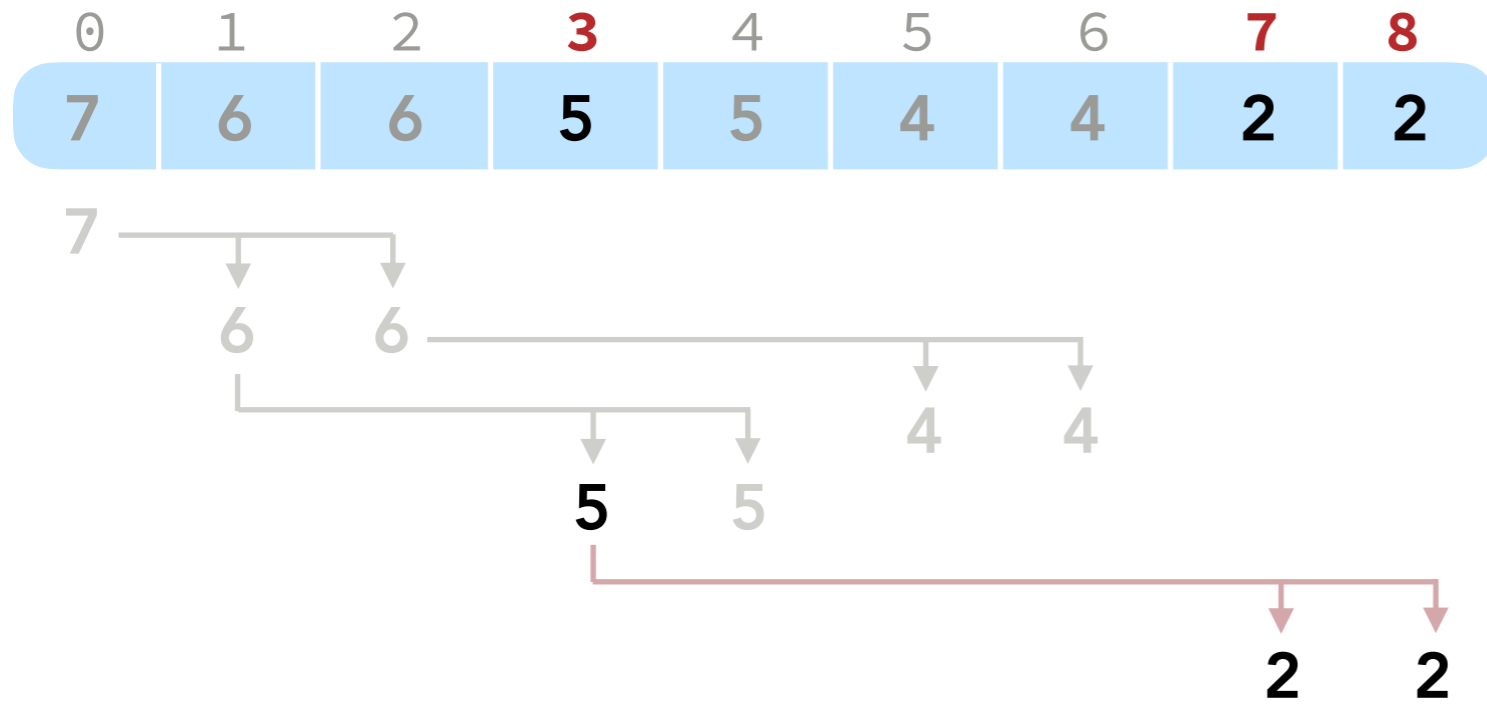
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return $(i-1)/2$

Parent is at index
 $(2-1)/2 = 0$

Binary Heaps (Array Representation)

Binary Heap: (max-ordered)



Three simple functions.

LEFT(i)

return $2*i + 1$

left child is at index
 $2*3 + 1 = 7$

RIGHT(i)

return $2*i + 2$

Right child is at index
 $2*3 + 2 = 8$

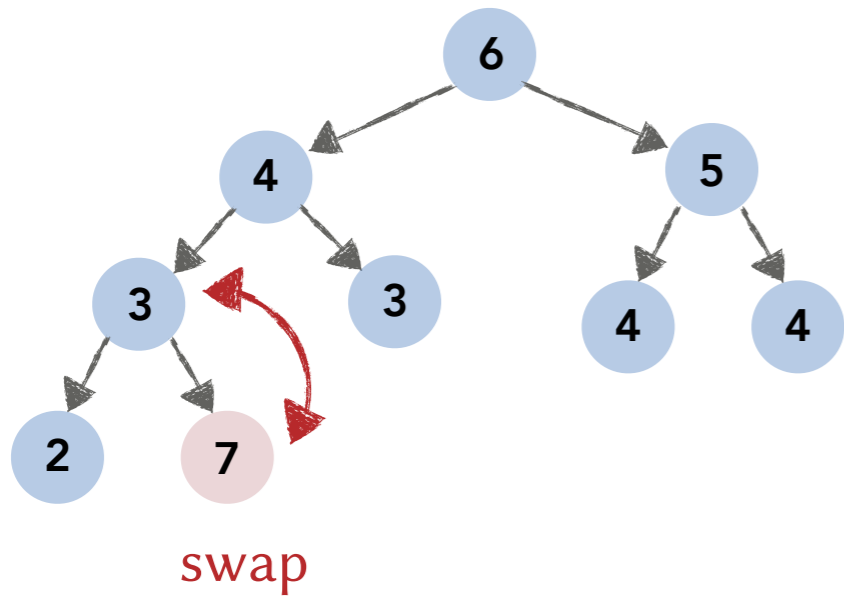
PARENT(i)

return $(i-1)/2$

Parent is at index
 $(3-1)/2 = 1$

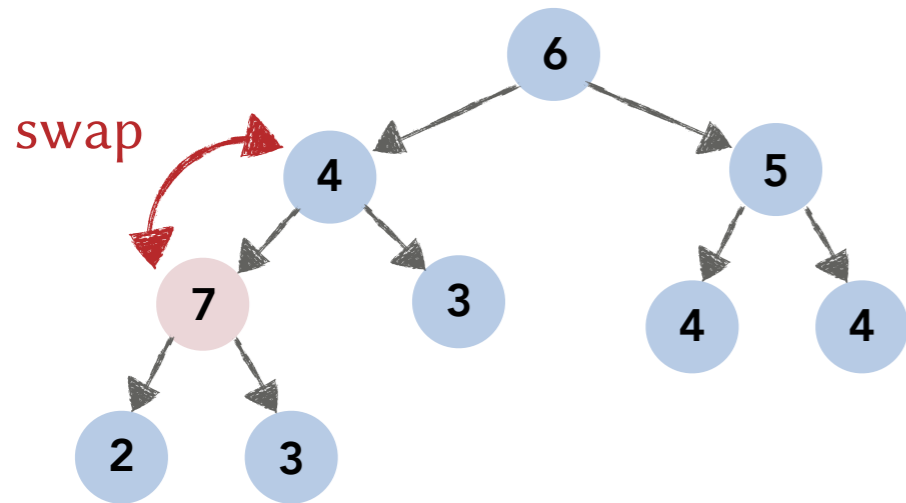
Fixing a *Locally Broken Heap*

1. If an item becomes **larger** than its parent, push it **up** the tree to maintain the heap order property.



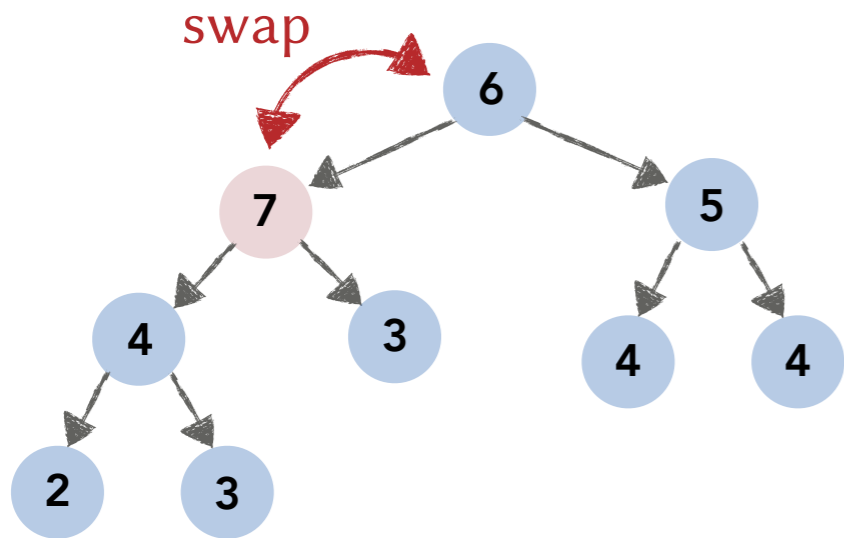
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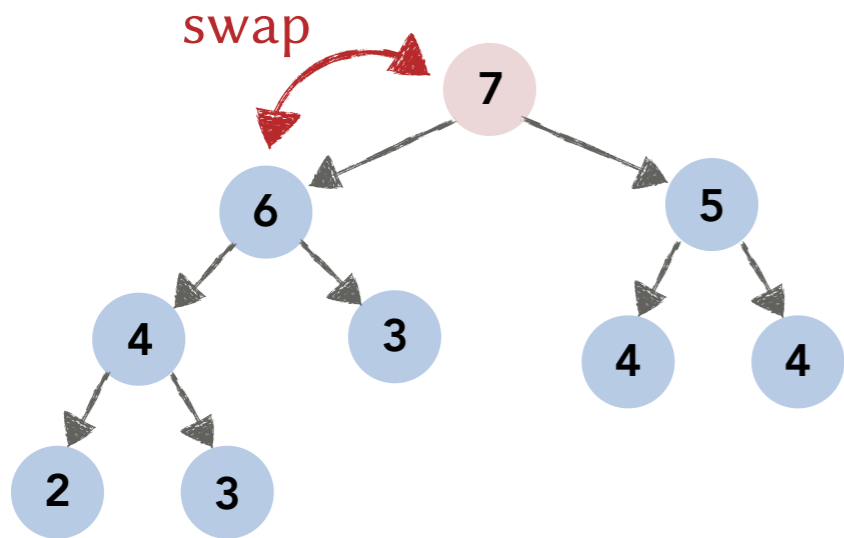
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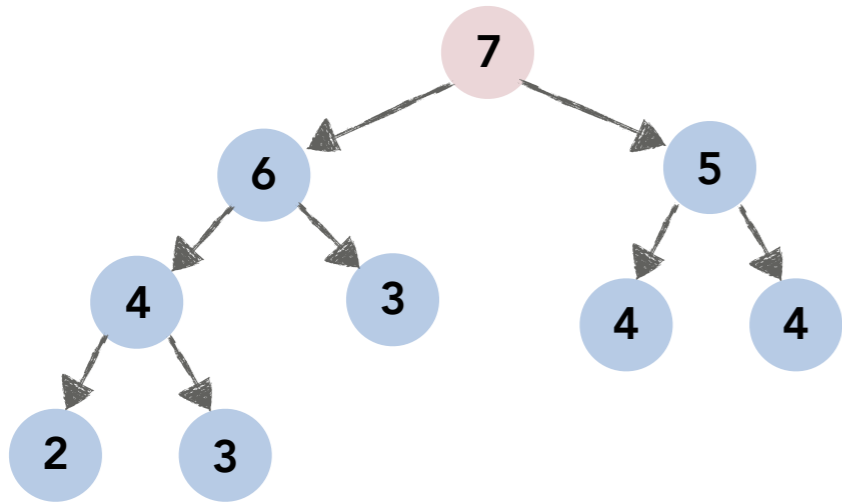
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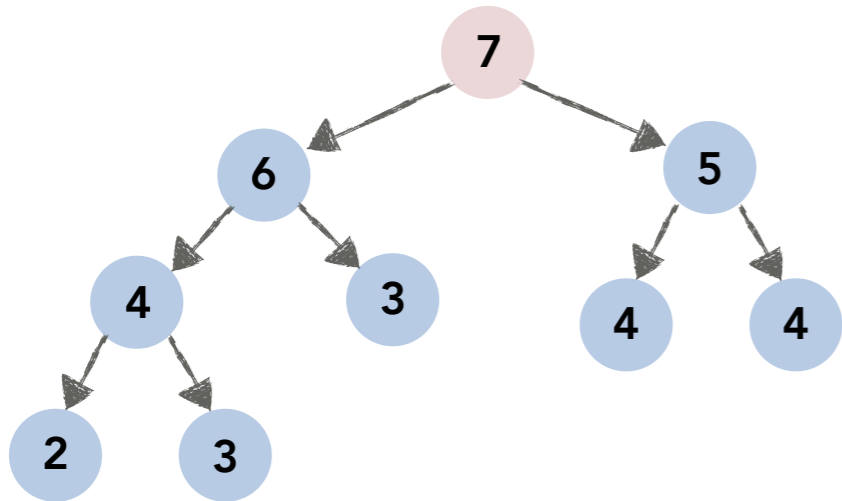
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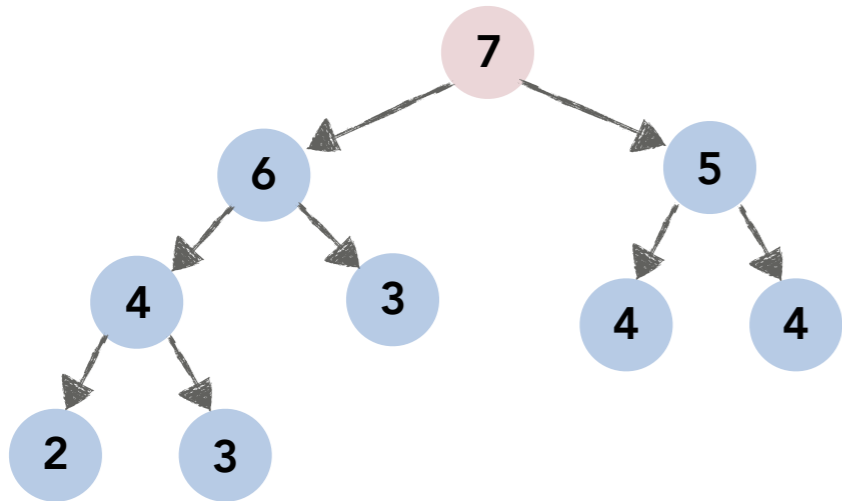
SWIM(a[], i, size)



also called `SiftUp()`
(not `shif tup`) on wikipedia

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SWIM(a[], i, size)
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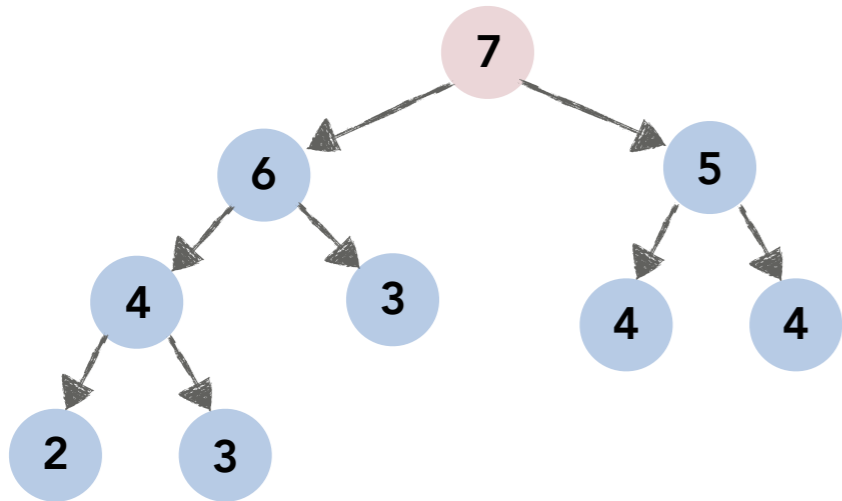
```
while (i > 0 and a[i] > a[PARENT(i)]):
```

↑
the element
is not the root

↑
the element is
greater than its
parent

Fixing a *Locally* Broken Heap

1. If an item becomes **larger** than its parent, push it **up** the tree to maintain the heap order property.



```
SWIM(a[], i, size)
```

```
while (i > 0 and a[i] > a[PARENT(i)]):
```

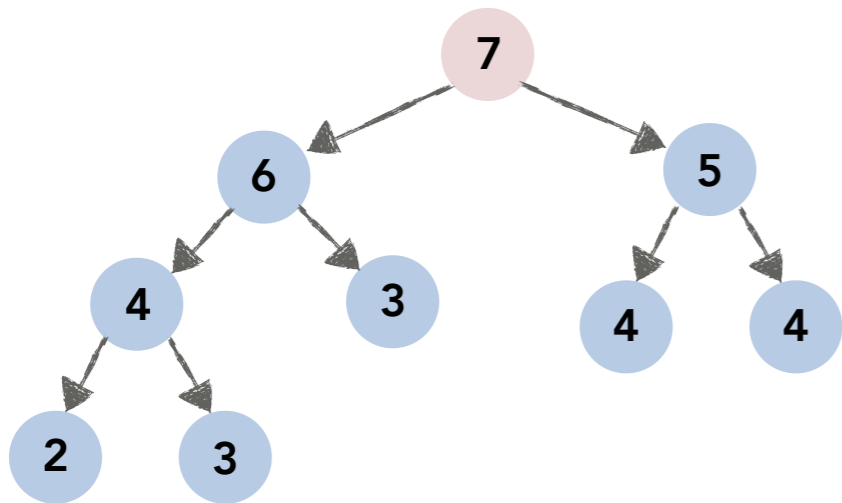
```
    swap(a[i], a[PARENT(i)])
```

```
    i = PARENT(i)
```

↑
swap values with the parent
and move to the parent for
the next iteration

Fixing a *Locally* Broken Heap

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```
SWIM(a[], i, size)
```

```
while (i > 0 and a[i] > a[PARENT(i)]):  
    swap(a[i], a[PARENT(i)])  
    i = PARENT(i)
```

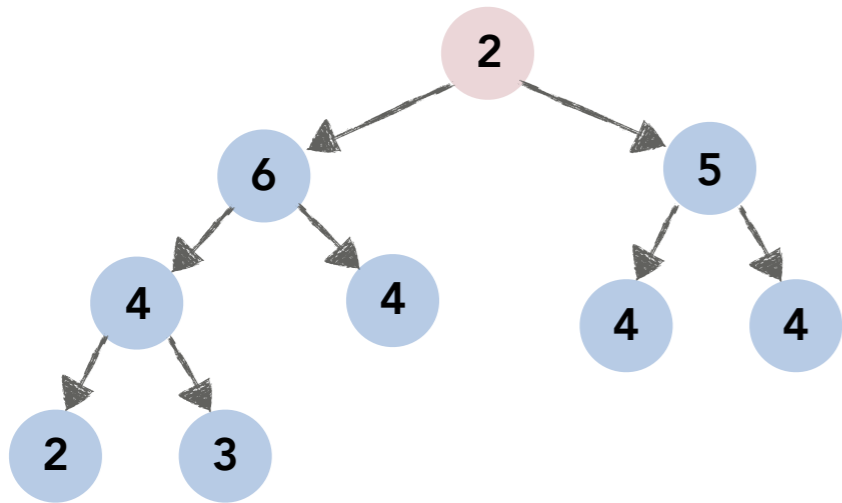


Running Time. $O(\log n)$

1 swap and 1 compare per iteration.
The number of iterations is bounded
by the tree height.

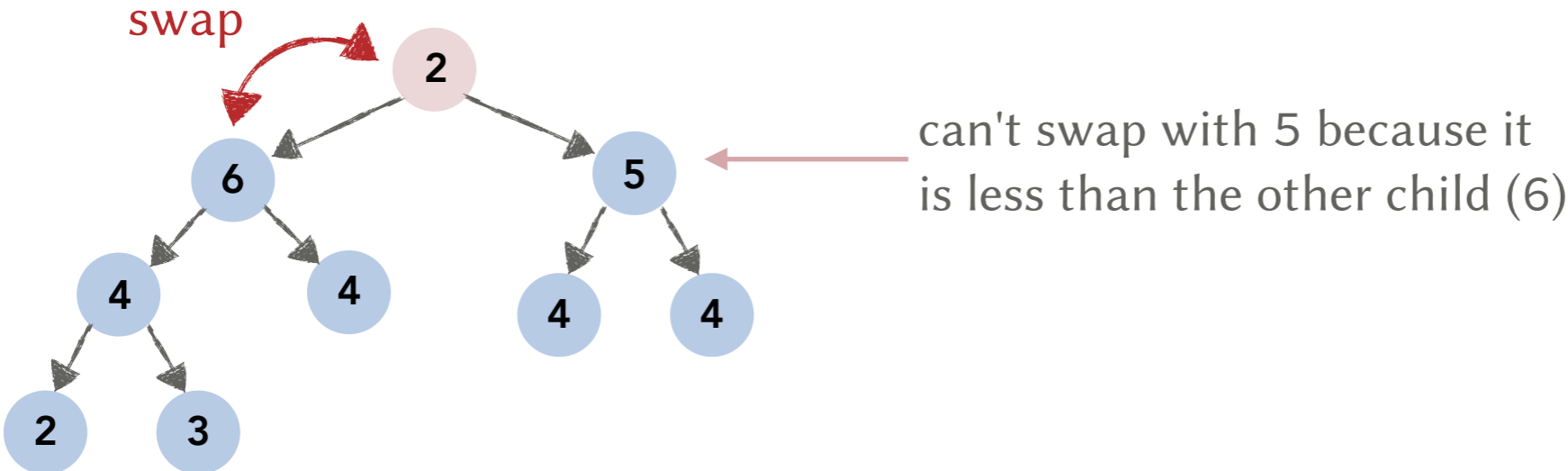
Fixing a *Locally Broken Heap*

2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



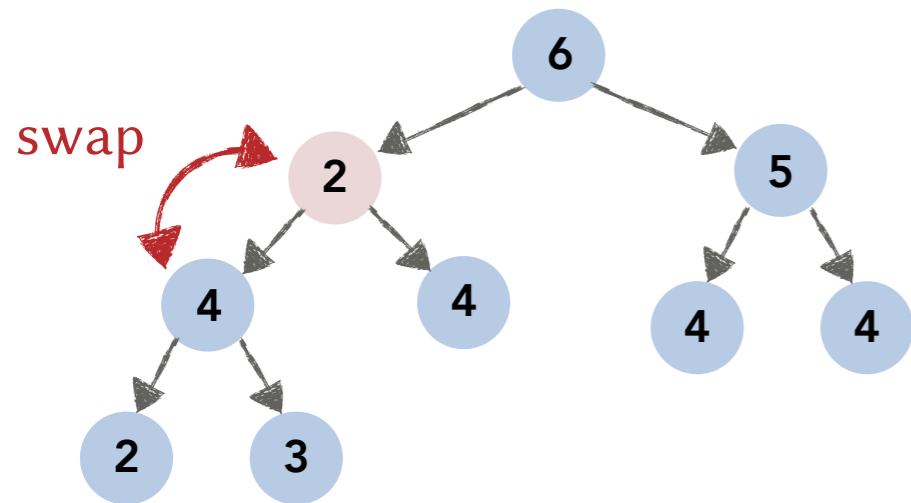
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2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



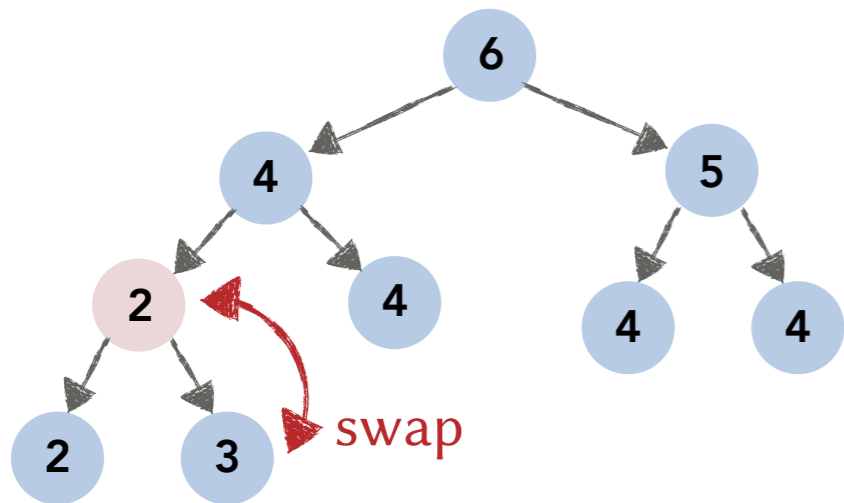
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Fixing a *Locally Broken Heap*

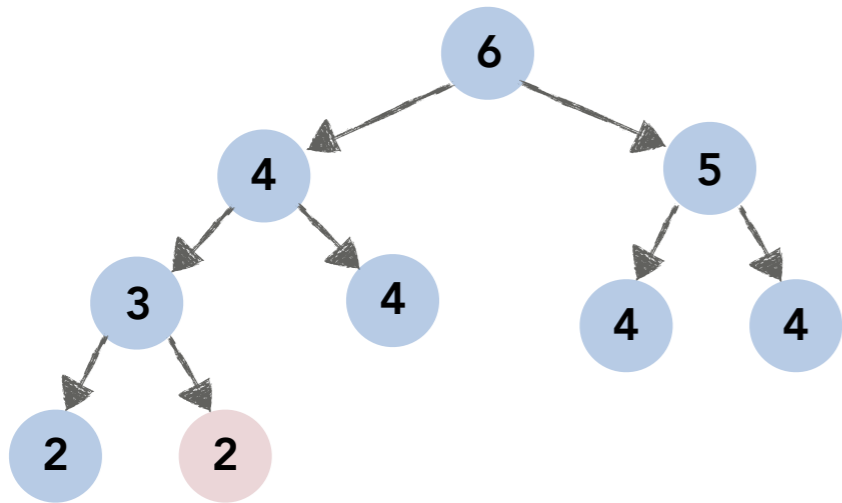
2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



can't swap with 2 because it is less than the other child (3)

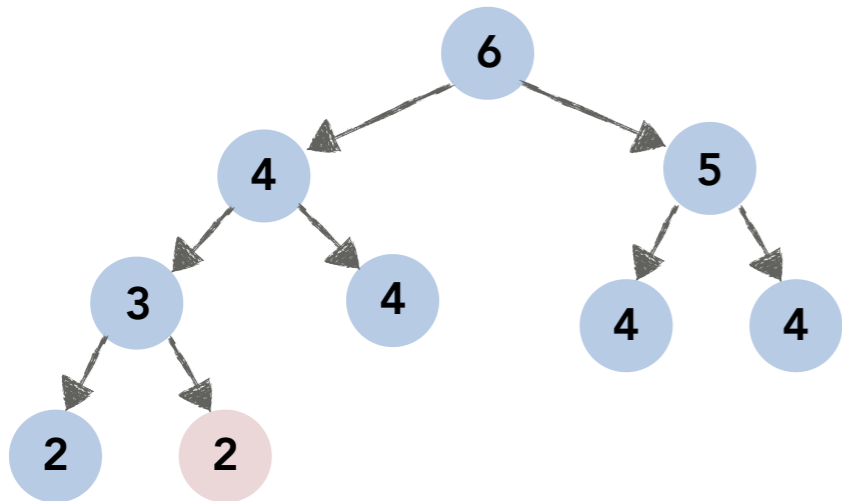
Fixing a *Locally Broken Heap*

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Fixing a *Locally Broken Heap*

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SINK(a[], i, size)

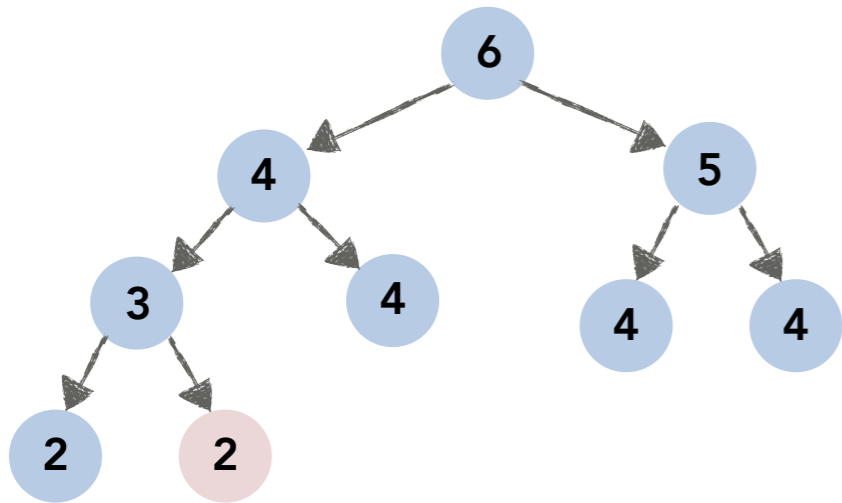


also called:

- SIFTDOWN on wikipedia
- MAX-HEAPIFY in our text-book
- FIX-HEAP in the slides of the other sections!

Fixing a *Locally Broken Heap*

2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



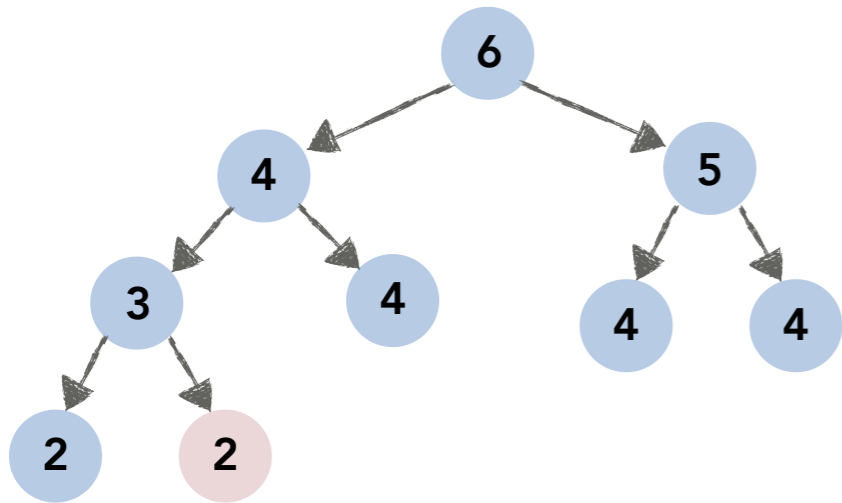
```
SINK(a[], i, size)
```

```
while (LEFT(i) < size):
```

↑
while there is
a left child

Fixing a *Locally* Broken Heap

2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



```
SINK(a[], i, size)
```

```
while (LEFT(i) < size):
```

```
    k = LEFT(i)
```

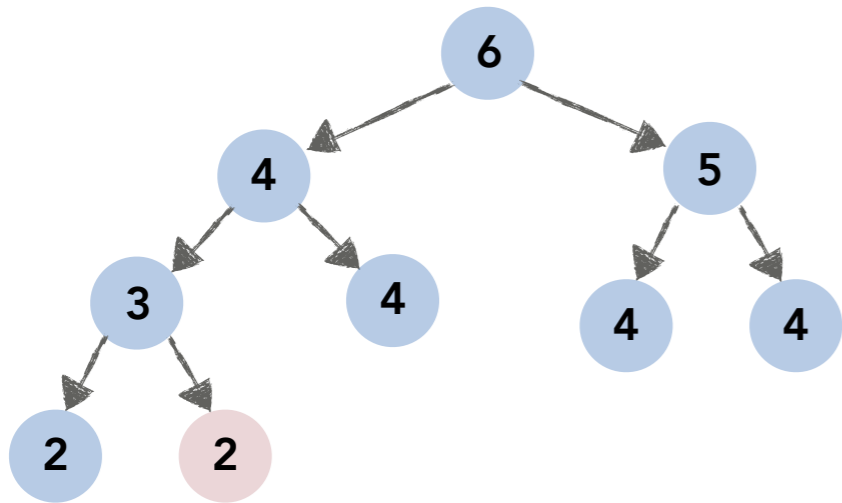
```
    if (RIGHT(i) < size):
```

```
        if (a[k] < a[RIGHT(i)]): k = RIGHT(i)
```

↑
pick between the left and
right child depending on
which one is the largest.

Fixing a *Locally Broken Heap*

2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



```
SINK(a[], i, size)
```

```
while (LEFT(i) < size):
```

```
    k = LEFT(i)
```

```
    if (RIGHT(i) < size):
```

```
        if (a[k] < a[RIGHT(i)]): k = RIGHT(i)
```

```
    if (a[i] < a[k]):
```

```
        swap(a[i], a[k])
```

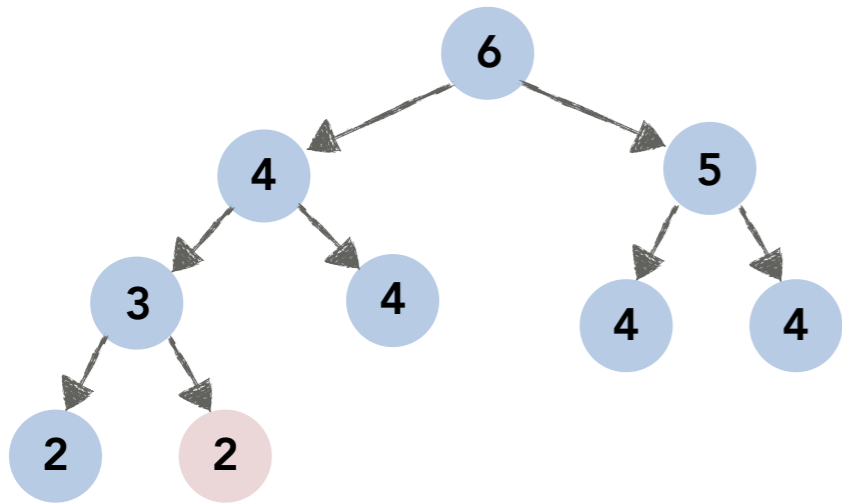
```
        i = k
```

```
    else: break
```

← swap with and move to
the larger child or stop
if no swap is necessary

Fixing a *Locally Broken Heap*

2. If an item becomes **less** than one of its children, push it **down** the tree to maintain the heap order property.



```
SINK(a[], i, size)
```

```
while (LEFT(i) < size):
```

```
    k = LEFT(i)
```

```
    if (RIGHT(i) < size):
```

```
        if (a[k] < a[RIGHT(i)]): k = RIGHT(i)
```

```
    if (a[i] < a[k]):
```

```
        swap(a[i], a[k])
```

```
        i = k
```

```
    else: break
```



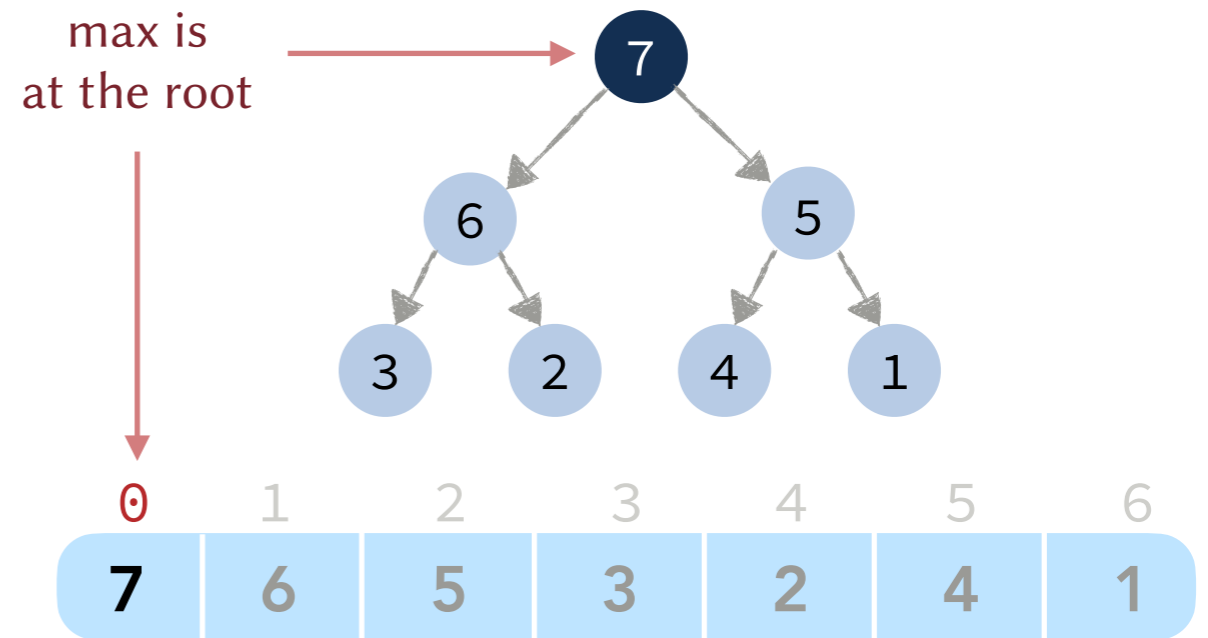
Running Time. $O(\log n)$

At most 1 swap and 2 comparisons per iteration

The number of iterations is bounded by the tree height.

Max-PQ Operations

Max: Always at index 0.
 $\Theta(1)$



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Max: Always at index 0.
 $\Theta(1)$

Insert: Insert at the end of the array and then **swim**.

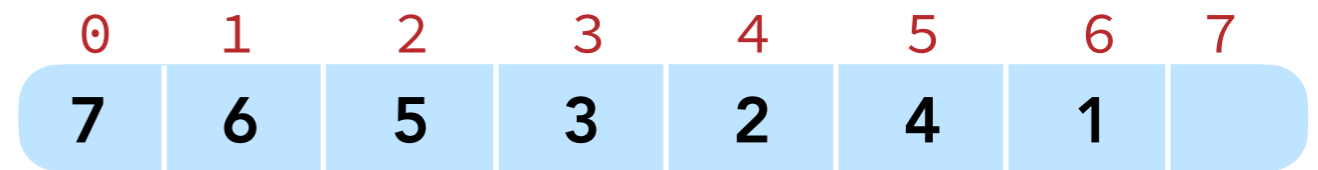
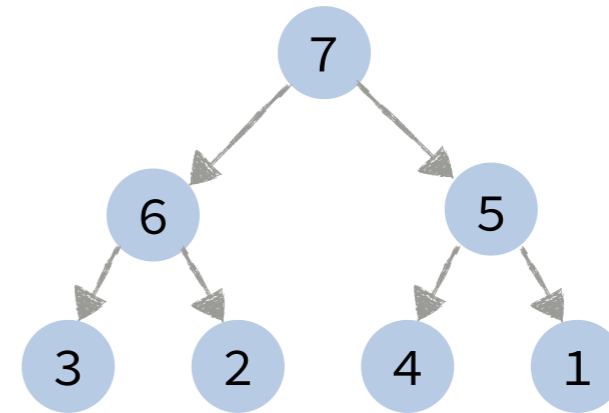
INSERT(a[], k, size)

a[size] = k

size = size + 1

SWIM(a, size-1, size)

$O(\log n)$: Swim at most to the root.



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Insert: Insert at the end of the array and then **swim**.

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INSERT(a[], k, size)
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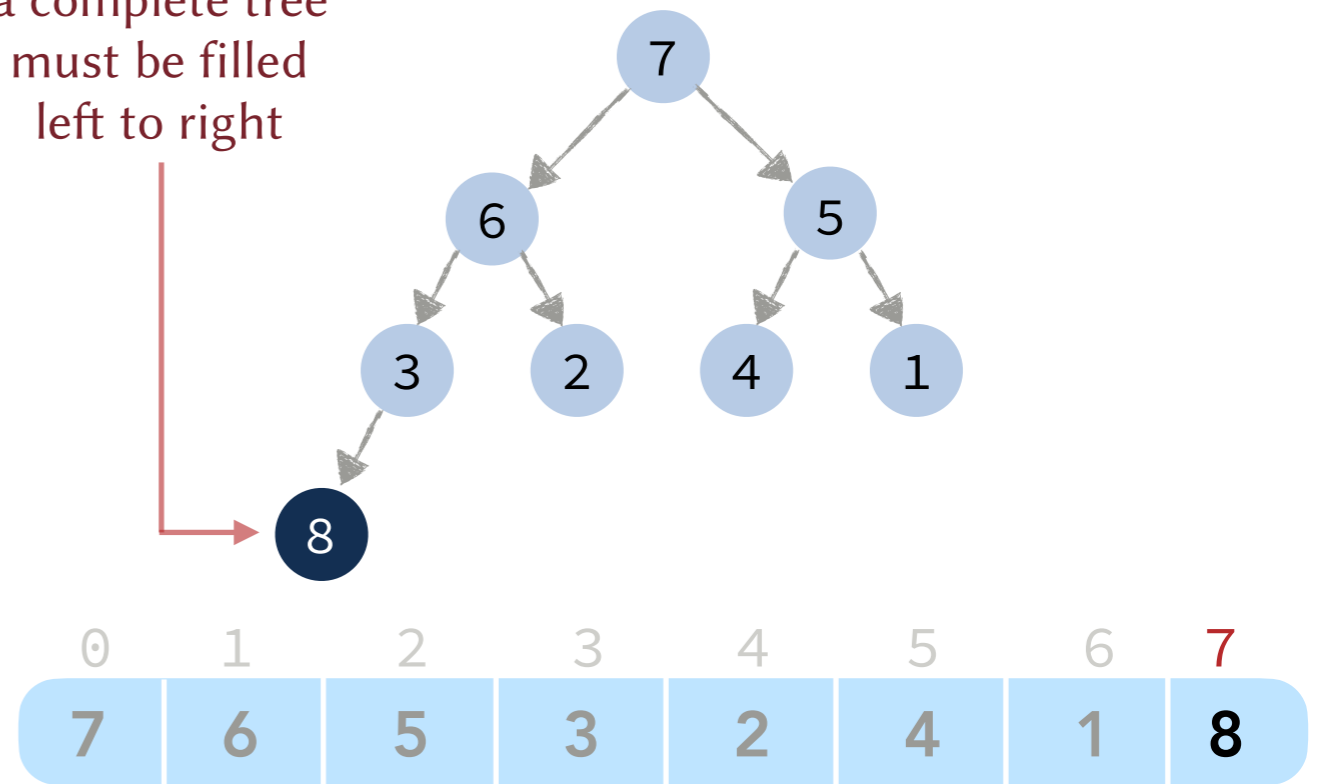
```
a[size] = k
```

```
size = size + 1
```

```
SWIM(a, size-1, size)
```

$O(\log n)$: Swim at most to the root.

a complete tree
must be filled
left to right



adding to the last index is
equivalent to filling the last
level left-to-right

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Max: Always at index 0.
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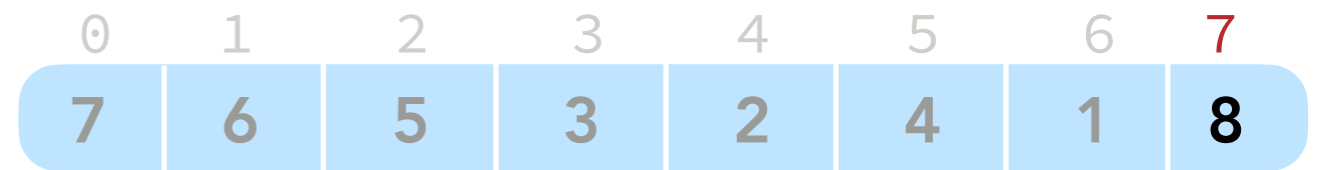
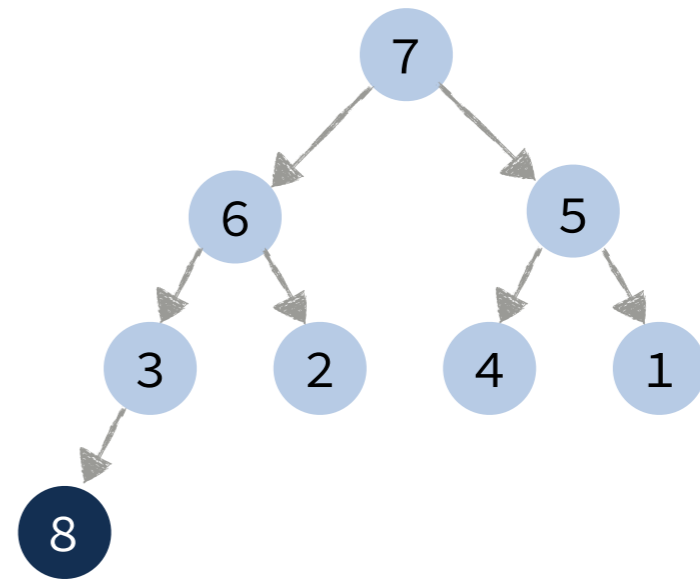
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INSERT(a[], k, size)
```

```
a[size] = k
```

```
size = size + 1
```

```
SWIM(a, size-1, size)
```

$O(\log n)$: Swim at most to the root.



fix the heap after
inserting the new
element

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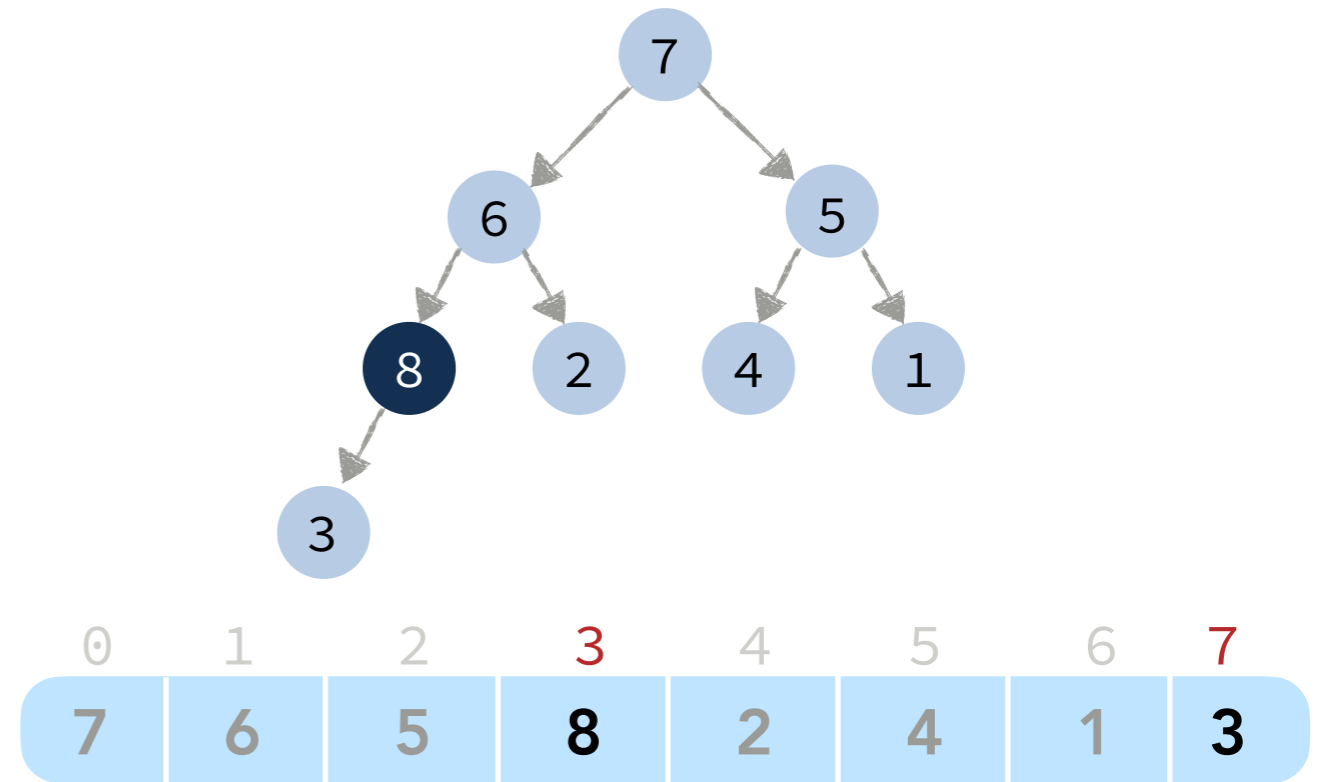
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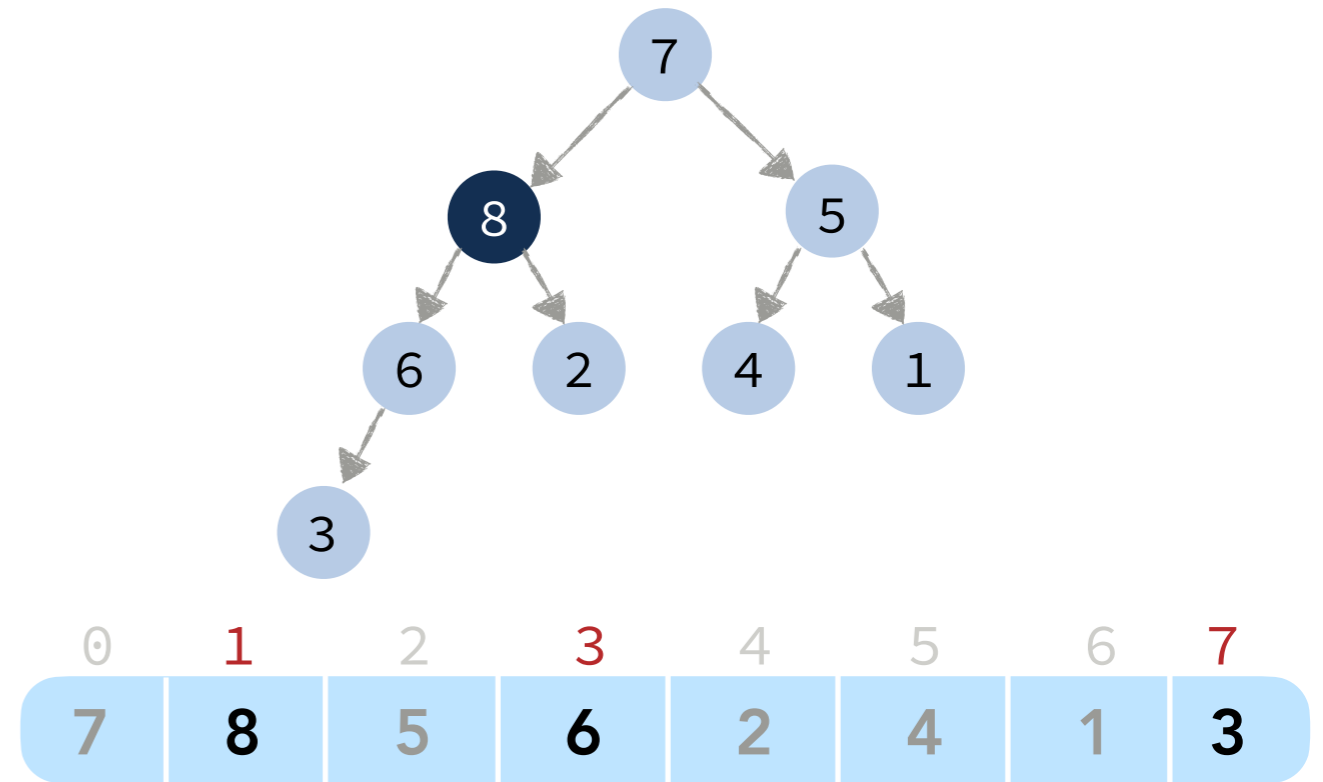
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a[size] = k
```

```
size = size + 1
```

```
SWIM(a, size-1, size)
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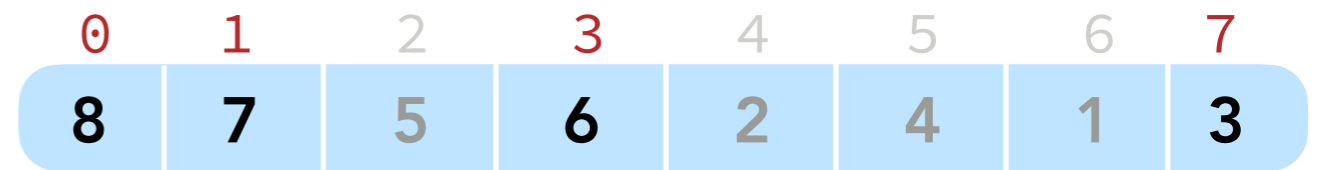
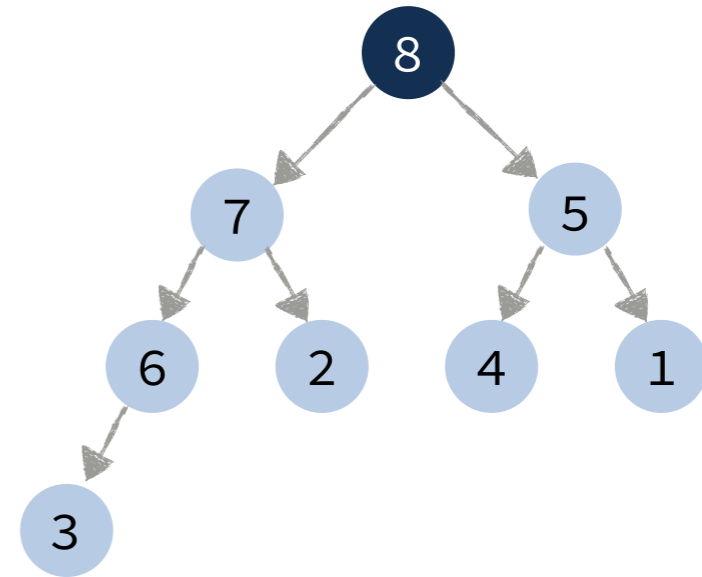
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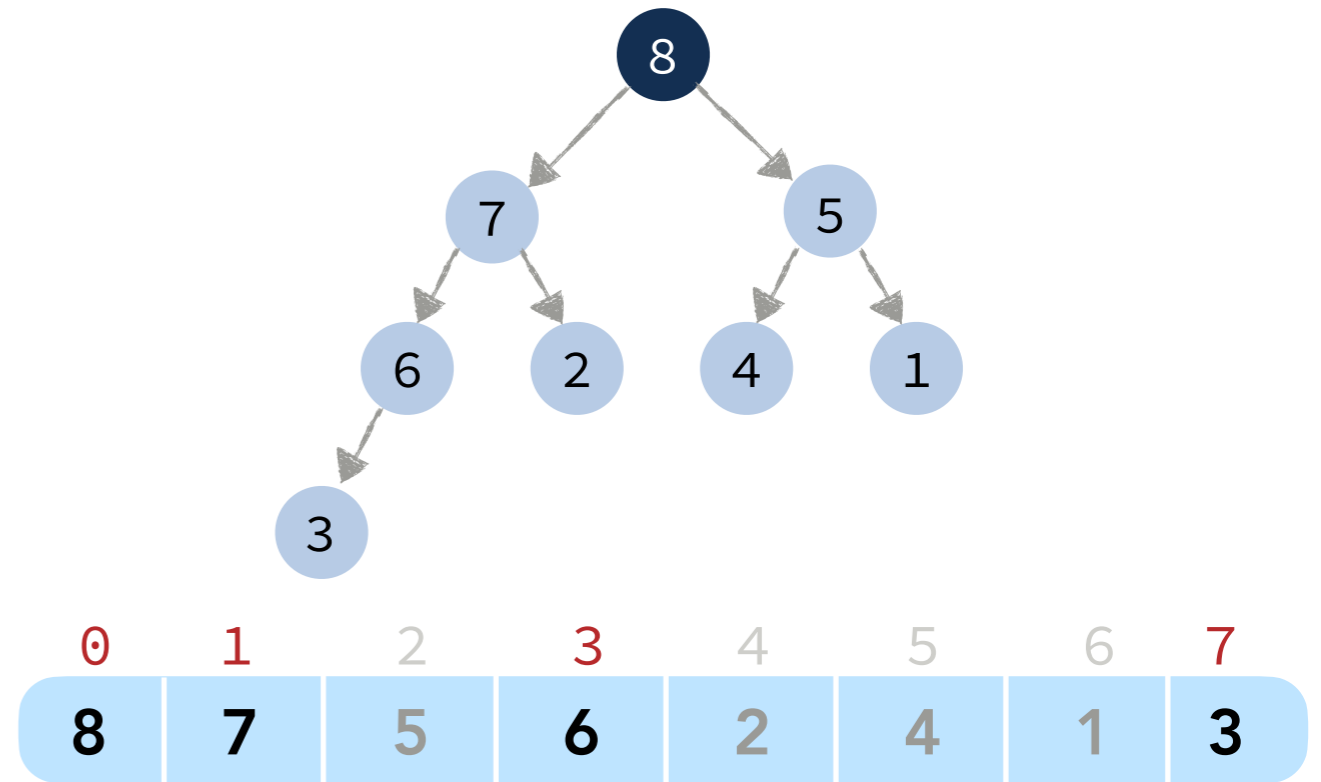
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Del-Max: Swap the last element with the element at index 0 and then **sink**.

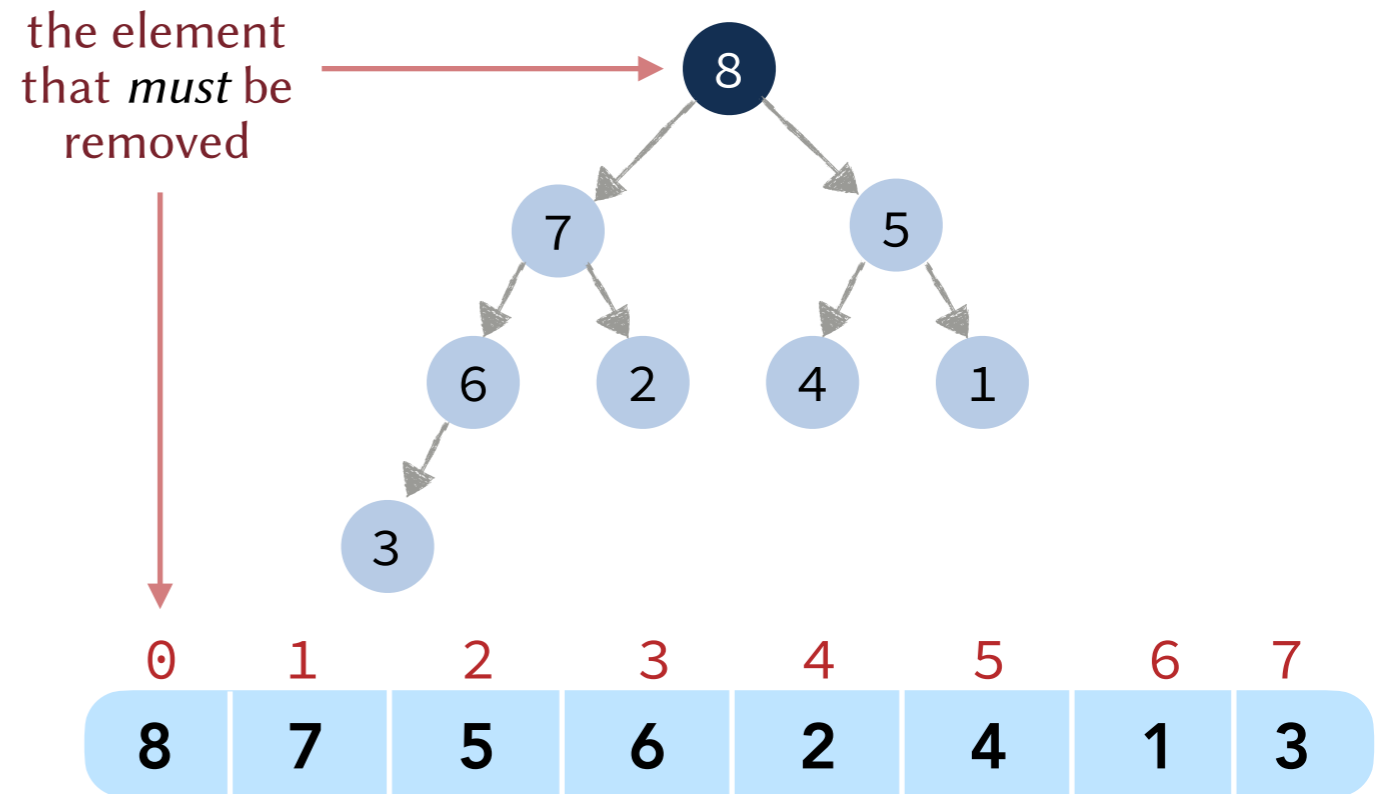
```
DEL-MAX(a[], size)
```

```
swap(a[size-1], a[0])
```

```
size = size - 1
```

```
SINK(a, 0, size)
```

$O(\log n)$: Sink at most to the last level.



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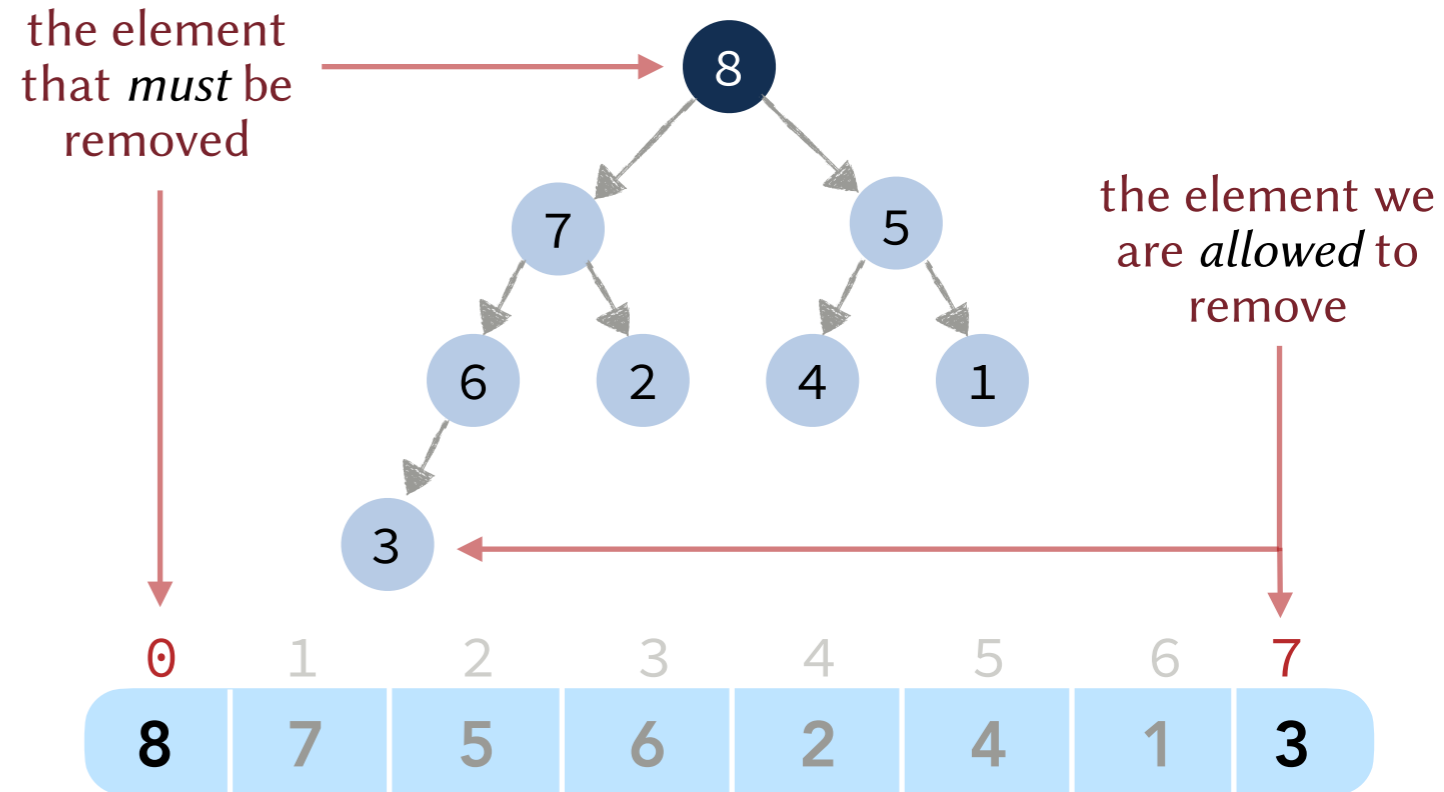
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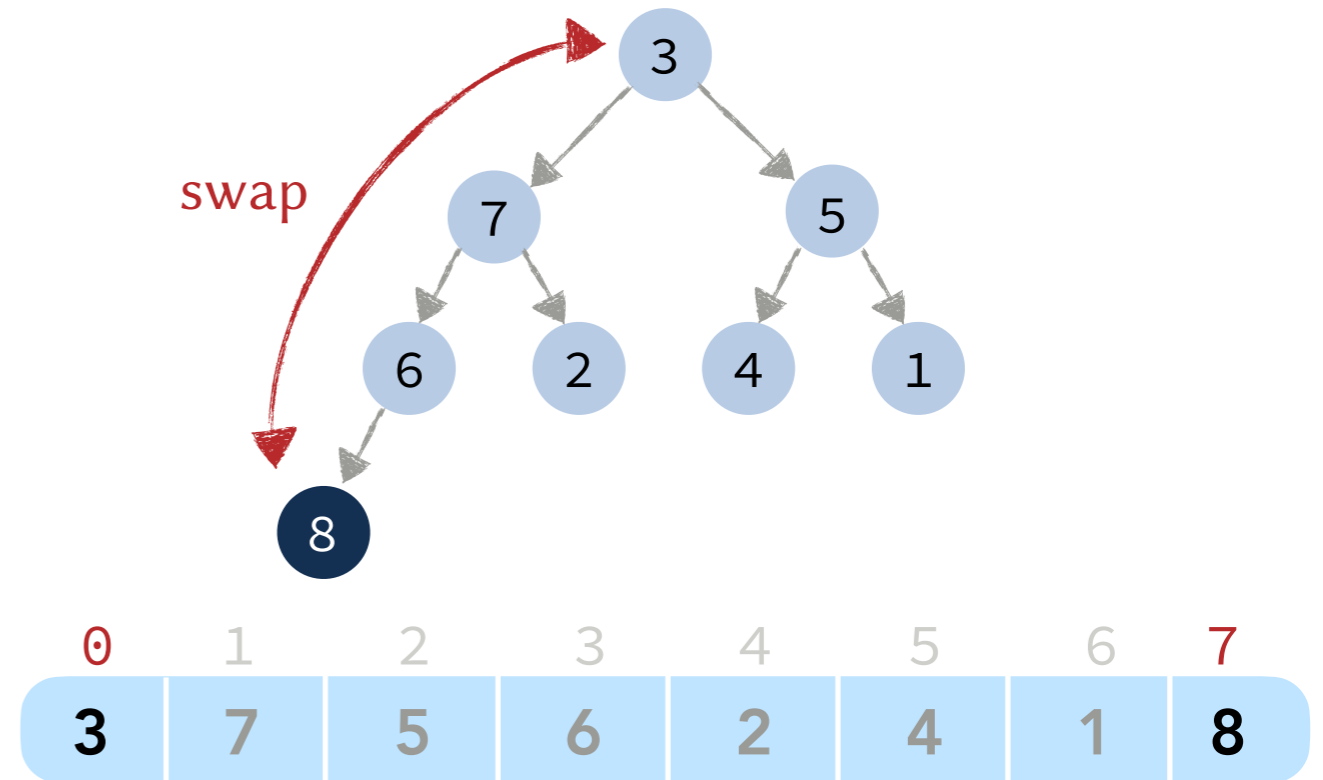
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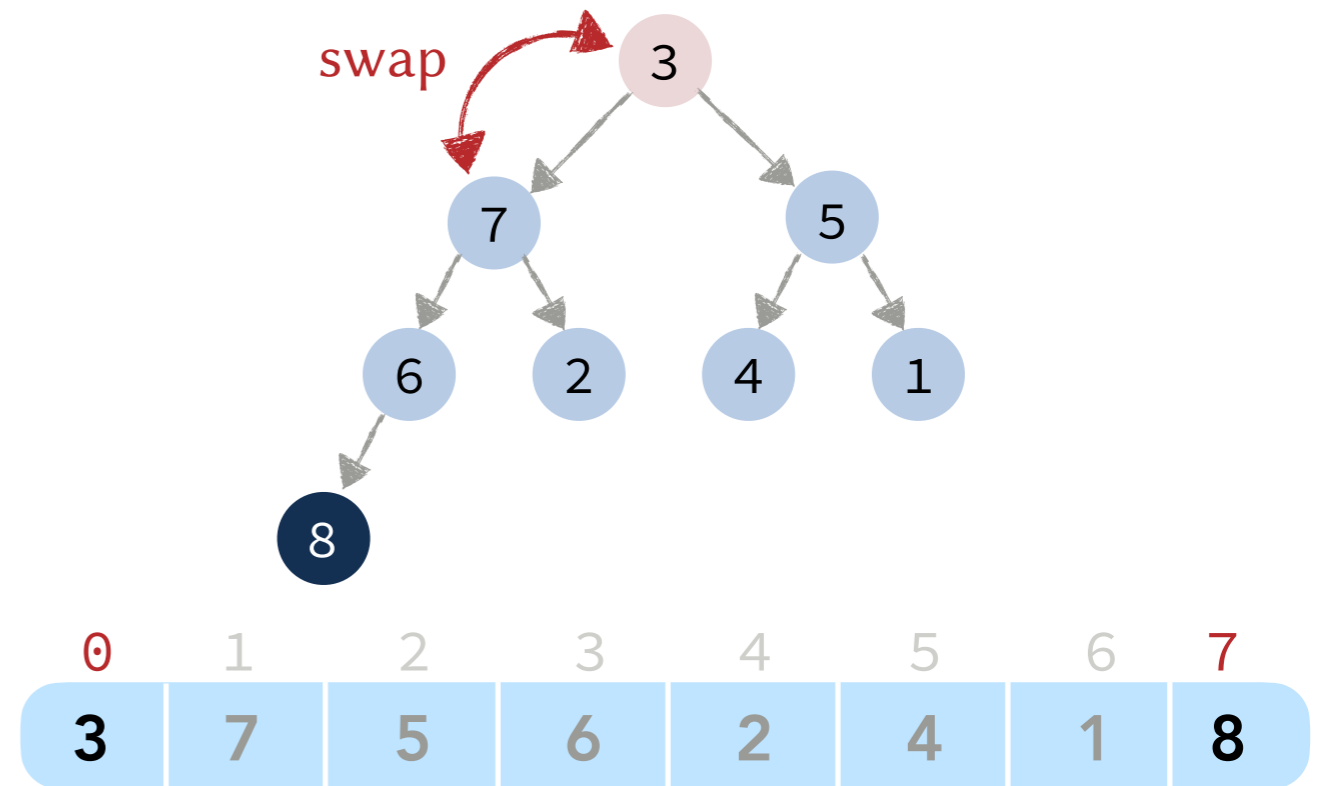
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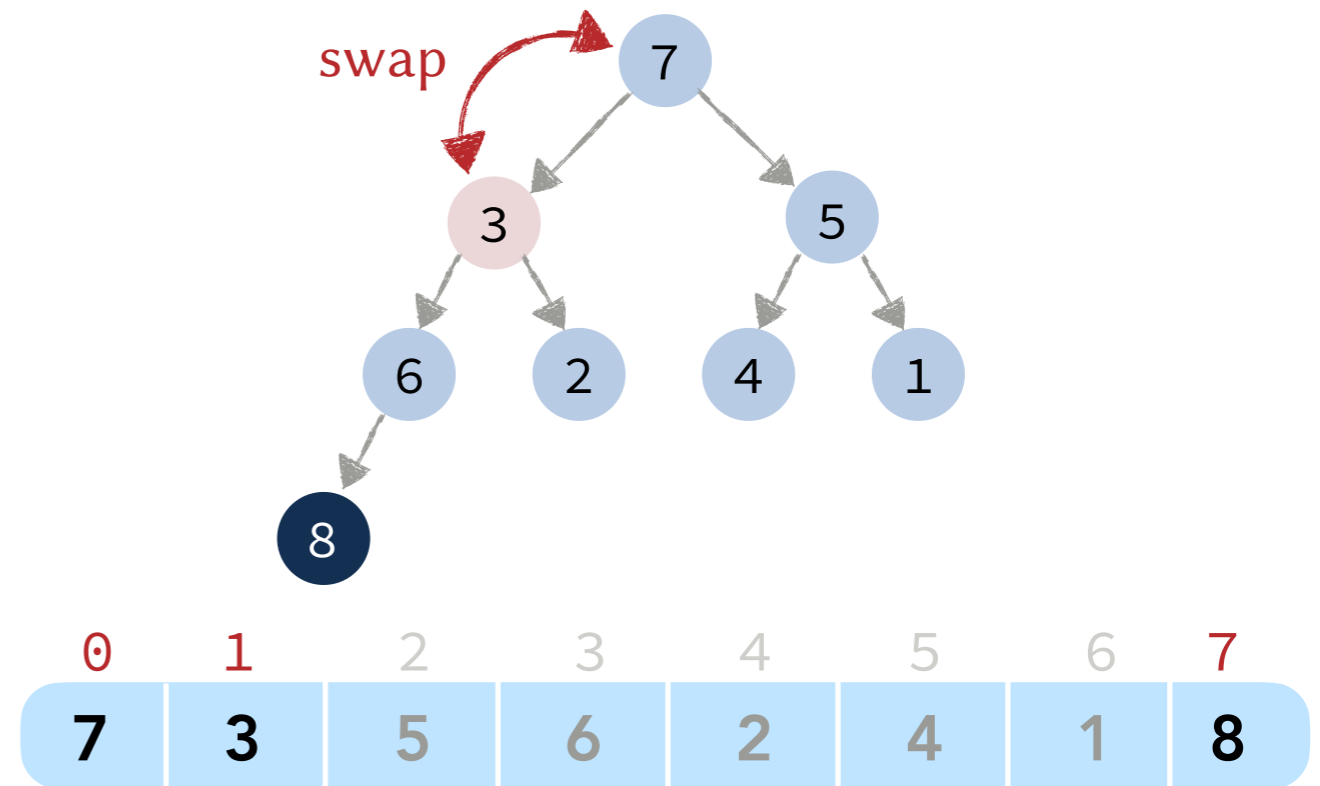
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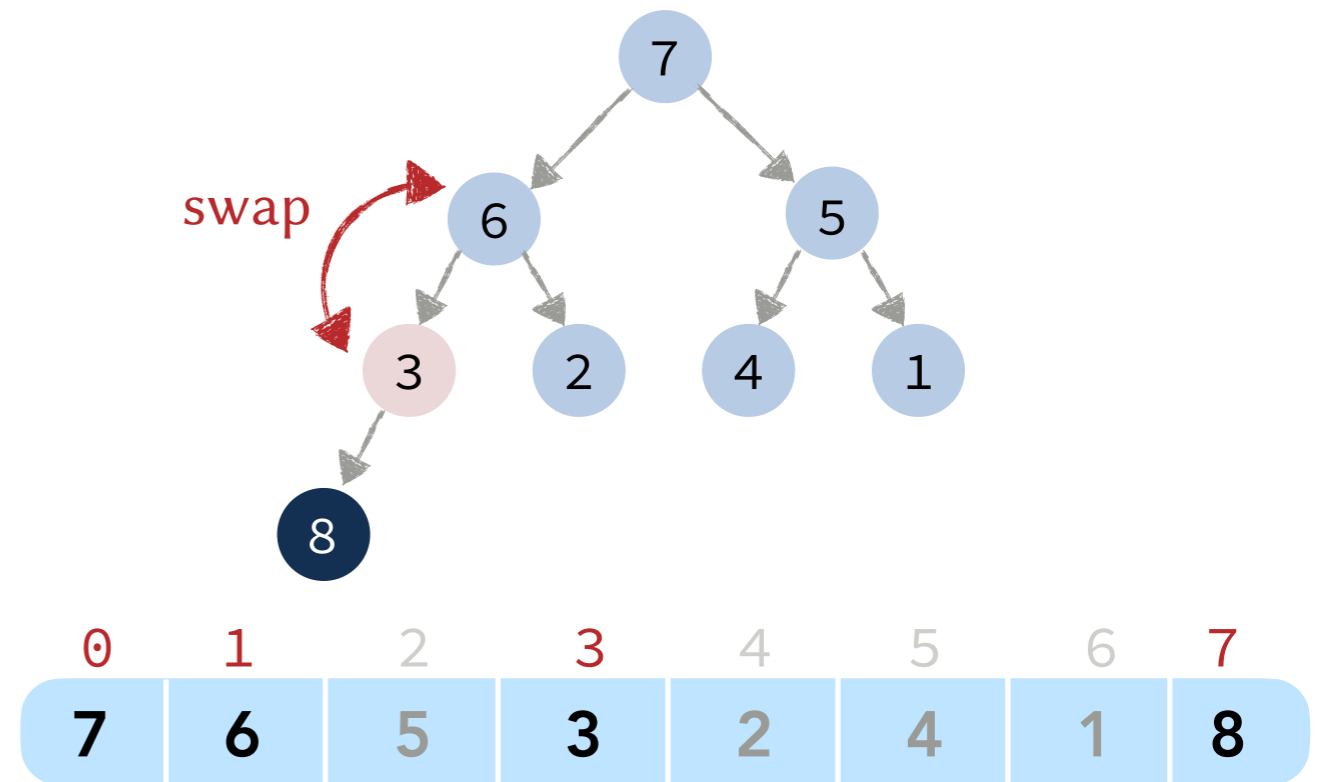
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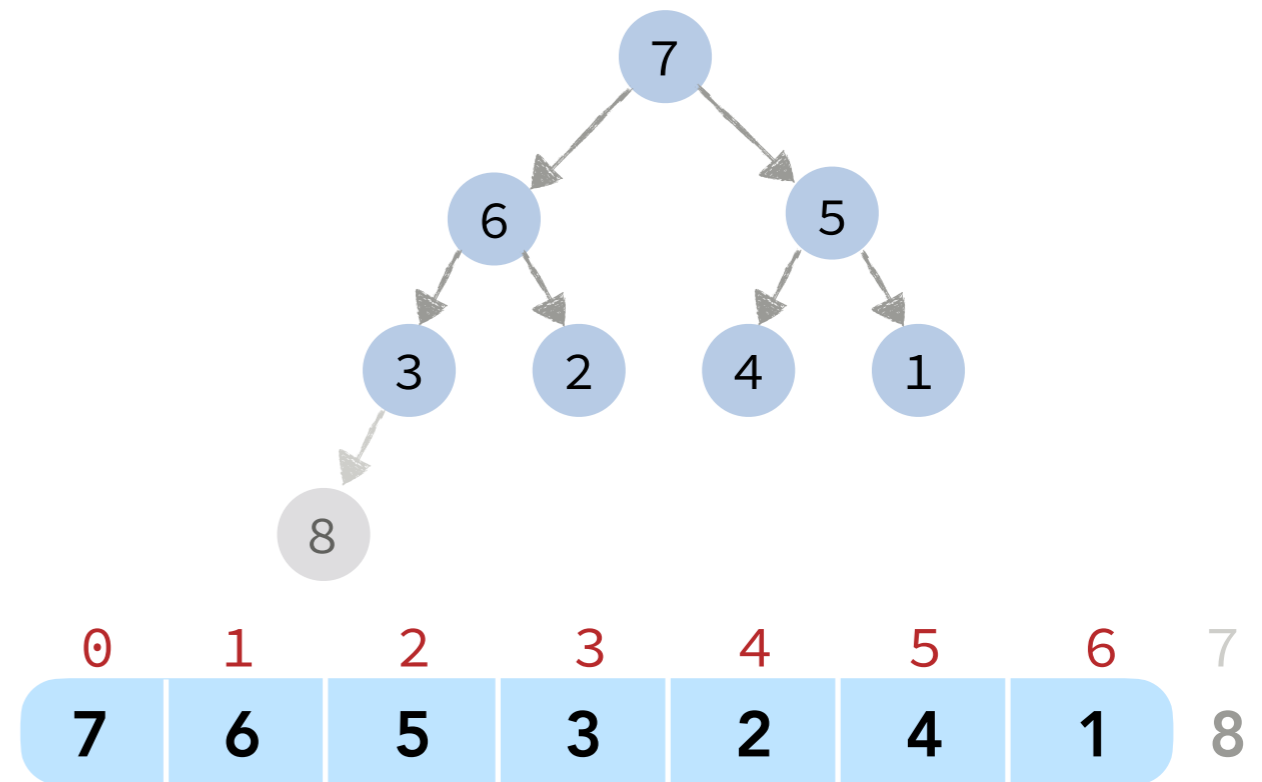
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Quiz # 1

Implement a max-PQ that supports the following operation:

del-Random: Removes a random element from the priority queue.

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del-Random: Removes a random element from the priority queue.

Answer.

```
DEL-RANDOM(a[], size)
```

```
k = random index in [0, size-1]
```

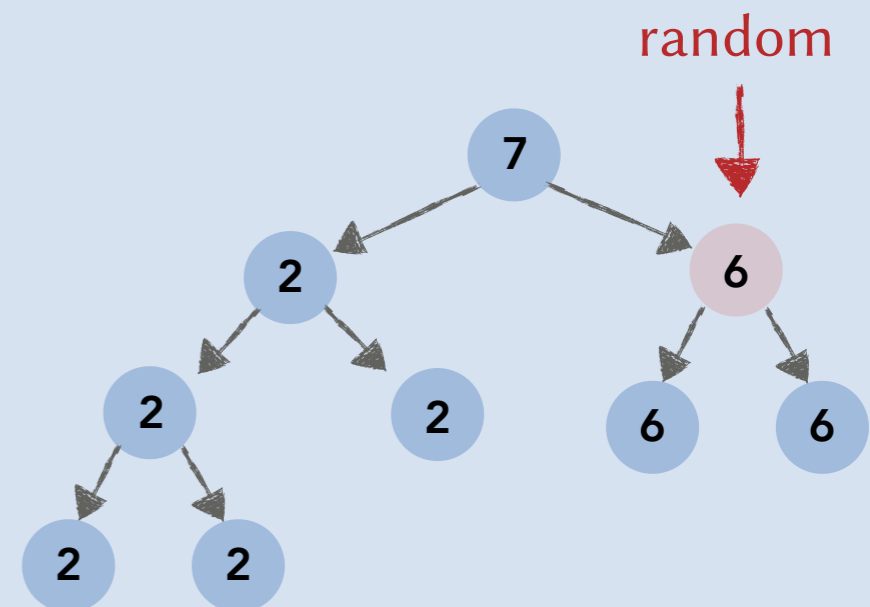
```
swap(a[k], a[size-1])
```

```
size = size-1
```

```
SINK(a, k, size)
```

```
SWIM(a, k, size)
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Example 1.



Quiz # 1

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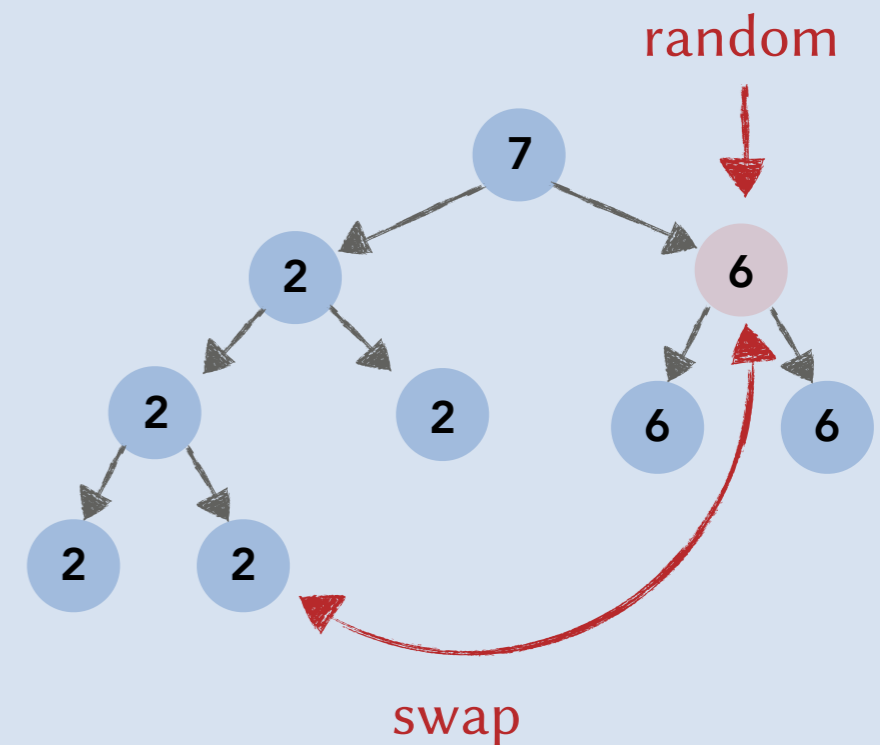
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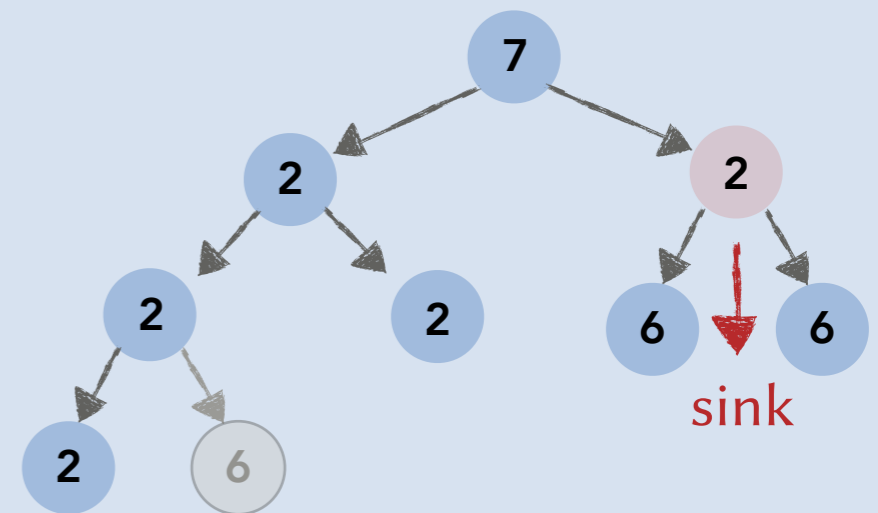
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```
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Example 1.



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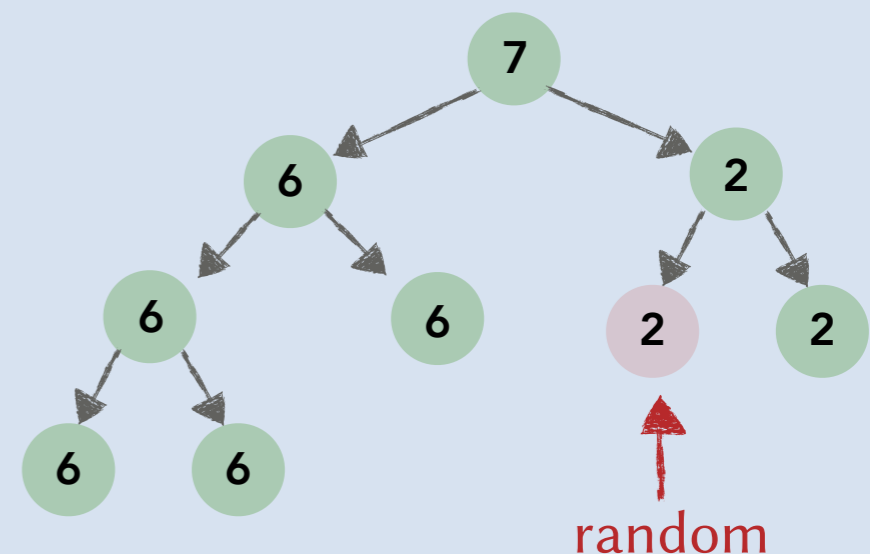
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```

```
size = size-1
```

```
SINK(a, k, size)
```

```
SWIM(a, k, size)
```

Example 2.



Quiz # 1

Implement a max-PQ that supports the following operation:

del-Random: Removes a random element from the priority queue.

Answer.

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DEL-RANDOM(a[], size)
```

```
k = random index in [0, size-1]
```

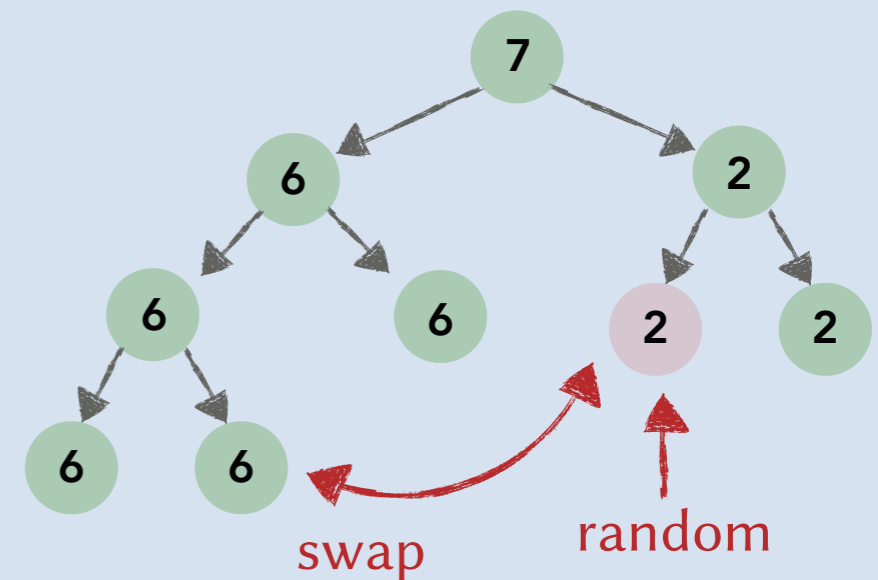
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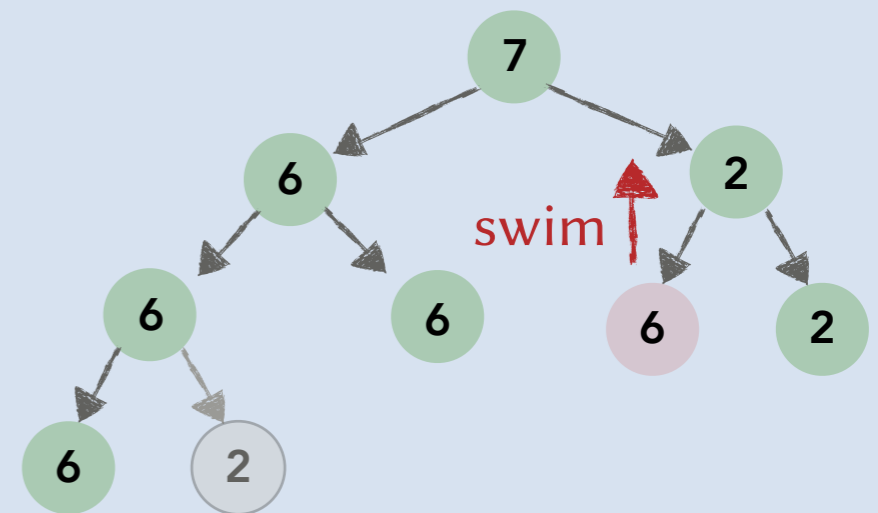
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SINK(a, k, size)
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Example 2.



Heapsort

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

```
    heap.INSERT(a[i])
```

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

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1

insert all the array elements
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1

insert all the array elements into a max-heap

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

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1

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    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!)$

Heapsort: Naive Implementation

HEAP-SORT(a[], size)

heap \leftarrow An empty max heap

for $i = 0 \rightarrow n-1$:

heap.**INSERT**(a[i])

1

insert all the array elements into a max-heap

for $i = n-1 \rightarrow 0$:

a[i] = heap.**MAX**()

heap.**DELETE-MAX**()

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!)$

↑
insert the second element into a heap of size 1

↑
insert the last element into a heap of size $n-1$

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

```
    heap.INSERT(a[i])
```

1

insert all the array elements into a max-heap

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!) = O(n \log n)$
- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1)) \leq 2 \times \log_2(n!)$

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

```
    heap.INSERT(a[i])
```

1

insert all the array elements into a max-heap

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!) = O(n \log n)$
- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1))$
 $\leq 2 \times \log_2(n!) = O(n \log n)$

check the analysis of the **SINK** operation!

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

```
    heap.INSERT(a[i])
```

1

insert all the array elements into a max-heap

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!) = O(n \log n)$
- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1))$
 $\leq 2 \times \log_2(n!) = O(n \log n)$
- Total. $O(n \log n)$

Heapsort: Naive Implementation

```
HEAP-SORT(a[], size)
```

```
heap ← An empty max heap
```

```
for i = 0 → n-1:
```

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    heap.INSERT(a[i])
```

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insert all the array elements into a max-heap

```
for i = n-1 → 0:
```

```
    a[i] = heap.MAX()
```

```
    heap.DELETE-MAX()
```

2

copy all the elements back from the heap to the array (in order)

Running Time. (number of compares in the worst case)

- Step 1. $\log_2(1) + \log_2(2) + \log_2(3) + \dots + \log_2(n-1) \leq \log_2(n!) = O(n \log n)$
- Step 2. $2 \times (\log_2(n-1) + \log_2(n-2) + \log_2(n-3) + \dots + \log_2(1))$
 $\leq 2 \times \log_2(n!) = O(n \log n)$
- Total. $O(n \log n)$



Can we do better?

Not asymptotically, but we can still improve the actual running time!

Heapsort: A Better Implementation

```
HEAP-SORT(a[], size)
```

```
  CONSTRUCT-HEAP(a, size)
```

```
  while (size > 1):  
    swap(a[0], a[size-1])  
    size = size-1  
    SINK(a, 0, size)
```

0	1	2	3	4	5	6	7	8
6	7	6	2	4	4	5	2	5

random array

size-1

Heapsort: A Better Implementation

```
HEAP-SORT(a[], size)
```

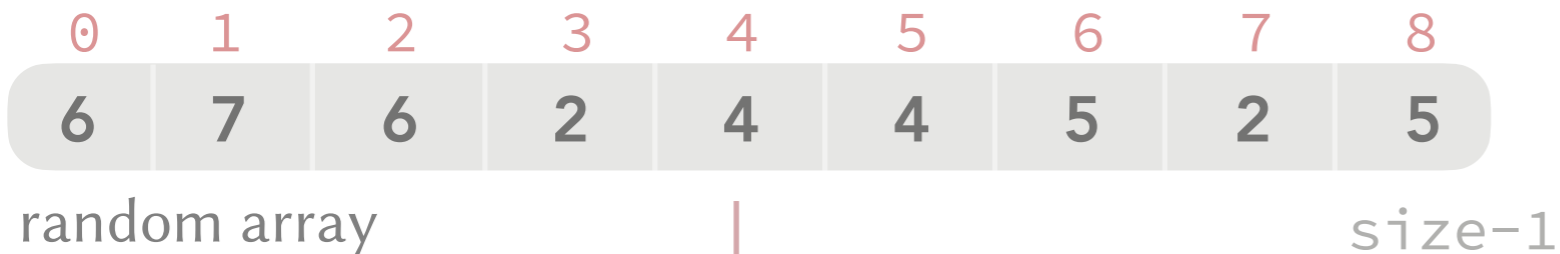
```
  CONSTRUCT-HEAP(a, size)
```

```
  while (size > 1):  
    swap(a[0], a[size-1])  
    size = size-1  
    SINK(a, 0, size)
```

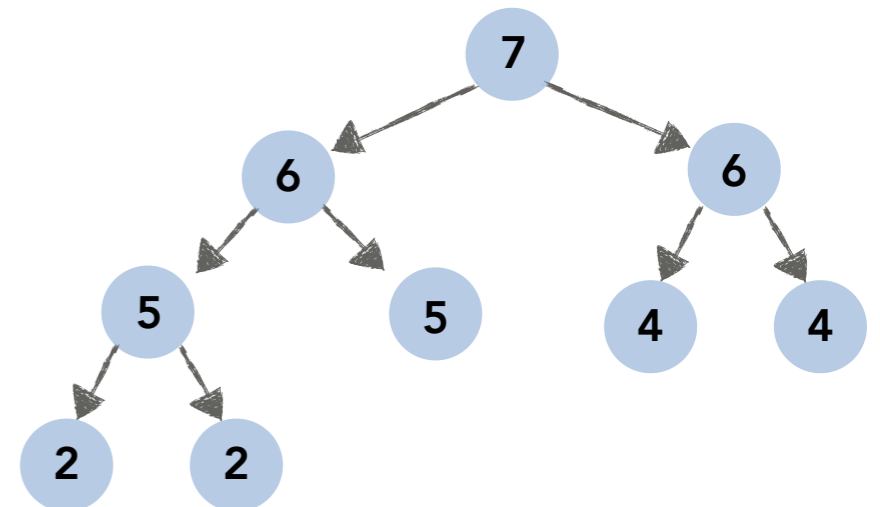
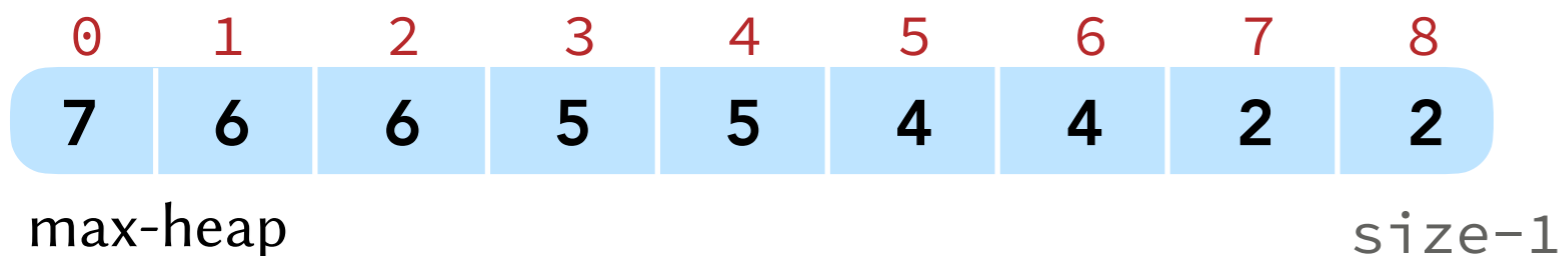
1

construct a max-heap in-place
(convert the array to become a heap)

How? stay tuned!



CONSTRUCT-HEAP()



Heapsort: A Better Implementation

```
HEAP-SORT(a[], size)
```

```
  CONSTRUCT-HEAP(a, size)
```

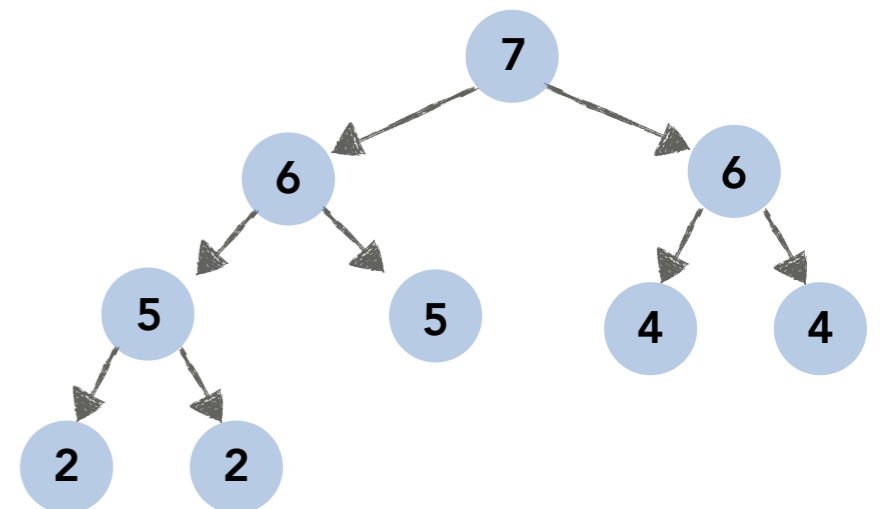
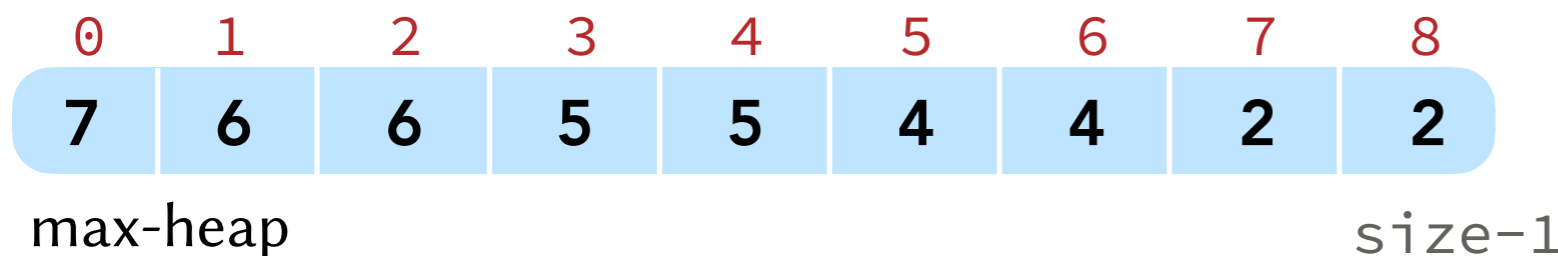
```
  while (size > 1):  
    swap(a[0], a[size-1])  
    size = size-1  
    SINK(a, 0, size)
```

1

construct a max-heap in-place
(change the array to become a heap)

2

repeatedly place the next
maximum in its right position



Heapsort: A Better Implementation

```
HEAP-SORT(a[], size)
```

```
  CONSTRUCT-HEAP(a, size)
```

```
  while (size > 1):
```

```
    swap(a[0], a[size-1])
```

```
    size = size-1
```

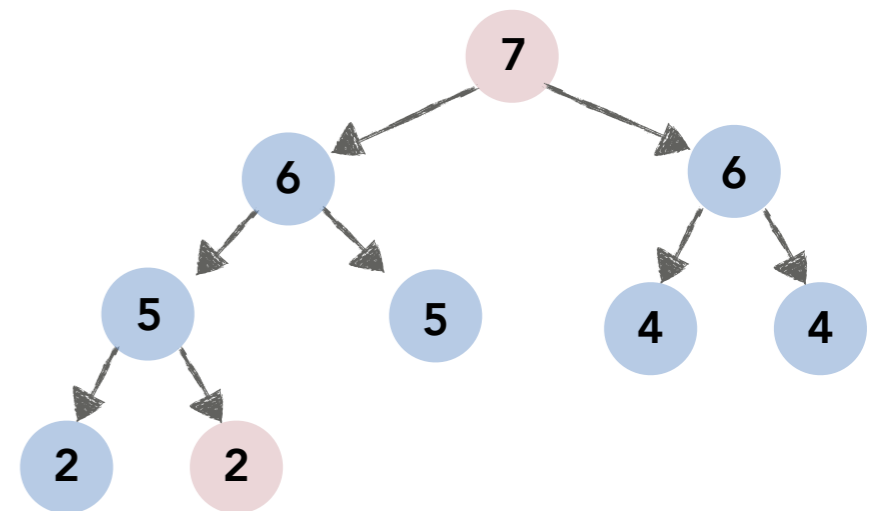
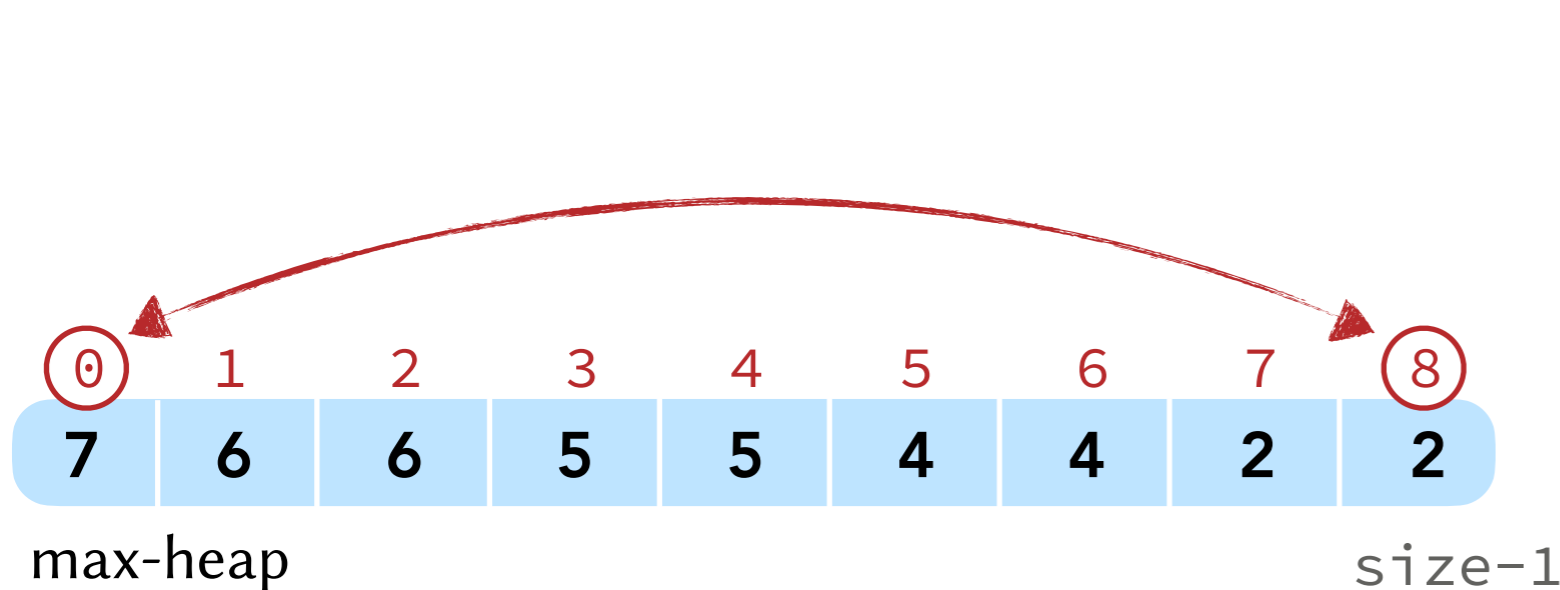
```
    SINK(a, 0, size)
```

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```
  while (size > 1):
```

```
    swap(a[0], a[size-1])
```

```
    size = size-1
```

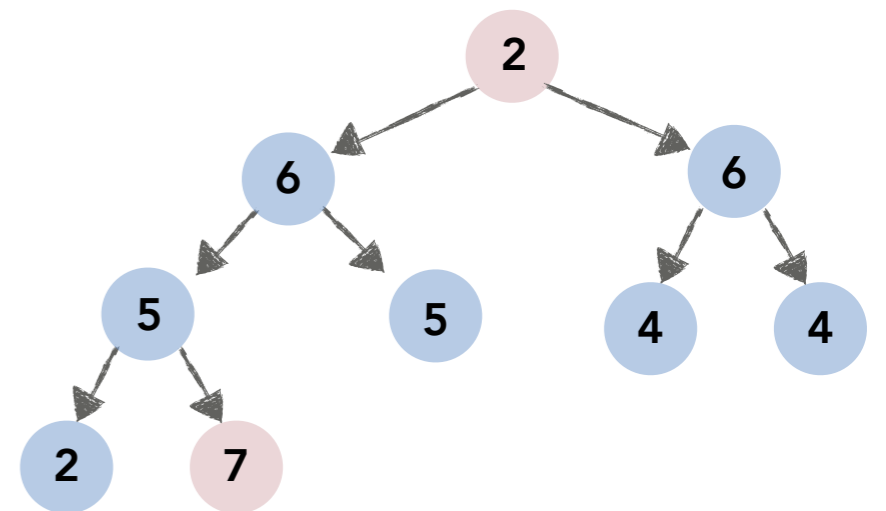
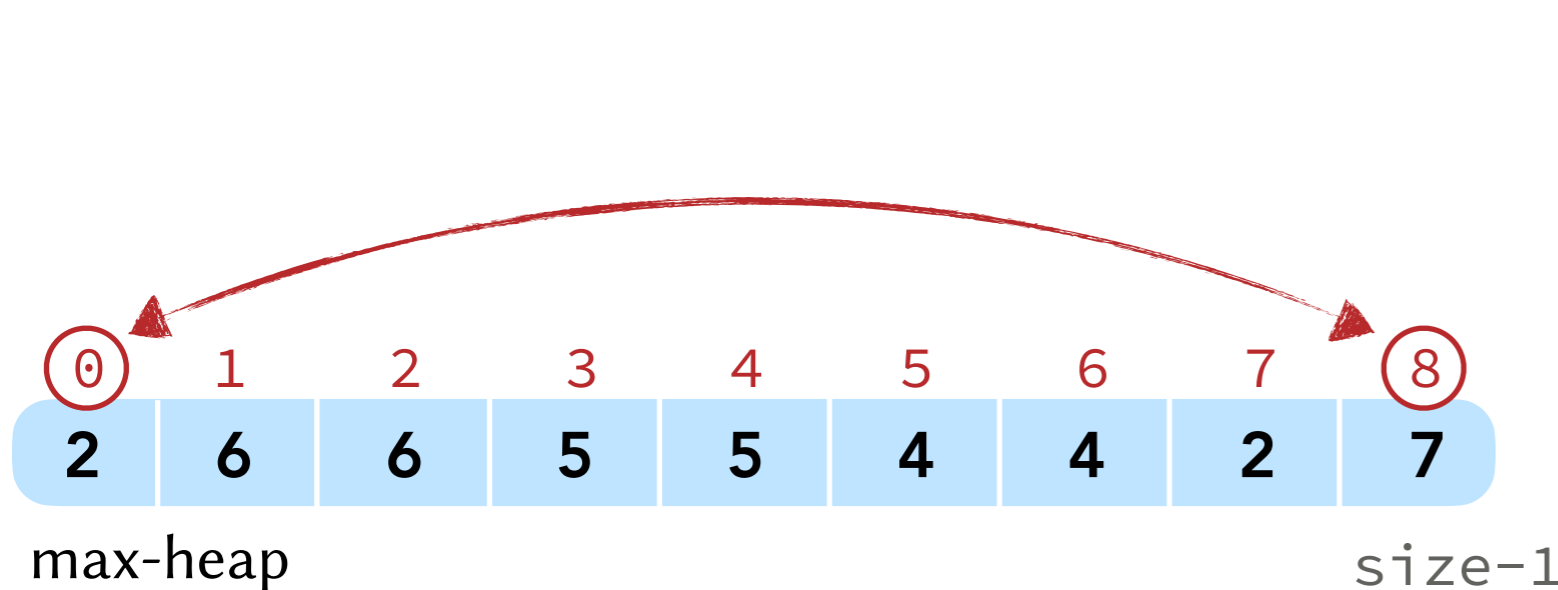
```
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Heapsort: A Better Implementation

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```
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```

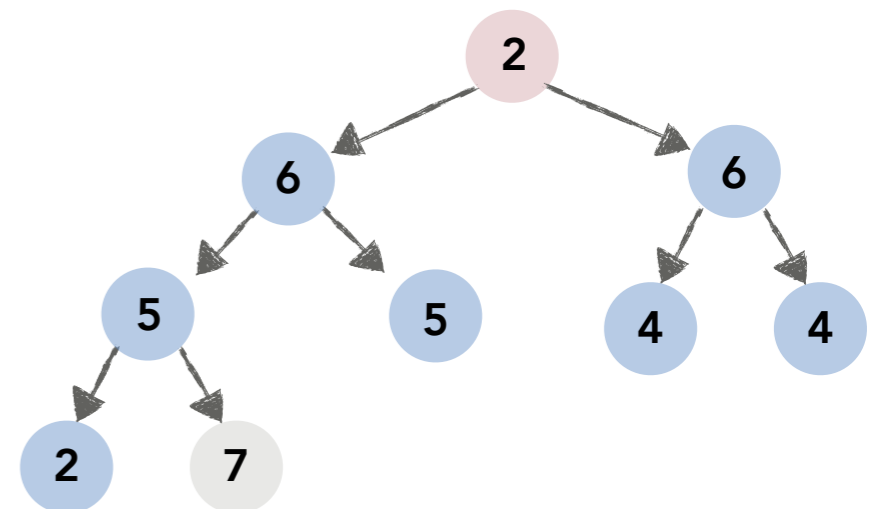
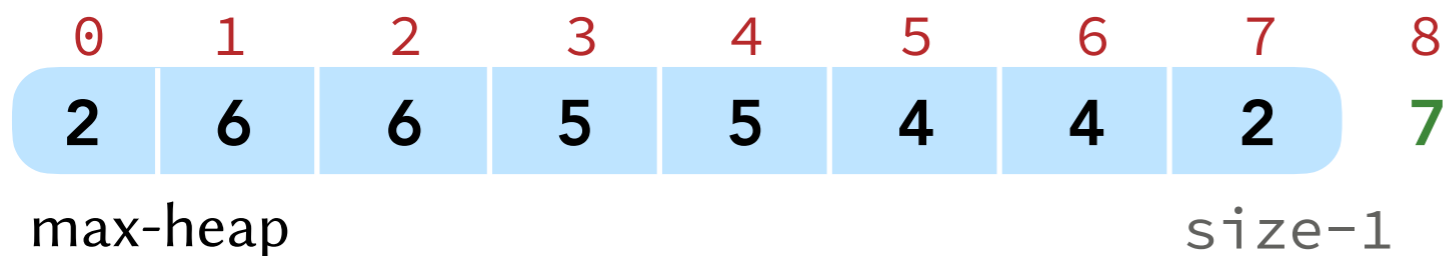
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Heapsort: A Better Implementation

HEAP-SORT(a[], size)

CONSTRUCT-HEAP(a, size)

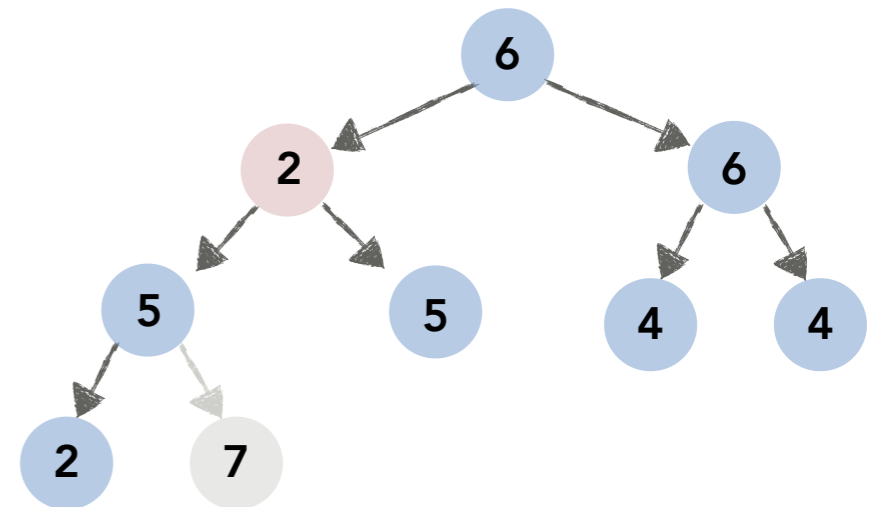
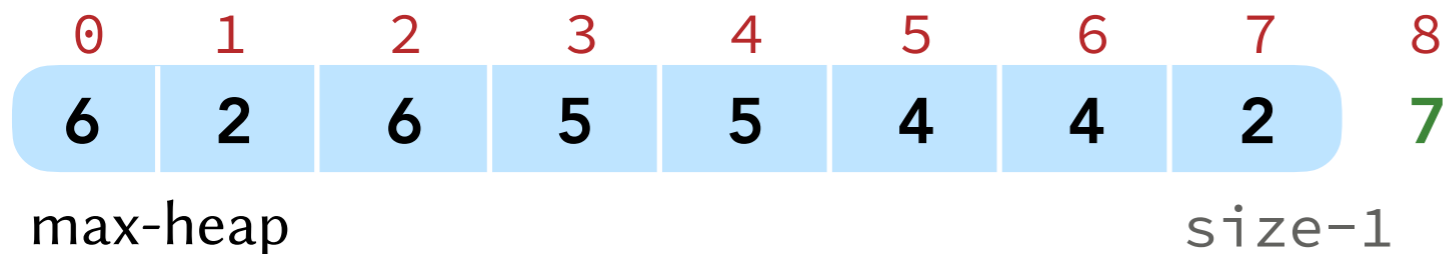
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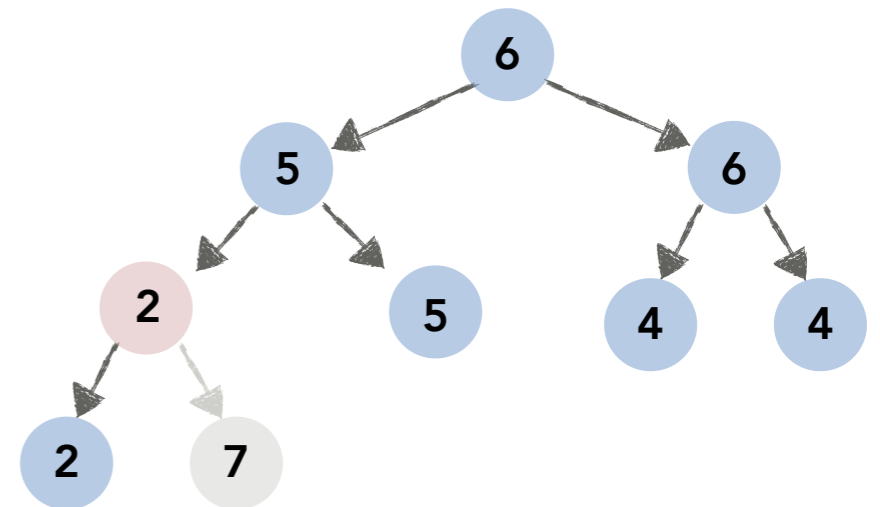
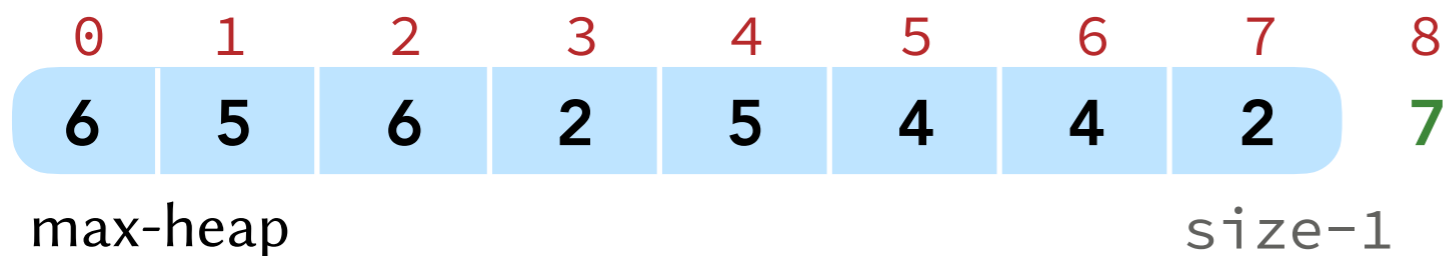
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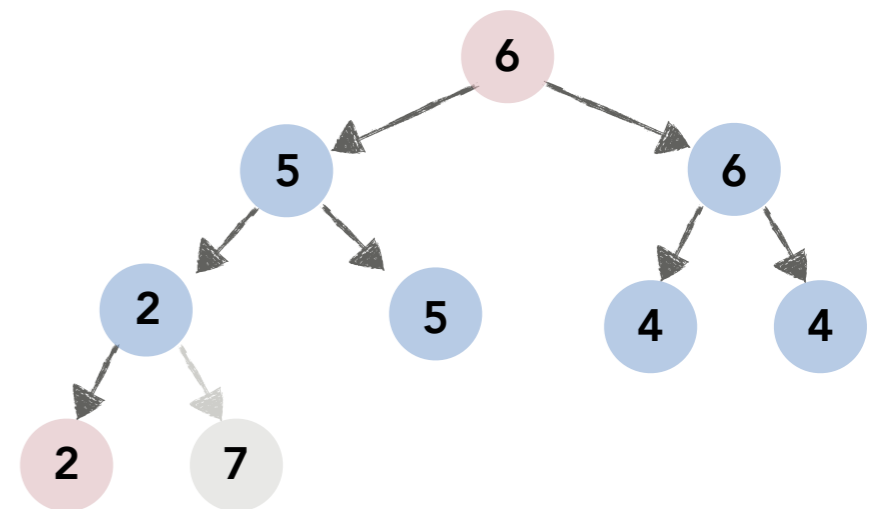
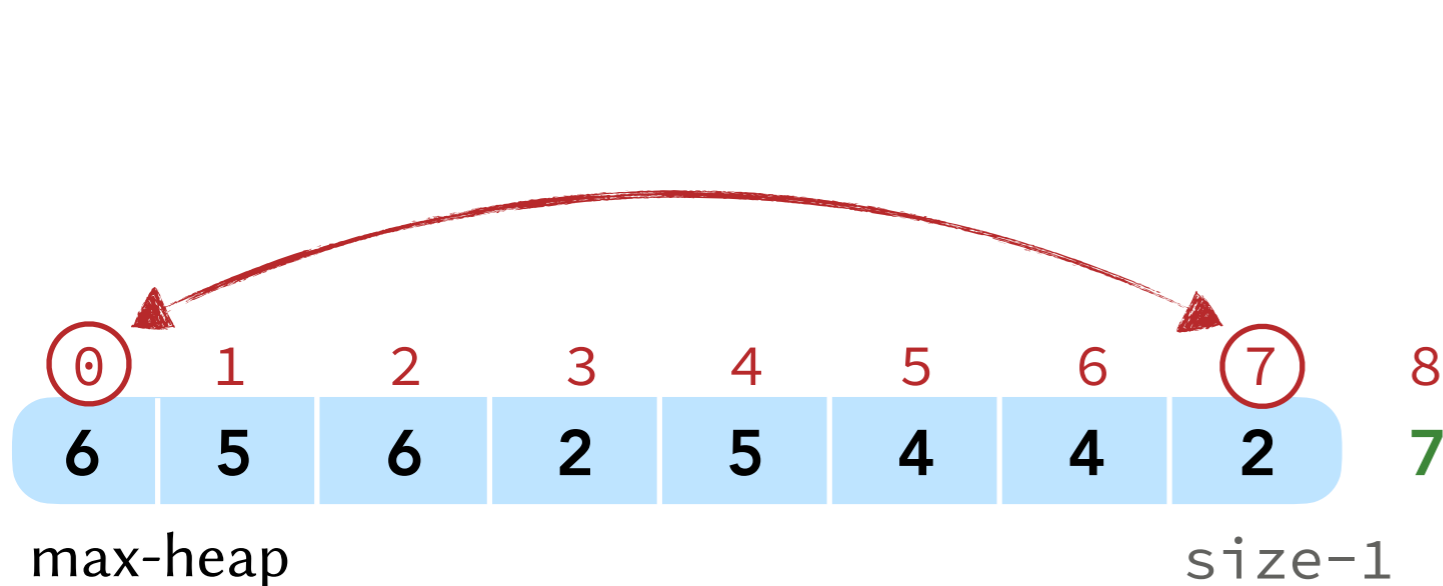
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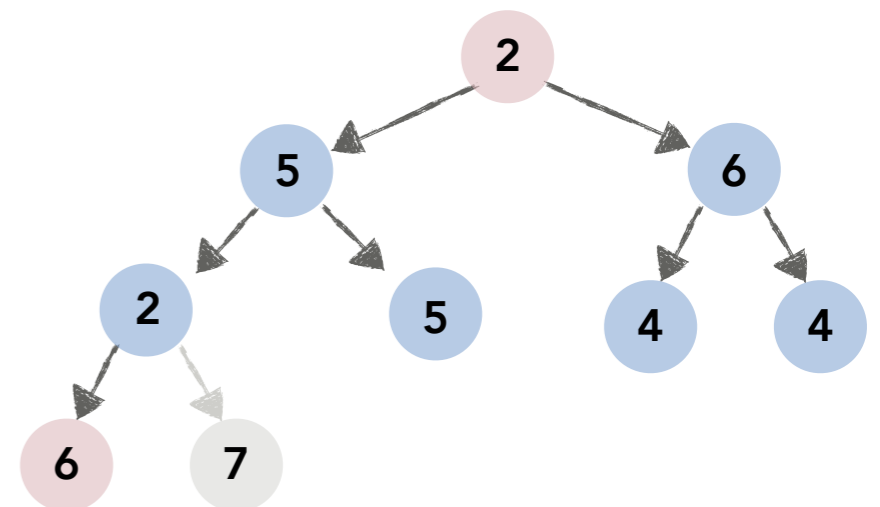
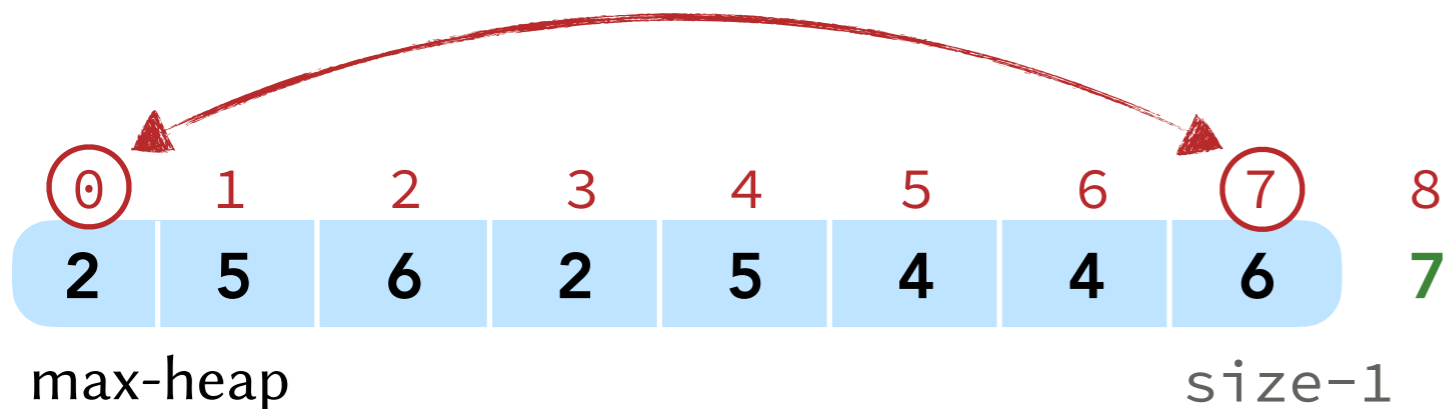
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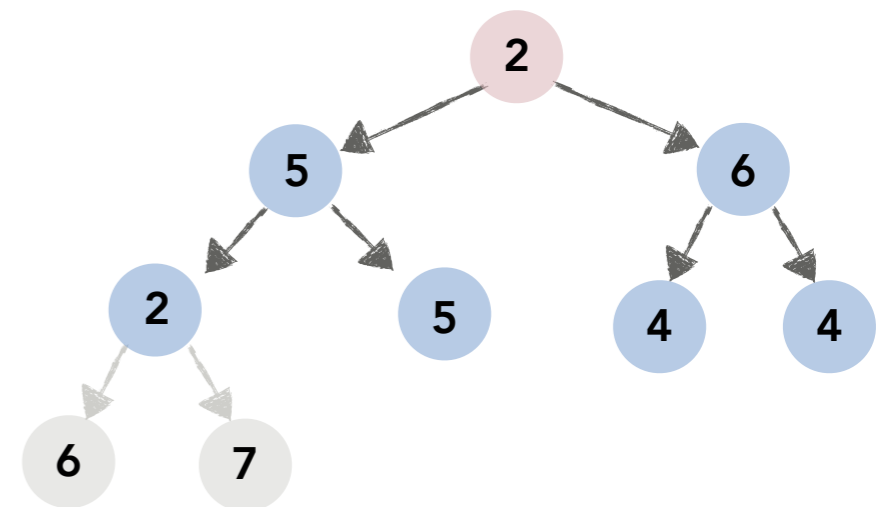
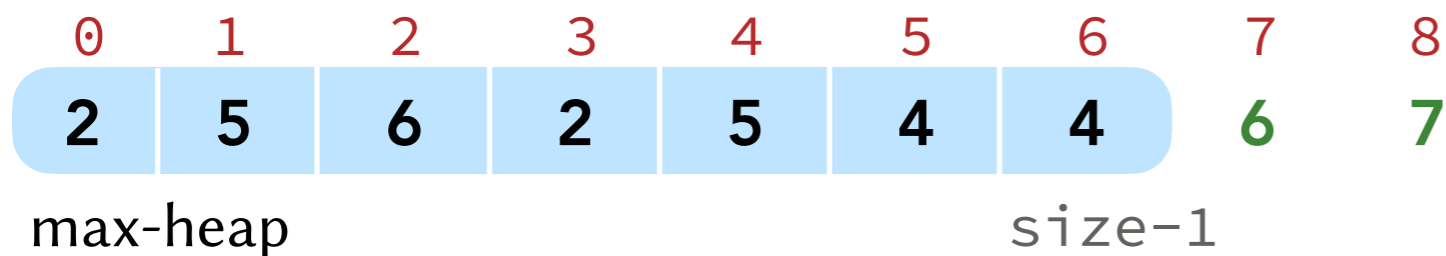
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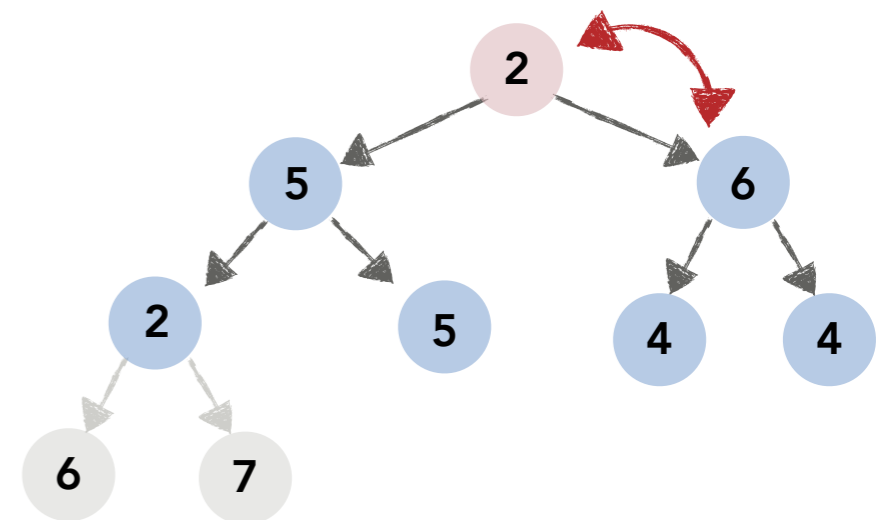
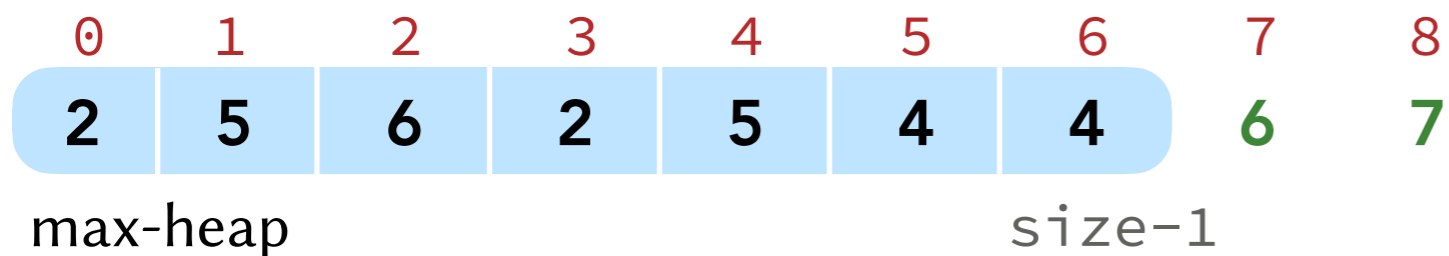
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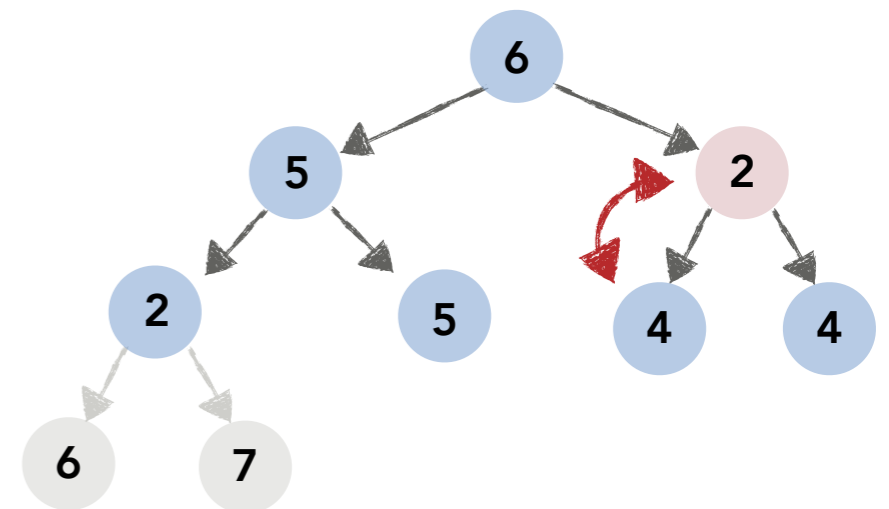
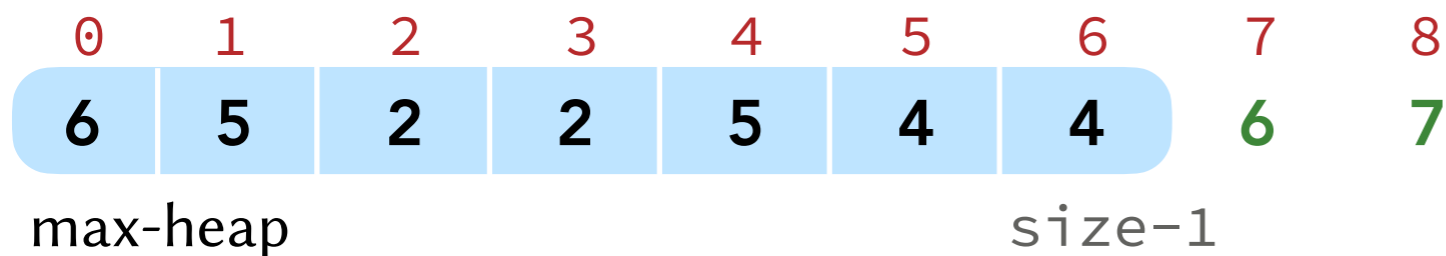
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Heapsort: A Better Implementation

HEAP-SORT(a[], size)

CONSTRUCT-HEAP(a, size)

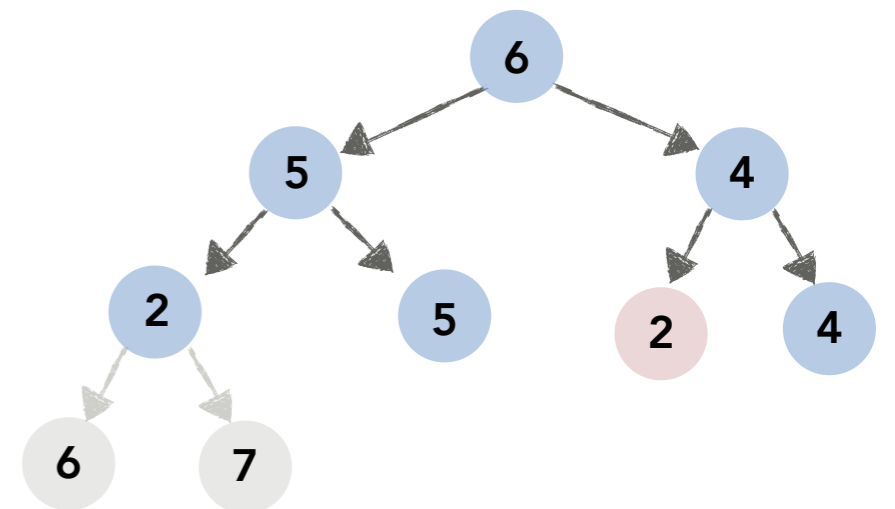
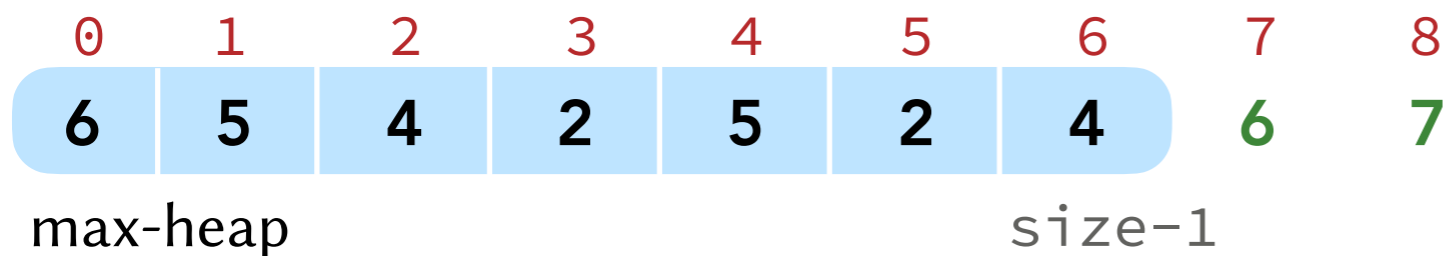
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Heapsort: A Better Implementation

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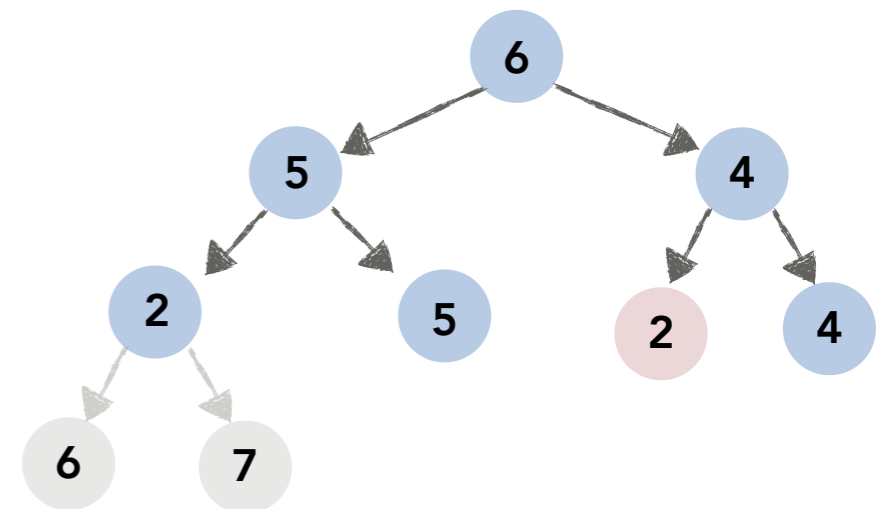
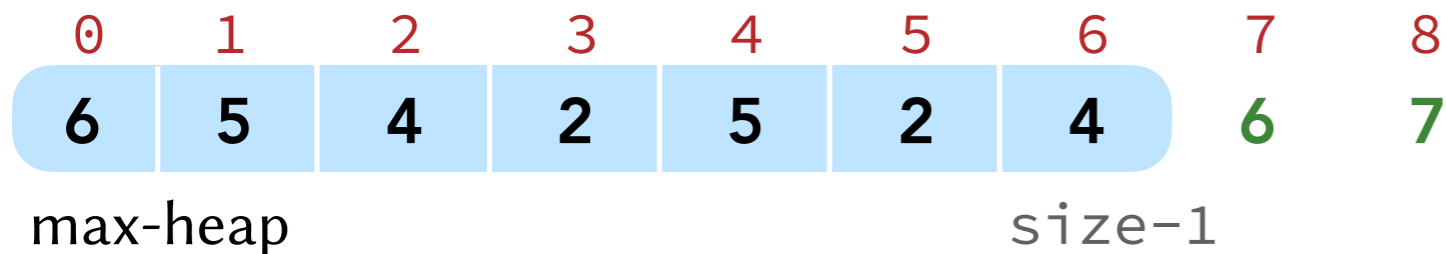
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    size = size-1  
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```

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construct a max-heap in-place
(change the array to become a heap)

2

repeatedly place the next
maximum in its right position
repeat until all the elements
are in their correct positions



Heapsort: A Better Implementation

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HEAP-SORT(a[], size)
```

```
  CONSTRUCT-HEAP(a, size)
```

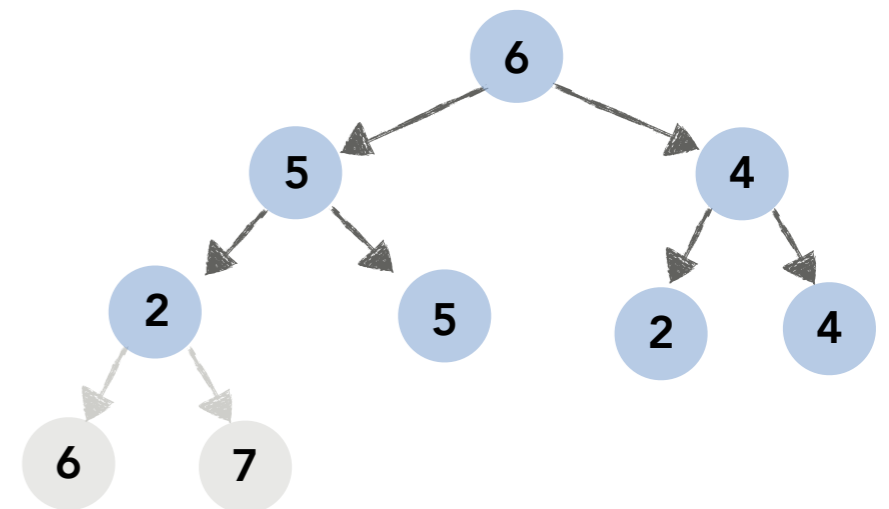
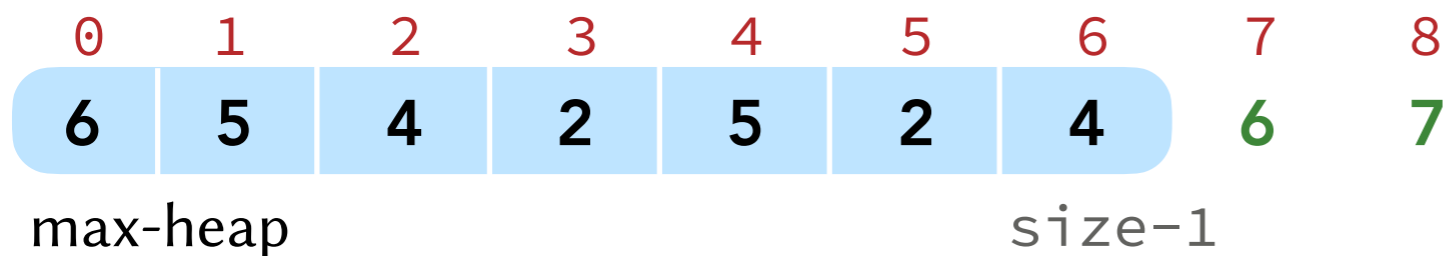
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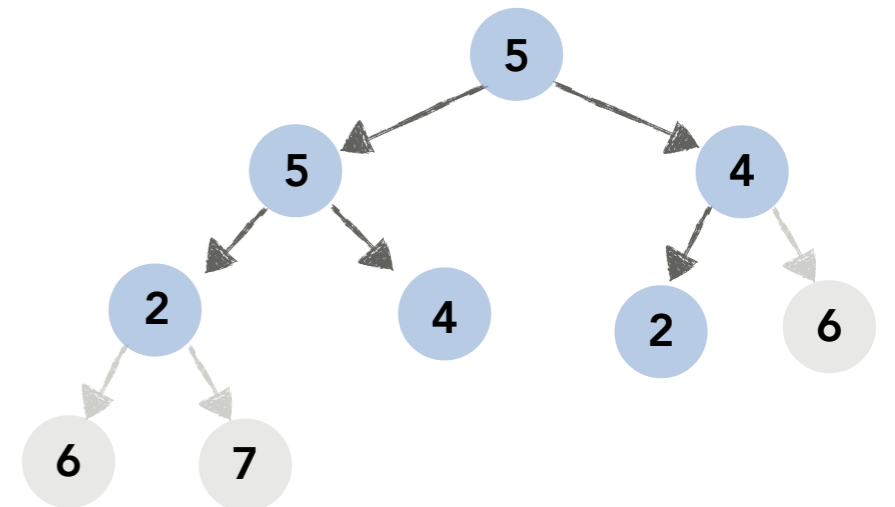
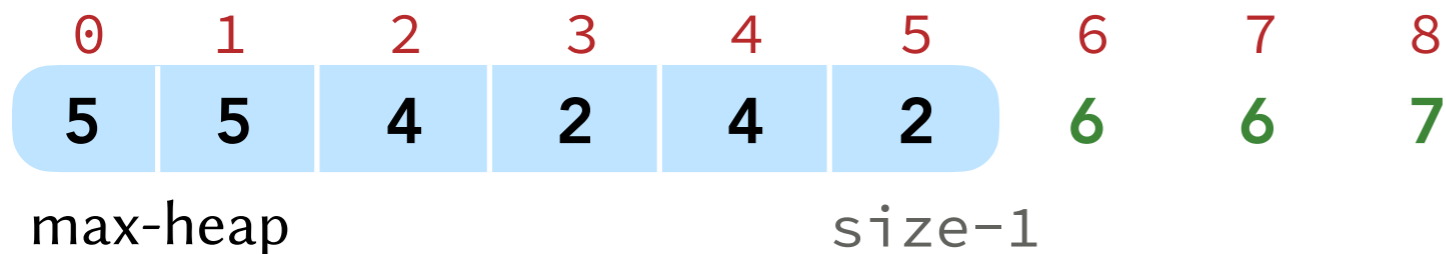
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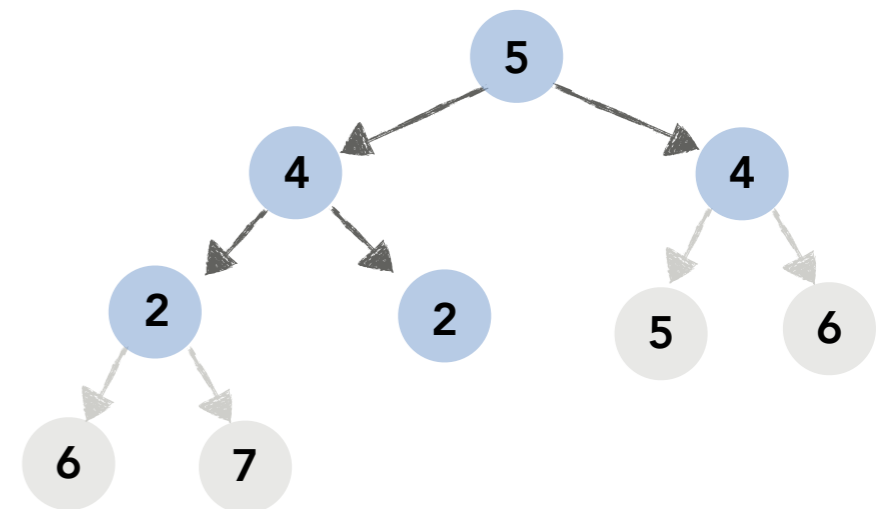
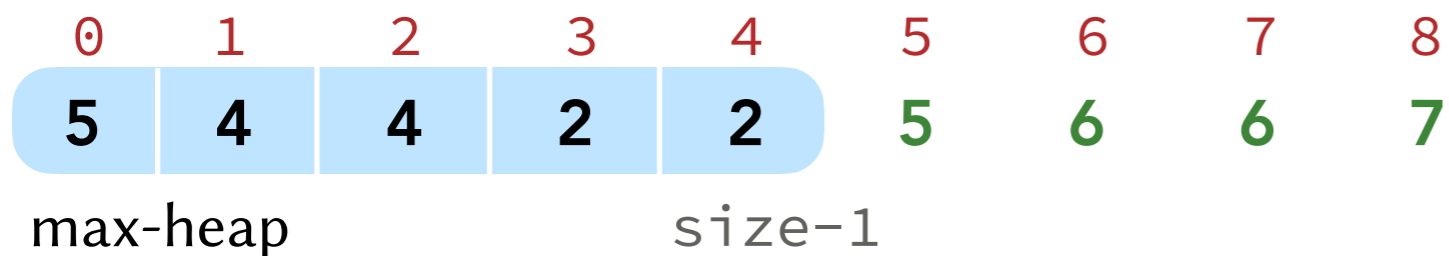
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Heapsort: A Better Implementation

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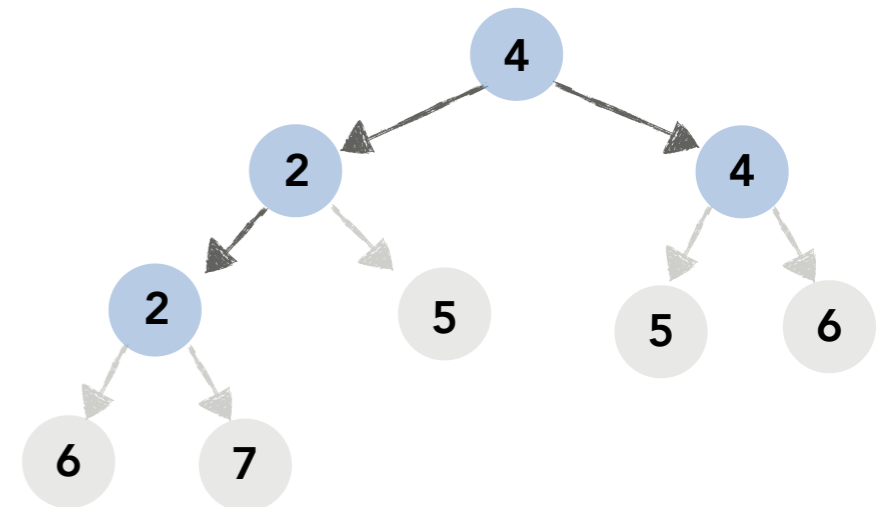
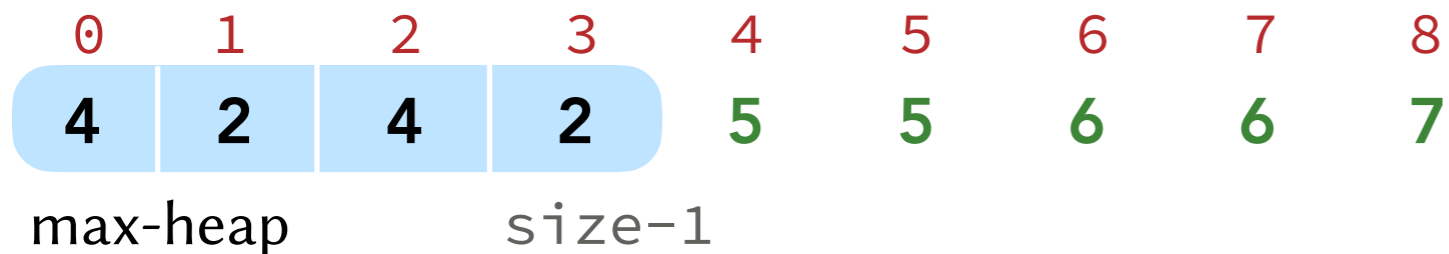
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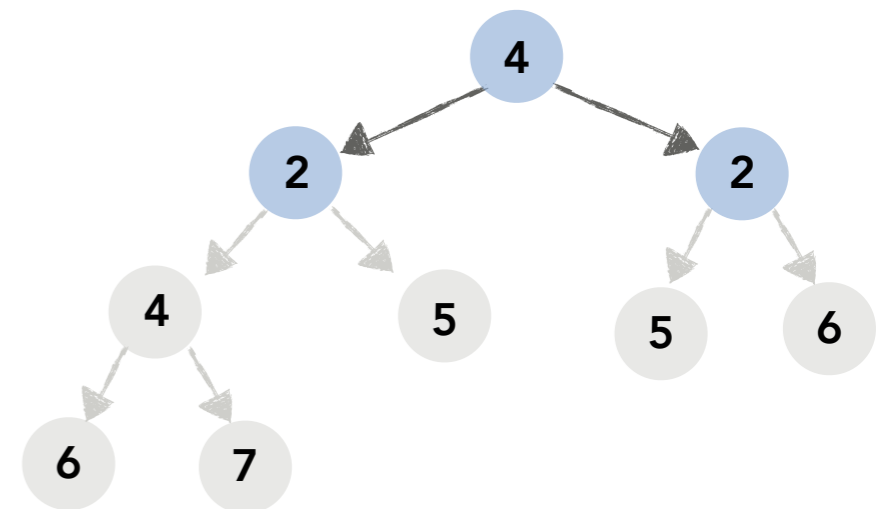
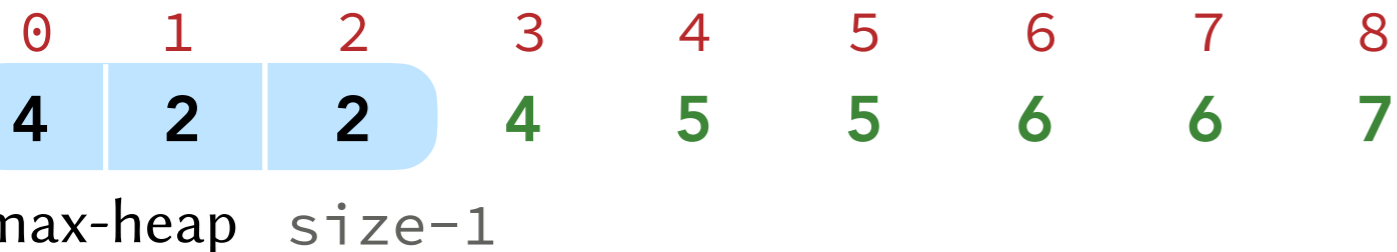
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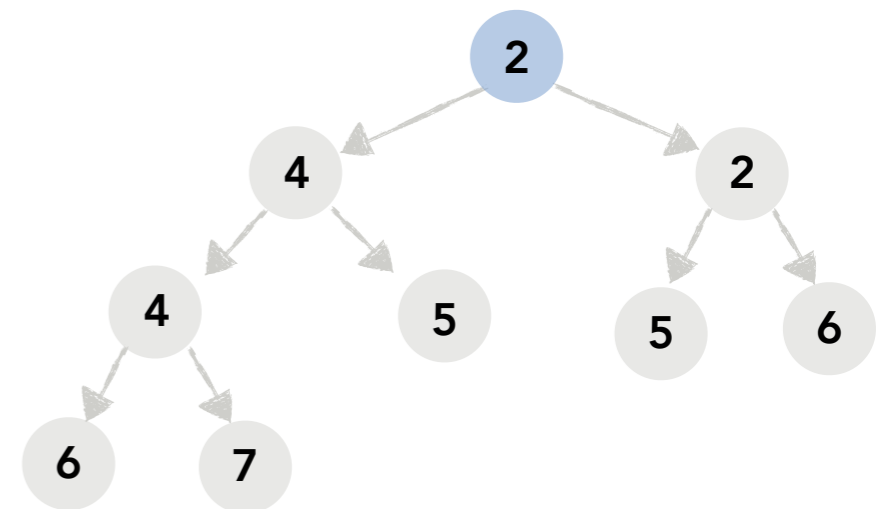
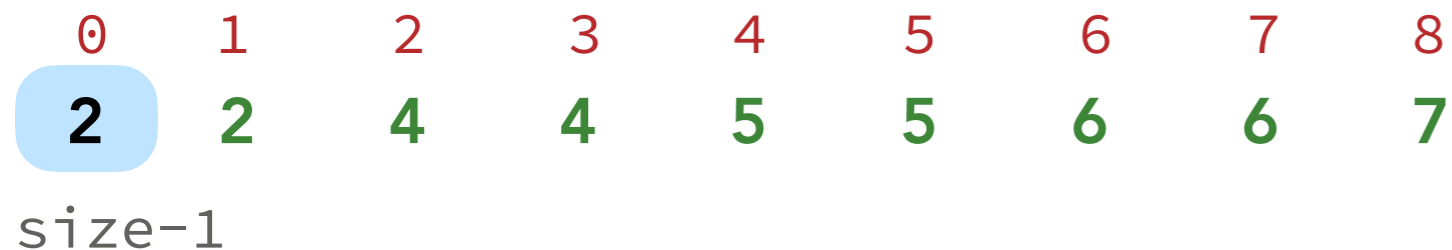
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Heapsort: **A Better** Implementation

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```

```
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```
  while (size > 1):  
    swap(a[0], a[size-1])  
    size = size-1  
    SINK(a, 0, size)
```

```
CONSTRUCT-HEAP(a, size)
```

```
for i = size/2 - 1 → 0:  
  SINK(a, i, size)
```

Heapsort: A Better Implementation

```
HEAP-SORT(a[], size)
```

```
  CONSTRUCT-HEAP(a, size)
```

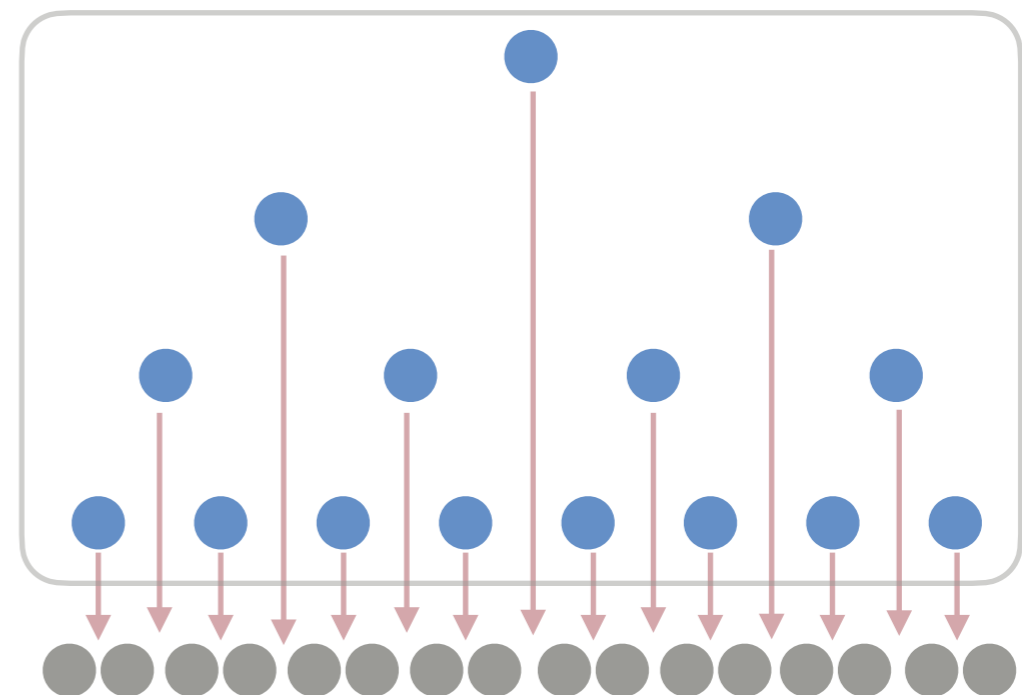
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```

```
CONSTRUCT-HEAP(a, size)
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```
for i = size/2 - 1 → 0:  
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```

sink all the
non-leaf nodes

at indices 0 to $\text{size}/2 - 1$



Heapsort: A Better Implementation

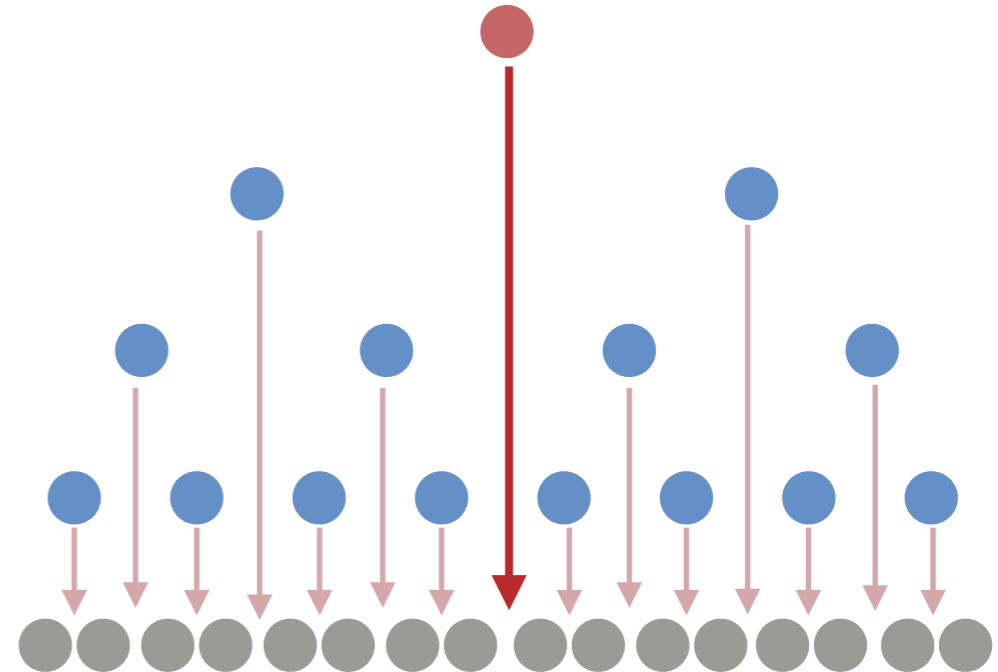
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```
  for i = size/2 - 1 → 0:  
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```



Heap Construction Analysis:

- Maximum number of swaps: $1 \cdot h$ ← number of swaps = tree height
 ↑
 number of nodes

Heapsort: *A Better* Implementation

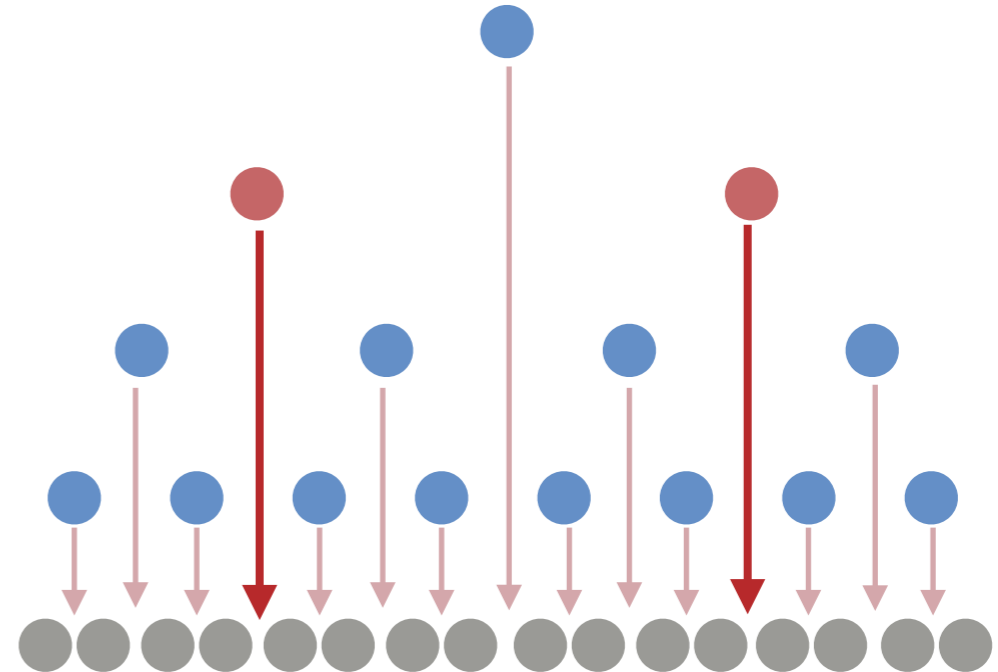
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```



Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1)$

Heapsort: *A Better* Implementation

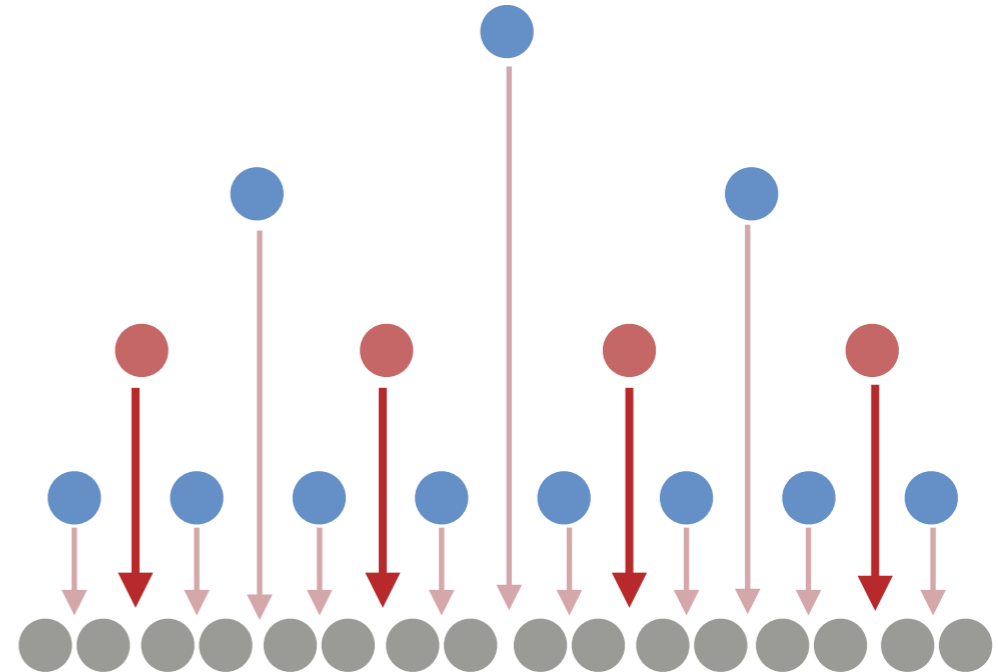
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Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2)$

Heapsort: A Better Implementation

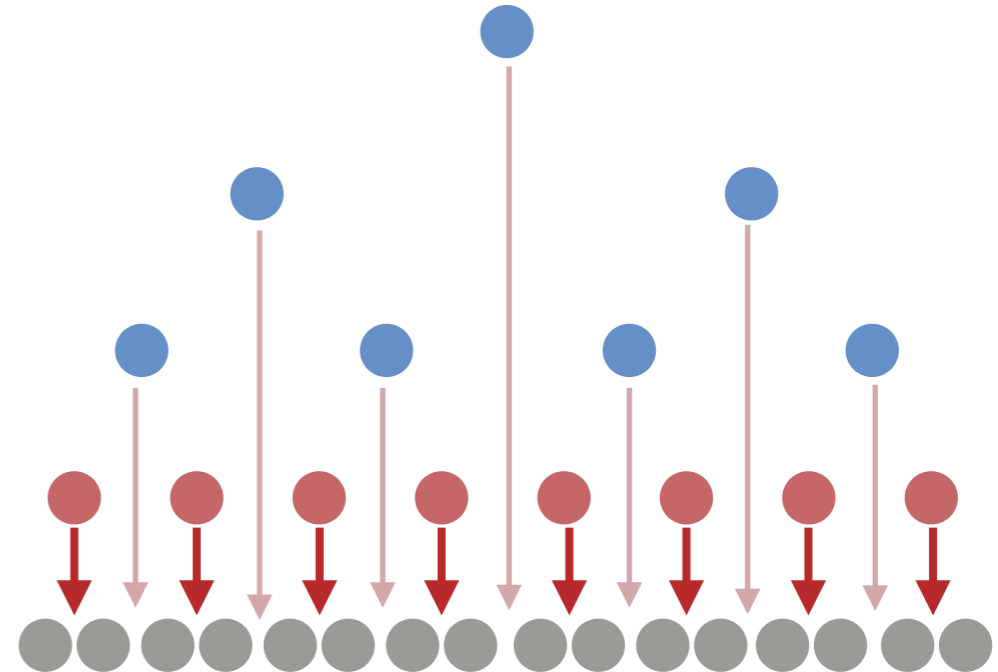
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Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + (\frac{n}{4} \cdot 1)$

Heapsort: A Better Implementation

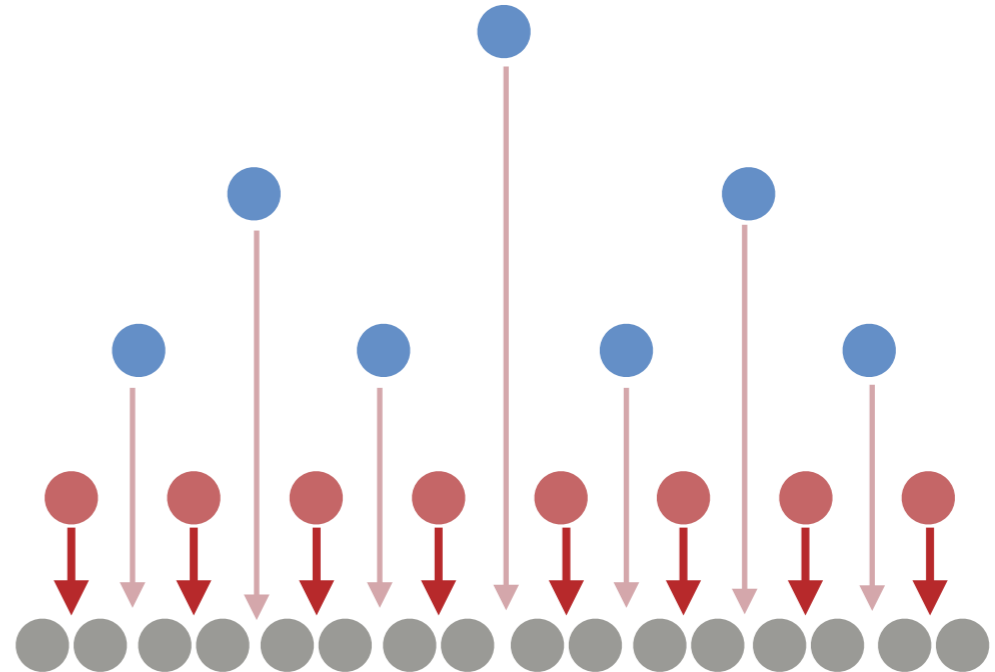
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Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + \frac{n}{4}(1) = O(n)$

↑
tricky sum
(math skipped)

Heapsort: A Better Implementation

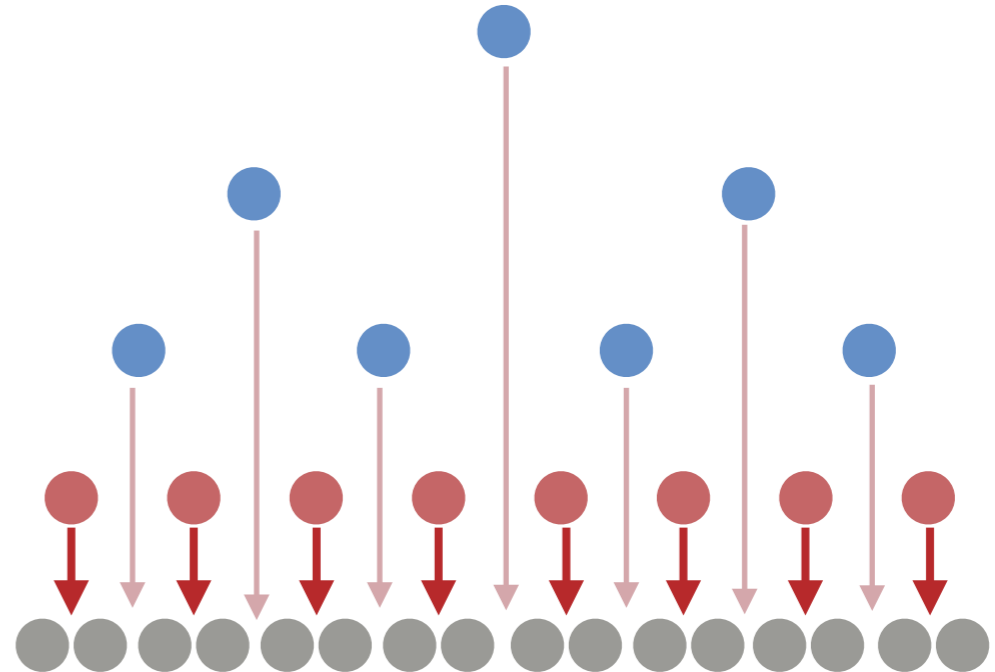
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Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + \frac{n}{4}(1) = O(n)$

number of
swaps is linear!

Heapsort: A Better Implementation

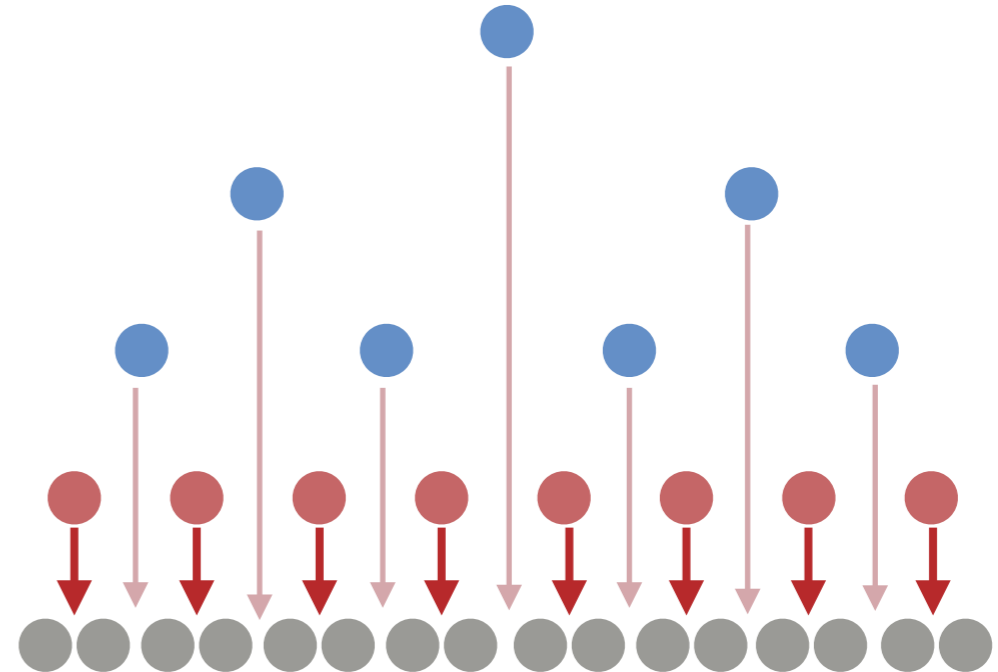
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Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + \frac{n}{4}(1) = O(n)$
- Maximum number of compares: $2 \times$ number of swaps

↑
check the analysis
of the **SINK** operation!

Heapsort: A Better Implementation

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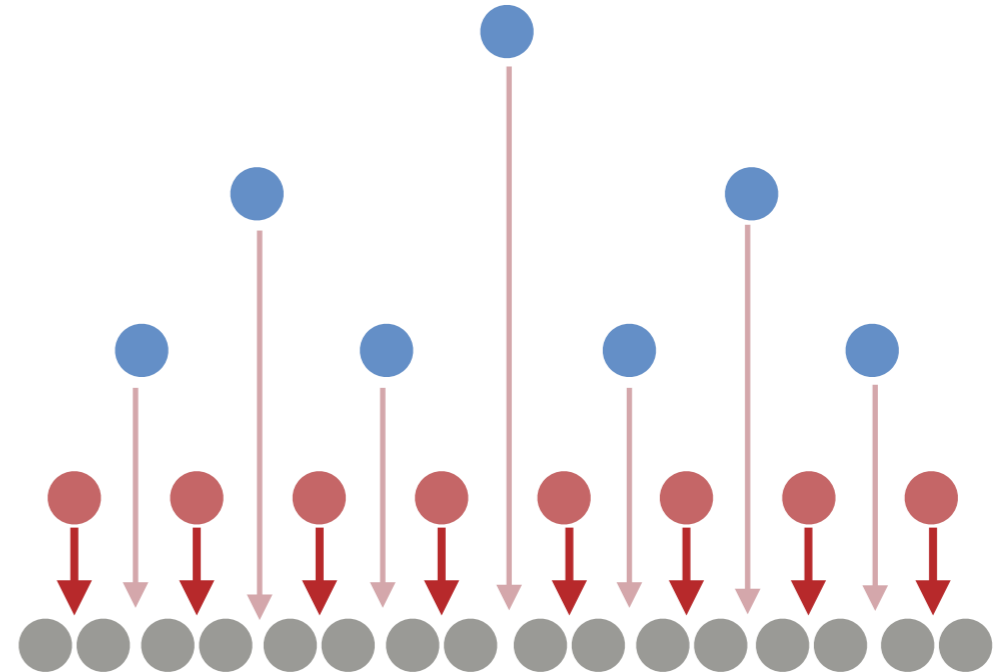
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CONSTRUCT-HEAP(a, size)
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```
for i = size/2 - 1 → 0:  
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```



Think. Why does this heap construction code run in $O(n)$ while inserting all the elements into a heap takes $O(n \log n)$ time?



Heap Construction Analysis:

- Maximum number of swaps: $(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + \frac{n}{4}(1) = O(n)$
- Maximum number of compares: $2 \times$ number of swaps



check the analysis
of the **SINK** operation!

Optional

$$(1 \cdot h) + 2(h - 1) + 4(h - 2) + \dots + \frac{n}{4}(1) \\ = 2^0(1 \cdot h) + 2^1(h - 1) + 2^2(h - 2) + \dots + 2^{h-1}$$

$$= \sum_{i=0}^{h-1} 2^i(h - i) = \left(\sum_{i=0}^{h-1} 2^i h \right) - \left(\sum_{i=0}^{h-1} i 2^i \right) = h(2^h - 1) - \left(\sum_{i=0}^{h-1} i 2^i \right)$$

$$= h(2^h - 1) - ((h - 2)2^h + 2)$$

$$= h(2^h - 1) - (h2^h - 2^{h+1} + 2)$$

$$= h2^h - h - h2^h + 2^{h+1} - 2$$

$$= 2^{h+1} - 2 \quad \leftarrow h \sim \log_2 n$$

$$= O(n)$$

$$\sum_{i=0}^n i \times 2^i = (n - 1)2^{n+1} + 2$$



Heapsort Analysis

Worst Case: $\Theta(n)$ to **construct** the heap and $\Theta(n \log n)$ to **heapsort**.

Average Case: $\Theta(n \log n)$

Heapsort Analysis

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Heapsort Analysis

Worst Case: $\Theta(n)$ to **construct** the heap and $\Theta(n \log n)$ to **heapsort**.

Average Case: $\Theta(n \log n)$

Best Case: $\Theta(n)$ if all the elements are the same.



Why? Trace on a piece of paper to see why!

Heapsort Analysis

Worst Case: $\Theta(n)$ to **construct** the heap and $\Theta(n \log n)$ to **heapsort**.

Average Case: $\Theta(n \log n)$

Best Case: $\Theta(n)$ if all the elements are the same.

Running Time:

- Number of compares: At most $\sim 2n \log_2 n$.



$\sim n \log_2 n$ for merge sort and
 $\sim 1.39n \log_2 n$ for quicksort (on random data)

Heapsort Analysis

Worst Case: $\Theta(n)$ to **construct** the heap and $\Theta(n \log n)$ to **heapsort**.

Average Case: $\Theta(n \log n)$

Best Case: $\Theta(n)$ if all the elements are the same.

Running Time:

- **Number of compares:** At most $\sim 2n \log_2 n$.
- **Actual running time:** Slower than merge sort and quicksort because of the higher number of comparisons and the the poor use of cache.

↑
optimizations are possible

Heapsort Analysis

Worst Case: $\Theta(n)$ to **construct** the heap and $\Theta(n \log n)$ to **heapsort**.

Average Case: $\Theta(n \log n)$

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Memory. Heapsort is an *in-place* sorting algorithm.

Heapsort Analysis

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Memory. Heapsort is an *in-place* sorting algorithm.

Bottom line.

- $\Theta(n \log n)$ in the worst case and also sorts in-place at the same time.
(Merge Sort is not in-place and Quicksort has a theoretical worst case of $\Theta(n^2)$)
- Practically, not frequently used because it is slower than merge sort and quicksort.



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Introsort

From Wikipedia, the free encyclopedia

Introsort or **introspective sort** is a [hybrid sorting algorithm](#) that provides both fast average performance and (asymptotically) optimal worst-case performance. It begins with [quicksort](#), it switches to [heapsort](#) when the recursion depth exceeds a level based on (the [logarithm](#) of) the number of elements being sorted and it switches to [insertion sort](#) when the number of elements is below some threshold. This combines the good parts of the three algorithms, with practical performance comparable to quicksort on typical data sets and worst-case $O(n \log n)$ runtime due to the heap sort. Since the three algorithms it uses are [comparison sorts](#), it is also a comparison sort.

Introsort

Class	Sorting algorithm
Data structure	Array
Worst-case performance	$O(n \log n)$
Average performance	$O(n \log n)$



Used for the C++ STL `sort()` function

Sorting algorithms: summary

	inplace?	stable?	best	average	worst	remarks
selection	✓		$\frac{1}{2} n^2$	$\frac{1}{2} n^2$	$\frac{1}{2} n^2$	n exchanges
insertion	✓	✓	n	$\frac{1}{4} n^2$	$\frac{1}{2} n^2$	use for small n or partially ordered
merge		✓	$\frac{1}{2} n \log_2 n$	$n \log_2 n$	$n \log_2 n$	$\Theta(n \log n)$ guarantee; stable
timsort		✓	n	$n \log_2 n$	$n \log_2 n$	improves mergesort when pre-existing order
quick	✓		$n \log_2 n$	$2 n \ln n$	$\frac{1}{2} n^2$	$\Theta(n \log n)$ probabilistic guarantee; fastest in practice
3-way quick	✓		n	$2 n \ln n$	$\frac{1}{2} n^2$	improves quicksort when duplicate keys
heap	✓		$3 n$	$2 n \log_2 n$	$2 n \log_2 n$	$\Theta(n \log n)$ guarantee; in-place
?	✓	✓	n	$n \log_2 n$	$n \log_2 n$	holy sorting grail

number of compares to sort an array of n elements